# A NOTE ON THE APPROXIMATION OF FIXED POINTS IN THE HILBERT BALL 

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#### Abstract

We establish a strong convergence theorem for an iterative scheme which approximates fixed points of $\rho$-nonexpansive self-mappings of the Hilbert ball.


## 1. Introduction

In a recent paper we have established a strong convergence theorem [5, Theorem 3.12] for an implicit continuous scheme which approximates fixed points of $\rho$-nonexpansive self-mappings of the Hilbert ball. In the present note we complement this result by proving a corresponding strong convergence theorem (Theorem 4.1 below) for an explicit discrete scheme. This theorem may be considered a possible Hilbert ball analogue of the Hilbert space theorems in [8] and [13]. Another such analogue can be found in [6].

## 2. Preliminaries

Let $(H,\langle\cdot, \cdot\rangle)$ be a complex Hilbert space with inner product $\langle\cdot, \cdot\rangle$ and induced norm $|\cdot|$, and let $\mathbb{B}:=\{x \in H:|x|<1\}$ be its open unit ball. We denote the set of natural numbers, the interval $[0, \infty)$ and the complex plane by $\mathbb{N}, \mathbb{R}^{+}$and $\mathbb{C}$, respectively. The hyperbolic metric $\rho: \mathbb{B} \times \mathbb{B} \mapsto \mathbb{R}^{+}[3$, page 98$]$ is defined by

$$
\begin{equation*}
\rho(x, y):=\operatorname{argtanh}(1-\sigma(x, y))^{\frac{1}{2}} \tag{2.1}
\end{equation*}
$$

where

$$
\begin{equation*}
\sigma(x, y):=\frac{\left(1-|x|^{2}\right)\left(1-|y|^{2}\right)}{|1-\langle x, y\rangle|^{2}}, \quad x, y \in \mathbb{B} . \tag{2.2}
\end{equation*}
$$

This metric is the infinite-dimensional analogue of the Poincare metric on the open unit disk $\{z \in \mathbb{C}:|z|<1\}$. We let $B(a, r):=\{x \in \mathbb{B}: \rho(a, x)<r\}$ stand for the $\rho$-ball of center $a$ and radius $r$. A subset of $\mathbb{B}$ is called $\rho$-bounded if it is contained in a $\rho$-ball. We say that a mapping $c: \mathbb{R} \mapsto \mathbb{B}$ is a metric embedding of the real line $\mathbb{R}$ into $\mathbb{B}$ if $\rho(c(s), c(t))=|s-t|$ for all real $s$ and $t$. The image of $\mathbb{R}$ under a metric embedding is called a metric line. The image of a real interval $[a, b]=\{t \in \mathbb{R}: a \leq t \leq b\}$ under such a mapping is called a metric segment. It is known [3, page 102] that for any two distinct points $x$ and $y$ in $\mathbb{B}$, there is a unique metric line (also called a geodesic) which passes through $x$ and $y$. This metric line determines a unique metric segment joining $x$ and $y$. We denote this

[^0]segment by $[x, y]$. For each $0 \leq t \leq 1$, there is a unique point $z \in[x, y]$ such that $\rho(x, z)=t \rho(x, y)$ and $\rho(z, y)=(1-t) \rho(x, y)$. This point will be denoted by $(1-t) x \oplus t y$. Similarly, for $r \geq 0$, we let $(1+r) x \ominus r y$ stand for the unique point $z \in \mathbb{B}$ that satisfies $\rho(z, x)=r \rho(x, y)$ and $\rho(z, y)=(1+r) \rho(x, y)$. This point lies on the unique geodesic determined by $x$ and $y$. The following inequality [3, page 104] shows that the metric space $(\mathbb{B}, \rho)$ is hyperbolic in the sense of [11].
Lemma 2.1. For any four points $a, b, x$ and $y$ in $\mathbb{B}$, and any number $t \in[0,1]$,
\[

$$
\begin{equation*}
\rho((1-t) a \oplus t x,(1-t) b \oplus t y) \leq(1-t) \rho(a, b)+t \rho(x, y) \tag{2.3}
\end{equation*}
$$

\]

Next, we mention another useful property of the hyperbolic metric.
Lemma 2.2. For any two points $x$ and $y$ in $\mathbb{B}$, and any number $t \in[0,1]$,

$$
\begin{equation*}
\rho(t x, t y) \leq t \rho(x, y) \tag{2.4}
\end{equation*}
$$

