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A NOTE ON THE APPROXIMATION OF FIXED POINTS IN THE HILBERT BALL

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ABSTRACT. We establish a strong convergence theorem for an iterative scheme which approximates fixed points of ρ -nonexpansive self-mappings of the Hilbert ball.

1. INTRODUCTION

In a recent paper we have established a strong convergence theorem [5, Theorem 3.12] for an implicit continuous scheme which approximates fixed points of ρ -nonexpansive self-mappings of the Hilbert ball. In the present note we complement this result by proving a corresponding strong convergence theorem (Theorem 4.1 below) for an explicit discrete scheme. This theorem may be considered a possible Hilbert ball analogue of the Hilbert space theorems in [8] and [13]. Another such analogue can be found in [6].

2. Preliminaries

Let $(H, \langle \cdot, \cdot \rangle)$ be a complex Hilbert space with inner product $\langle \cdot, \cdot \rangle$ and induced norm $|\cdot|$, and let $\mathbb{B} := \{x \in H : |x| < 1\}$ be its open unit ball. We denote the set of natural numbers, the interval $[0, \infty)$ and the complex plane by \mathbb{N} , \mathbb{R}^+ and \mathbb{C} , respectively. The *hyperbolic metric* $\rho : \mathbb{B} \times \mathbb{B} \mapsto \mathbb{R}^+$ [3, page 98] is defined by

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(2.1)
$$\rho(x,y) := \operatorname{argtanh}(1 - \sigma(x,y))^{\overline{2}},$$

where

(2.2)
$$\sigma(x,y) := \frac{(1-|x|^2)(1-|y|^2)}{|1-\langle x,y\rangle|^2}, \quad x,y \in \mathbb{B}.$$

This metric is the infinite-dimensional analogue of the Poincaré metric on the open unit disk $\{z \in \mathbb{C} : |z| < 1\}$. We let $B(a,r) := \{x \in \mathbb{B} : \rho(a,x) < r\}$ stand for the ρ -ball of center a and radius r. A subset of \mathbb{B} is called ρ -bounded if it is contained in a ρ -ball. We say that a mapping $c : \mathbb{R} \to \mathbb{B}$ is a metric embedding of the real line \mathbb{R} into \mathbb{B} if $\rho(c(s), c(t)) = |s - t|$ for all real s and t. The image of \mathbb{R} under a metric embedding is called a metric line. The image of a real interval $[a, b] = \{t \in \mathbb{R} : a \le t \le b\}$ under such a mapping is called a metric segment. It is known [3, page 102] that for any two distinct points x and y in \mathbb{B} , there is a unique metric line (also called a geodesic) which passes through x and y. This metric line determines a unique metric segment joining x and y. We denote this

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segment by [x,y]. For each $0 \le t \le 1$, there is a unique point $z \in [x,y]$ such that $\rho(x,z) = t\rho(x,y)$ and $\rho(z,y) = (1-t)\rho(x,y)$. This point will be denoted by $(1-t)x \oplus ty$. Similarly, for $r \ge 0$, we let $(1+r)x \ominus ry$ stand for the unique point $z \in \mathbb{B}$ that satisfies $\rho(z, x) = r\rho(x, y)$ and $\rho(z, y) = (1+r)\rho(x, y)$. This point lies on the unique geodesic determined by x and y. The following inequality [3, page 104] shows that the metric space (\mathbb{B}, ρ) is hyperbolic in the sense of [11].

Lemma 2.1. For any four points a, b, x and y in \mathbb{B} , and any number $t \in [0, 1]$,

(2.3)
$$\rho((1-t)a \oplus tx, (1-t)b \oplus ty) \le (1-t)\rho(a,b) + t\rho(x,y).$$

Next, we mention another useful property of the hyperbolic metric.

Lemma 2.2. For any two points x and y in \mathbb{B} , and any number $t \in [0, 1]$,

(2.4)
$$\rho(tx, ty) \le t\rho(x, y).$$

Proof. It is clear that we may assume without any loss of generality that $|x| \leq |y|$ and that 0 < t < 1. For a fixed 0 < t < 1, the function $g: (0,1) \mapsto \mathbb{R}^+$ defined by

(2.5)
$$g(r) := \frac{\operatorname{argtanh}(tr)}{\operatorname{argtanh}(r)}, \quad 0 < r < 1,$$

is decreasing and $\lim_{r\to 0^+} g(r) = t$. Therefore inequality (2.4) does hold for x = 0and we may also assume in the sequel that $x \neq 0$. There are numbers 0and 0 < s < 1 such that $tx = (1-p)0 \oplus px$ and $ty = (1-s)0 \oplus sy$. Since the function g is decreasing and its right limit at zero is t, we have $s \leq p \leq t$. Let $z := (1+r)(ty) \oplus r0$, where r := 1/p - 1 > 0. Then $ty = (1-p)0 \oplus pz$ and $|x| \leq |z| \leq |y|$. Hence $\rho(x, z) \leq \rho(x, y)$ and

$$\rho(tx, ty) = \rho((1-p)0 \oplus px, (1-p)0 \oplus pz) \le p\rho(x, z) \le p\rho(x, y) \le t\rho(x, y),$$

s claimed.

as claimed.

Recall (see [11] and [12]) that a set-valued operator $T \subset \mathbb{B} \times \mathbb{B}$ with domain D(T)and range R(T) is said to be *coaccretive* if

(2.6)
$$\rho(x_1, x_2) \le \rho((1+r)x_1 \ominus ry_1, (1+r)x_2 \ominus ry_2)$$

for all $y_1 \in Tx_1$, $y_2 \in Tx_2$, and r > 0. Such operators are the Hilbert ball analogues of the operators of the form T = I - A, where A is an accretive operator on a Banach space. In this case, the operator T is also said to be pseudo-contractive [2, page 876]. Let D be a subset of \mathbb{B} . A mapping $T: D \to \mathbb{B}$ is called ρ -nonexpansive if $\rho(Tx_1, x_2) \leq \rho(x_1, x_2)$ whenever x_1 and x_2 belong to D. It is known (see, for example, [3, page 91]) that each holomorphic self-mapping of \mathbb{B} is ρ -nonexpansive. Using Lemma 2.1, one can check that all ρ -nonexpansive mappings are coaccretive. An interesting family of (possibly set-valued) coaccretive operators is described in [12, page 641]. These operators are analogues of sub-differentials of convex functions in Hilbert space. In particular, if $R_K : \mathbb{B} \mapsto K$ is the nearest point projection of \mathbb{B} onto an arbitrary ρ -closed and ρ -convex subset K of \mathbb{B} , then the operator $\{(R_K z, 2R_K z \ominus z) : z \in \mathbb{B}\} \subset \mathbb{B} \times \mathbb{B}$ is coaccretive.

When the operator T is coaccretive, one can define for each positive r, a singlevalued ρ -nonexpansive mapping $J_r: R((1+r)I \ominus rT) \mapsto D(T)$, the resolvent of T, by

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(2.7)
$$J_r((1+r)x \ominus ry) = x,$$

where $x \in D(T)$ and $y \in Tx$. These mappings (which in normed linear spaces are indeed the resolvents of the accretive operator A = I - T) satisfy the following resolvent identity for all $t \geq s > 0$ and $x \in D(J_t)$:

(2.8)
$$J_t x = J_s((s/t)x \oplus (1 - s/t)J_t x).$$

Recall that a mapping $T: D \mapsto \mathbb{B}$ is said to be firmly nonexpansive of the first kind [3, page 124] if for each x and y in D, the function $\phi: [0,1] \mapsto [0,\infty)$ defined by

(2.9)
$$\phi(s) := \rho((1-s)x \oplus sTx, (1-s)y \oplus sTy), \ 0 \le s \le 1,$$

is decreasing. The set of all firmly nonexpansive mappings of the first kind will be denoted by FN_1 .