Proof. It is clear that we may assume without any loss of generality that $|x| \leq|y|$ and that $0<t<1$. For a fixed $0<t<1$, the function $g:(0,1) \mapsto \mathbb{R}^{+}$defined by

$$
\begin{equation*}
g(r):=\frac{\operatorname{argtanh}(t r)}{\operatorname{argtanh}(r)}, \quad 0<r<1 \tag{2.5}
\end{equation*}
$$

is decreasing and $\lim _{r \rightarrow 0^{+}} g(r)=t$. Therefore inequality (2.4) does hold for $x=0$ and we may also assume in the sequel that $x \neq 0$. There are numbers $0<p<1$ and $0<s<1$ such that $t x=(1-p) 0 \oplus p x$ and $t y=(1-s) 0 \oplus s y$. Since the function $g$ is decreasing and its right limit at zero is $t$, we have $s \leq p \leq t$. Let $z:=(1+r)(t y) \ominus r 0$, where $r:=1 / p-1>0$. Then $t y=(1-p) 0 \oplus p z$ and $|x| \leq|z| \leq|y|$. Hence $\rho(x, z) \leq \rho(x, y)$ and

$$
\rho(t x, t y)=\rho((1-p) 0 \oplus p x,(1-p) 0 \oplus p z) \leq p \rho(x, z) \leq p \rho(x, y) \leq t \rho(x, y)
$$

as claimed.
Recall (see [11] and [12]) that a set-valued operator $T \subset \mathbb{B} \times \mathbb{B}$ with domain $D(T)$ and range $R(T)$ is said to be coaccretive if

$$
\begin{equation*}
\rho\left(x_{1}, x_{2}\right) \leq \rho\left((1+r) x_{1} \ominus r y_{1},(1+r) x_{2} \ominus r y_{2}\right) \tag{2.6}
\end{equation*}
$$

for all $y_{1} \in T x_{1}, y_{2} \in T x_{2}$, and $r>0$. Such operators are the Hilbert ball analogues of the operators of the form $T=I-A$, where $A$ is an accretive operator on a Banach space. In this case, the operator $T$ is also said to be pseudo-contractive [2, page 876]. Let $D$ be a subset of $\mathbb{B}$. A mapping $T: D \mapsto \mathbb{B}$ is called $\rho$-nonexpansive if $\rho\left(T x_{1}, x_{2}\right) \leq \rho\left(x_{1}, x_{2}\right)$ whenever $x_{1}$ and $x_{2}$ belong to $D$. It is known (see, for example, [3, page 91]) that each holomorphic self-mapping of $\mathbb{B}$ is $\rho$-nonexpansive. Using Lemma 2.1, one can check that all $\rho$-nonexpansive mappings are coaccretive. An interesting family of (possibly set-valued) coaccretive operators is described in [12, page 641]. These operators are analogues of sub-differentials of convex functions in Hilbert space. In particular, if $R_{K}: \mathbb{B} \mapsto K$ is the nearest point projection of $\mathbb{B}$ onto an arbitrary $\rho$-closed and $\rho$-convex subset $K$ of $\mathbb{B}$, then the operator $\left\{\left(R_{K} z, 2 R_{K} z \ominus z\right): z \in \mathbb{B}\right\} \subset \mathbb{B} \times \mathbb{B}$ is coaccretive.

When the operator $T$ is coaccretive, one can define for each positive $r$, a singlevalued $\rho$-nonexpansive mapping $J_{r}: R((1+r) I \ominus r T) \mapsto D(T)$, the resolvent of $T$, by

$$
\begin{equation*}
J_{r}((1+r) x \ominus r y)=x, \tag{2.7}
\end{equation*}
$$

where $x \in D(T)$ and $y \in T x$. These mappings (which in normed linear spaces are indeed the resolvents of the accretive operator $A=I-T$ ) satisfy the following resolvent identity for all $t \geq s>0$ and $x \in D\left(J_{t}\right)$ :

$$
\begin{equation*}
J_{t} x=J_{s}\left((s / t) x \oplus(1-s / t) J_{t} x\right) . \tag{2.8}
\end{equation*}
$$

Recall that a mapping $T: D \mapsto \mathbb{B}$ is said to be firmly nonexpansive of the first kind [3, page 124] if for each $x$ and $y$ in $D$, the function $\phi:[0,1] \mapsto[0, \infty)$ defined by

$$
\begin{equation*}
\phi(s):=\rho((1-s) x \oplus s T x,(1-s) y \oplus s T y), 0 \leq s \leq 1, \tag{2.9}
\end{equation*}
$$

is decreasing. The set of all firmly nonexpansive mappings of the first kind will be denoted by $F N_{1}$.