A proof of our next lemma (based on the resolvent identity (2.8)) can be found in [5, Section 2].

Lemma 2.3. Any resolvent of a coaccretive operator is firmly nonexpansive of the first kind.

We say that a coaccretive operator $T \subset \mathbb{B} \times \mathbb{B}$ is *m*-coaccretive if

$$(2.10) R((1+r)I \ominus rT) = \mathbb{B}$$

for all positive r.

Actually, given a coaccretive operator T, the assumption that (2.10) holds when r = 1 already implies that it holds for all r > 0. Any ρ -nonexpansive mapping $T : \mathbb{B} \to \mathbb{B}$ is *m*-coaccretive.

Lemma 2.4. If $0 \le \alpha < 1$ and the mapping $f : \mathbb{B} \mapsto \alpha \mathbb{B}$ is holomorphic, then f is a strict ρ -contraction with a ρ -Lipschitz constant α .

Proof. Since our claim is obviously true when $\alpha = 0$, we may assume that α is positive. In this case, the mapping $g = f/\alpha$ is a holomorphic self-mapping of \mathbb{B} . Hence it is ρ -nonexpansive and we have $\rho(f(x), f(y)) = \rho(\alpha g(x), \alpha g(y)) \leq \alpha \rho(g(x), g(y)) \leq \alpha \rho(x, y)$ by Lemma 2.2.

We conclude this section with a simple consequence of inequality (2.3).

Lemma 2.5. Let f and g be two ρ -Lipschitz self-mappings of \mathbb{B} with Lipschitz constants L and M, respectively, and let $\beta \in [0, 1]$. Then the mapping $h : \mathbb{B} \mapsto \mathbb{B}$ defined by $h(x) := (1 - \beta)f(x) \oplus \beta g(x), x \in \mathbb{B}$, is also ρ -Lipschitz, with Lipschitz constant $(1 - \beta)L + \beta M$.

3. Approximating Curves

Given a ρ -nonexpansive self-mapping T of \mathbb{B} , a holomorphic mapping $f : \mathbb{B} \to \alpha \mathbb{B}$, where $0 \leq \alpha < 1$, and a number $0 \leq t < 1$, we define the point $z_t \in \mathbb{B}$ as the unique fixed point of the strict ρ -contraction $S : \mathbb{B} \mapsto \mathbb{B}$ defined by

$$(3.1) Sx := (1-t)f(x) \oplus tTx, \quad x \in \mathbb{B}.$$

Note that S is indeed a strict ρ -contraction by Lemmata 2.4 and 2.5. It has a unique fixed point because the metric space (\mathbb{B}, ρ) is complete. In other words,

(3.2)
$$z_t = (1-t)f(z_t) \oplus tTz_t, \quad 0 \le t < 1.$$

In this section we recall a few facts regarding the behavior of the *approximating* curve $\{z_t : 0 \le t < 1\}$. See [5, Section 3] for more information regarding this curve and [6, Section 3] for a study of a related, but different approximating curve.

We can also write

where $F_t : \mathbb{B} \to \mathbb{B}$ is the mapping defined on page 123 of [3]. This mapping is, in fact, the resolvent $J_{r(t)}$ of the *m*-coaccretive operator *T*, where r(t) = t/(1-t). In view of Lemma 2.3, it is firmly nonexpansive of the first kind. It may be defined by the equation

(3.4)
$$F_t(x) = (1-t)x \oplus tTF_t(x), \quad x \in \mathbb{B}$$

Next, we recall [3, Theorem 24.1, page 122] (see also [12, Theorem 3.4, page 642]). Note (see [3, pages 110 and 120]) that the fixed point set F(T) of a ρ -nonexpansive self-mapping T of \mathbb{B} is both ρ -closed and ρ -convex, and that the nearest point projection R_K of \mathbb{B} onto a ρ -closed and ρ -convex subset K of \mathbb{B} is ρ -nonexpansive (and belongs to FN_1). The retraction R_K is also strongly nonexpansive [10, 1] and sunny [4, Proposition 5.4].