A proof of our next lemma (based on the resolvent identity (2.8)) can be found in [5, Section 2].
Lemma 2.3. Any resolvent of a coaccretive operator is firmly nonexpansive of the first kind.

We say that a coaccretive operator $T \subset \mathbb{B} \times \mathbb{B}$ is $m$-coaccretive if

$$
\begin{equation*}
R((1+r) I \ominus r T)=\mathbb{B} \tag{2.10}
\end{equation*}
$$

for all positive $r$.
Actually, given a coaccretive operator $T$, the assumption that (2.10) holds when $r=1$ already implies that it holds for all $r>0$. Any $\rho$-nonexpansive mapping $T: \mathbb{B} \mapsto \mathbb{B}$ is $m$-coaccretive.

Lemma 2.4. If $0 \leq \alpha<1$ and the mapping $f: \mathbb{B} \mapsto \alpha \mathbb{B}$ is holomorphic, then $f$ is a strict $\rho$-contraction with a $\rho$-Lipschitz constant $\alpha$.
Proof. Since our claim is obviously true when $\alpha=0$, we may assume that $\alpha$ is positive. In this case, the mapping $g=f / \alpha$ is a holomorphic self-mapping of $\mathbb{B}$. Hence it is $\rho$-nonexpansive and we have $\rho(f(x), f(y))=\rho(\alpha g(x), \alpha g(y)) \leq$ $\alpha \rho(g(x), g(y)) \leq \alpha \rho(x, y)$ by Lemma 2.2.

We conclude this section with a simple consequence of inequality (2.3).
Lemma 2.5. Let $f$ and $g$ be two $\rho$-Lipschitz self-mappings of $\mathbb{B}$ with Lipschitz constants $L$ and $M$, respectively, and let $\beta \in[0,1]$. Then the mapping $h: \mathbb{B} \mapsto \mathbb{B}$ defined by $h(x):=(1-\beta) f(x) \oplus \beta g(x), x \in \mathbb{B}$, is also $\rho$-Lipschitz, with Lipschitz constant $(1-\beta) L+\beta M$.

## 3. Approximating Curves

Given a $\rho$-nonexpansive self-mapping $T$ of $\mathbb{B}$, a holomorphic mapping $f: \mathbb{B} \rightarrow \alpha \mathbb{B}$, where $0 \leq \alpha<1$, and a number $0 \leq t<1$, we define the point $z_{t} \in \mathbb{B}$ as the unique fixed point of the strict $\rho$-contraction $S: \mathbb{B} \mapsto \mathbb{B}$ defined by

$$
\begin{equation*}
S x:=(1-t) f(x) \oplus t T x, \quad x \in \mathbb{B} . \tag{3.1}
\end{equation*}
$$

Note that $S$ is indeed a strict $\rho$-contraction by Lemmata 2.4 and 2.5. It has a unique fixed point because the metric space $(\mathbb{B}, \rho)$ is complete. In other words,

$$
\begin{equation*}
z_{t}=(1-t) f\left(z_{t}\right) \oplus t T z_{t}, \quad 0 \leq t<1 \tag{3.2}
\end{equation*}
$$

In this section we recall a few facts regarding the behavior of the approximating curve $\left\{z_{t}: 0 \leq t<1\right\}$. See [5, Section 3] for more information regarding this curve and [6, Section 3] for a study of a related, but different approximating curve.

We can also write

$$
\begin{equation*}
z_{t}=F_{t}\left(f\left(z_{t}\right)\right) \tag{3.3}
\end{equation*}
$$

where $F_{t}: \mathbb{B} \mapsto \mathbb{B}$ is the mapping defined on page 123 of [3]. This mapping is, in fact, the resolvent $J_{r(t)}$ of the $m$-coaccretive operator $T$, where $r(t)=t /(1-t)$. In view of Lemma 2.3, it is firmly nonexpansive of the first kind. It may be defined by the equation

$$
\begin{equation*}
F_{t}(x)=(1-t) x \oplus t T F_{t}(x), \quad x \in \mathbb{B} \tag{3.4}
\end{equation*}
$$

Next, we recall [3, Theorem 24.1, page 122] (see also [12, Theorem 3.4, page 642]). Note (see [3, pages 110 and 120]) that the fixed point set $F(T)$ of a $\rho$-nonexpansive self-mapping $T$ of $\mathbb{B}$ is both $\rho$-closed and $\rho$-convex, and that the nearest point projection $R_{K}$ of $\mathbb{B}$ onto a $\rho$-closed and $\rho$-convex subset $K$ of $\mathbb{B}$ is $\rho$-nonexpansive (and belongs to $F N_{1}$ ). The retraction $R_{K}$ is also strongly nonexpansive [10, 1] and sunny [4, Proposition 5.4].

Proposition 3.1. Let $T: \mathbb{B} \rightarrow \mathbb{B}$ be $\rho$-nonexpansive and let $F_{t}, 0 \leq t<1$, be the family of mappings defined by (3.4). If $T$ has a fixed point, then for each $x \in \mathbb{B}$, the strong $\lim _{t \rightarrow 1^{-}} F_{t}(x)=R_{F(T)} x$.

Finally, we recall Theorem 3.12 of [5] (the proof of which makes use of Proposition 3.1). We say that a mapping $f: \mathbb{B} \mapsto \mathbb{B}$ is compact if the closure of its image $\overline{f(\mathbb{B})}$ is a compact subset of $H$.

Proposition 3.2. Let $T$ be a $\rho$-nonexpansive self-mapping of $\mathbb{B}, f: \mathbb{B} \mapsto \alpha \mathbb{B} a$ holomorphic mapping, where $0 \leq \alpha<1$, and let $z_{t}, 0 \leq t<1$, be defined by (3.2). If $T$ has a fixed point and $f$ is compact, then the strong $\lim _{t \rightarrow 1^{-}} z_{t}=v$, where $v$ is the unique solution of the equation $z=R_{F(T)}(f(z))$.

## 4. An Iterative Scheme

In this section we study a discrete iterative scheme for approximating fixed points of $\rho$-nonexpansive self-mappings of $\mathbb{B}$. The proof of our convergence theorem (Theorem 4.1 below) depends on Proposition 3.2.

Let a sequence $\left\{\alpha_{n} \in[0,1): n \in \mathbb{N}\right\}$ satisfy the following three conditions:

$$
\begin{gather*}
\lim _{n \rightarrow \infty} \alpha_{n}=1  \tag{4.1}\\
\sum_{n=1}^{\infty}\left(1-\alpha_{n}\right)=\infty \tag{4.2}
\end{gather*}
$$

$$
\begin{equation*}
\lim _{n \rightarrow \infty} \frac{\alpha_{n}-\alpha_{n-1}}{\left(1-\alpha_{n}\right)^{2}}=0 \tag{4.3}
\end{equation*}
$$

These conditions, which originate with P.-L. Lions [7], are satisfied, for instance, when for each $n \in \mathbb{N}, \alpha_{n}=1-n^{-\beta}$, where $0<\beta<1$. They had already been used in [9].

Given a $\rho$-nonexpansive self-mapping of $\mathbb{B}$, a holomorphic $f: \mathbb{B} \mapsto \alpha \mathbb{B}$, where $0 \leq \alpha<1$, and a point $x_{0} \in \mathbb{B}$, we consider in this section the iterative scheme

$$
\begin{equation*}
x_{n}=\left(1-\alpha_{n}\right) f\left(x_{n-1}\right) \oplus \alpha_{n} T x_{n-1}, \quad n \in \mathbb{N} \tag{4.4}
\end{equation*}
$$

Theorem 4.1. Let $T$ be a $\rho$-nonexpansive self-mapping of $\mathbb{B}, f: \mathbb{B} \mapsto \alpha \mathbb{B}$ a holomorphic mapping, where $0 \leq \alpha<1,\left\{\alpha_{n} \in[0,1): n \in \mathbb{N}\right\}$ a sequence satisfying (4.1)-(4.3), and $x_{0}$ a point in $\mathbb{B}$. If $T$ has a fixed point and $f$ is compact, then the sequence $\left\{x_{n}: n \in \mathbb{N}\right\}$ defined by (4.4) converges strongly to the unique solution $v \in \mathbb{B}$ of the equation $z=R_{F(T)}(f(z))$, where $R_{F(T)}: \mathbb{B} \mapsto F(T)$ is the nearest point projection of $\mathbb{B}$ onto the fixed point set $F(T)$ of $T$.

Proof. Fix $n \in \mathbb{N}$ and consider the mapping $S_{n}: \mathbb{B} \mapsto \mathbb{B}$ defined by

$$
\begin{equation*}
S_{n} z:=\left(1-\alpha_{n}\right) f(z) \oplus \alpha_{n} T z, \quad z \in \mathbb{B} \tag{4.5}
\end{equation*}
$$

In view of Lemmata 2.4 and 2.5, this mapping is a strict $\rho$-contraction with Lipschitz constant

$$
p_{n}:=\left(1-\alpha_{n}\right) \alpha+\alpha_{n}<1
$$

Since the metric space $(\mathbb{B}, \rho)$ is complete, $S_{n}$ has a unique fixed point $y_{n} \in \mathbb{B}$. In other words,

$$
\begin{equation*}
y_{n}=\left(1-\alpha_{n}\right) f\left(y_{n}\right) \oplus \alpha_{n} T y_{n}, \quad n \in \mathbb{N} \tag{4.6}
\end{equation*}
$$