Proposition 3.1. Let $T : \mathbb{B} \to \mathbb{B}$ be ρ -nonexpansive and let F_t , $0 \le t < 1$, be the family of mappings defined by (3.4). If T has a fixed point, then for each $x \in \mathbb{B}$, the strong $\lim_{t\to 1^-} F_t(x) = R_{F(T)}x$.

Finally, we recall Theorem 3.12 of [5] (the proof of which makes use of Proposition 3.1). We say that a mapping $f : \mathbb{B} \to \mathbb{B}$ is compact if the closure of its image $\overline{f(\mathbb{B})}$ is a compact subset of H.

Proposition 3.2. Let T be a ρ -nonexpansive self-mapping of \mathbb{B} , $f : \mathbb{B} \mapsto \alpha \mathbb{B}$ a holomorphic mapping, where $0 \leq \alpha < 1$, and let z_t , $0 \leq t < 1$, be defined by (3.2). If T has a fixed point and f is compact, then the strong $\lim_{t\to 1^-} z_t = v$, where v is the unique solution of the equation $z = R_{F(T)}(f(z))$.

4. An Iterative Scheme

In this section we study a discrete iterative scheme for approximating fixed points of ρ -nonexpansive self-mappings of \mathbb{B} . The proof of our convergence theorem (Theorem 4.1 below) depends on Proposition 3.2.

Let a sequence $\{\alpha_n \in [0,1) : n \in \mathbb{N}\}$ satisfy the following three conditions:

(4.1)
$$\lim_{n \to \infty} \alpha_n = 1;$$

(4.2)
$$\sum_{n=1}^{\infty} (1 - \alpha_n) = \infty;$$

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(4.3)
$$\lim_{n \to \infty} \frac{\alpha_n - \alpha_{n-1}}{(1 - \alpha_n)^2} = 0.$$

These conditions, which originate with P.-L. Lions [7], are satisfied, for instance, when for each $n \in \mathbb{N}$, $\alpha_n = 1 - n^{-\beta}$, where $0 < \beta < 1$. They had already been used in [9].

Given a ρ -nonexpansive self-mapping of \mathbb{B} , a holomorphic $f : \mathbb{B} \mapsto \alpha \mathbb{B}$, where $0 \leq \alpha < 1$, and a point $x_0 \in \mathbb{B}$, we consider in this section the iterative scheme

(4.4)
$$x_n = (1 - \alpha_n) f(x_{n-1}) \oplus \alpha_n T x_{n-1}, \quad n \in \mathbb{N}.$$

Theorem 4.1. Let T be a ρ -nonexpansive self-mapping of \mathbb{B} , $f: \mathbb{B} \mapsto \alpha \mathbb{B}$ a holomorphic mapping, where $0 \leq \alpha < 1$, $\{\alpha_n \in [0,1) : n \in \mathbb{N}\}$ a sequence satisfying (4.1)-(4.3), and x_0 a point in \mathbb{B} . If T has a fixed point and f is compact, then the sequence $\{x_n : n \in \mathbb{N}\}$ defined by (4.4) converges strongly to the unique solution $v \in \mathbb{B}$ of the equation $z = R_{F(T)}(f(z))$, where $R_{F(T)} : \mathbb{B} \mapsto F(T)$ is the nearest point projection of \mathbb{B} onto the fixed point set F(T) of T.

Proof. Fix $n \in \mathbb{N}$ and consider the mapping $S_n : \mathbb{B} \mapsto \mathbb{B}$ defined by

(4.5)
$$S_n z := (1 - \alpha_n) f(z) \oplus \alpha_n T z, \quad z \in \mathbb{B}$$

In view of Lemmata 2.4 and 2.5, this mapping is a strict ρ -contraction with Lipschitz constant

$$p_n := (1 - \alpha_n)\alpha + \alpha_n < 1.$$

Since the metric space (\mathbb{B}, ρ) is complete, S_n has a unique fixed point $y_n \in \mathbb{B}$. In other words,

(4.6)
$$y_n = (1 - \alpha_n) f(y_n) \oplus \alpha_n T y_n, \quad n \in \mathbb{N}.$$

Note that $y_n = z_{\alpha_n}$ in the notation of equation (3.2) and Section 3. Since we already know by Proposition 3.2 and (4.1) that $y_n \to v$ strongly as $n \to \infty$, it is sufficient to show that $(x_n - y_n) \to 0$ strongly as $n \to \infty$. To this end, we first note that

$$\rho(x_n, y_n) = \rho(S_n x_{n-1}, S_n y_n) \le p_n \rho(x_{n-1}, y_n) \le p_n \rho(x_{n-1}, y_{n-1}) + \rho(y_{n-1}, y_n)$$

for all $n \in \mathbb{N}$. Setting

(4.7)
$$A(m) = \sup_{n \ge m+1} \frac{\rho(y_{n-1}, y_n)}{1 - p_n}$$

for all $m \in \mathbb{N}$, we conclude that

(4.8)
$$\rho(x_n, y_n) \le \rho(x_m, y_m) \prod_{j=m+1}^n p_j + A(m)$$

for all $n \ge m+1$. Since for each $n \ge 2$, the points $S_{n-1}y_{n-1}$ and S_ny_{n-1} lie on the metric segment joining $f(y_{n-1})$ and Ty_{n-1} , and since the sequences $\{y_n : n \in \mathbb{N}\}$

and $\{f(y_n): n \in \mathbb{N}\}\$ are ρ -bounded, there is a number $M \in \mathbb{R}^+$ such that

$$\rho(y_{n-1}, y_n) = \rho(S_{n-1}y_{n-1}, S_n y_n)
\leq \rho(S_{n-1}y_{n-1}, S_n y_{n-1}) + \rho(S_n y_{n-1}, S_n y_n)
= |\alpha_n - \alpha_{n-1}| \rho(f(y_{n-1}), Ty_{n-1}) + \rho(S_n y_{n-1}, S_n y_n)
\leq M |\alpha_n - \alpha_{n-1}| + p_n \rho(y_{n-1}, y_n)$$

for all $n \geq 2$. Hence

(4.9)
$$A(m) \le \frac{M}{(1-\alpha)^2} \sup_{n \ge m+1} \frac{|\alpha_n - \alpha_{n-1}|}{(1-\alpha_n)^2}$$

for all $m \in \mathbb{N}$. Combining (4.2)–(4.3) with (4.8) and (4.9), we now see that $\rho(x_n, y_n) \to 0$ as $n \to \infty$. Since the sequences $\{x_n\}$ and $\{y_n\}$ are ρ -bounded, it follows that $(x_n - y_n) \to 0$ and $x_n \to v$ strongly, as asserted.

This theorem seems to be new even in the special case where the mapping f is a constant. It holds, in particular, when the (complex) Hilbert space H is finite dimensional. It remains an open question whether it continues to hold when H is infinite dimensional and f is no longer assumed to be compact. Note that although f is not assumed to be compact in [6, Theorem 4.1] (which concerns a related, but different iterative scheme), the self-mapping T is assumed to be holomorphic there. It would also be of interest to determine the behavior of the sequence $\{x_n : n \in \mathbb{N}\}$ when other conditions are imposed on the sequence of parameters $\{\alpha_n : n \in \mathbb{N}\}$ and when the mapping T is fixed point free, and to find out if Theorem 4.1 can be extended to other hyperbolic spaces in the sense of [11].

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