Note that $y_{n}=z_{\alpha_{n}}$ in the notation of equation (3.2) and Section 3. Since we already know by Proposition 3.2 and (4.1) that $y_{n} \rightarrow v$ strongly as $n \rightarrow \infty$, it is sufficient to show that $\left(x_{n}-y_{n}\right) \rightarrow 0$ strongly as $n \rightarrow \infty$. To this end, we first note that

$$
\rho\left(x_{n}, y_{n}\right)=\rho\left(S_{n} x_{n-1}, S_{n} y_{n}\right) \leq p_{n} \rho\left(x_{n-1}, y_{n}\right) \leq p_{n} \rho\left(x_{n-1}, y_{n-1}\right)+\rho\left(y_{n-1}, y_{n}\right)
$$

for all $n \in \mathbb{N}$. Setting

$$
\begin{equation*}
A(m)=\sup _{n \geq m+1} \frac{\rho\left(y_{n-1}, y_{n}\right)}{1-p_{n}} \tag{4.7}
\end{equation*}
$$

for all $m \in \mathbb{N}$, we conclude that

$$
\begin{equation*}
\rho\left(x_{n}, y_{n}\right) \leq \rho\left(x_{m}, y_{m}\right) \prod_{j=m+1}^{n} p_{j}+A(m) \tag{4.8}
\end{equation*}
$$

for all $n \geq m+1$. Since for each $n \geq 2$, the points $S_{n-1} y_{n-1}$ and $S_{n} y_{n-1}$ lie on the metric segment joining $f\left(y_{n-1}\right)$ and $T y_{n-1}$, and since the sequences $\left\{y_{n}: n \in \mathbb{N}\right\}$
and $\left\{f\left(y_{n}\right): n \in \mathbb{N}\right\}$ are $\rho$-bounded, there is a number $M \in \mathbb{R}^{+}$such that

$$
\begin{aligned}
\rho\left(y_{n-1}, y_{n}\right) & =\rho\left(S_{n-1} y_{n-1}, S_{n} y_{n}\right) \\
& \leq \rho\left(S_{n-1} y_{n-1}, S_{n} y_{n-1}\right)+\rho\left(S_{n} y_{n-1}, S_{n} y_{n}\right) \\
& =\left|\alpha_{n}-\alpha_{n-1}\right| \rho\left(f\left(y_{n-1}\right), T y_{n-1}\right)+\rho\left(S_{n} y_{n-1}, S_{n} y_{n}\right) \\
& \leq M\left|\alpha_{n}-\alpha_{n-1}\right|+p_{n} \rho\left(y_{n-1}, y_{n}\right)
\end{aligned}
$$

for all $n \geq 2$. Hence

$$
\begin{equation*}
A(m) \leq \frac{M}{(1-\alpha)^{2}} \sup _{n \geq m+1} \frac{\left|\alpha_{n}-\alpha_{n-1}\right|}{\left(1-\alpha_{n}\right)^{2}} \tag{4.9}
\end{equation*}
$$

for all $m \in \mathbb{N}$. Combining (4.2)-(4.3) with (4.8) and (4.9), we now see that $\rho\left(x_{n}, y_{n}\right) \rightarrow 0$ as $n \rightarrow \infty$. Since the sequences $\left\{x_{n}\right\}$ and $\left\{y_{n}\right\}$ are $\rho$-bounded, it follows that $\left(x_{n}-y_{n}\right) \rightarrow 0$ and $x_{n} \rightarrow v$ strongly, as asserted.

This theorem seems to be new even in the special case where the mapping $f$ is a constant. It holds, in particular, when the (complex) Hilbert space $H$ is finite dimensional. It remains an open question whether it continues to hold when $H$ is infinite dimensional and $f$ is no longer assumed to be compact. Note that although $f$ is not assumed to be compact in [6, Theorem 4.1] (which concerns a related, but different iterative scheme), the self-mapping $T$ is assumed to be holomorphic there. It would also be of interest to determine the behavior of the sequence $\left\{x_{n}: n \in \mathbb{N}\right\}$ when other conditions are imposed on the sequence of parameters $\left\{\alpha_{n}: n \in \mathbb{N}\right\}$ and when the mapping $T$ is fixed point free, and to find out if Theorem 4.1 can be extended to other hyperbolic spaces in the sense of [11].

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