



SECOND-ORDER IMPLICIT DIFFERENTIAL INCLUSIONS WITH DISCONTINUOUS RIGHT-HAND SIDE

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ABSTRACT. Given a multifunction $F : [a, b] \times \mathbb{R} \rightarrow 2^{\mathbb{R}}$, we consider the implicit multivalued boundary value problem

$$\begin{cases} h(u''(t)) \in F(t, u(t)) & \text{a.e. in } [a, b] \\ u(a) = u(b) = 0. \end{cases}$$

We prove an existence theorem for solutions $u \in W^{2,p}([a, b])$, where for each $t \in [a, b]$ the multifunction $F(t, \cdot)$ can fail to be lower semicontinuous even at all points $x \in \mathbb{R}$. In particular, our assumptions are satisfied, for instance, if there exist a negligible set $E \subseteq \mathbb{R}$ and a multifunction $G : [a, b] \times \mathbb{R} \rightarrow 2^{\mathbb{R}}$ such that for a.a. $t \in [a, b]$ one has

$$\{x \in \mathbb{R} : G(t, \cdot) \text{ is not l.s.c. at } x\} \cup \{x \in \mathbb{R} : G(t, x) \neq F(t, x)\} \subseteq E.$$

No monotonicity assumption is required for h or F . Our result extends Theorem 3 of [5], in which the explicit case is considered.

1. INTRODUCTION

Recently, in [16], J. Saint Raymond proved the following deep result concerning the existence of Riemann-measurable selections (that is, selections that are continuous at almost each point of their domain) of a given multifunction.

Theorem 1.1 (Theorem 3 of [16]). *Let X be a Polish space (that is, a complete separable metric space) equipped with a σ -finite regular Borel measure, E a metric space and $F : X \rightarrow 2^E$ a multifunction with nonempty complete values. If F is lower semicontinuous at almost every point of X , then F admits a selection which is continuous at almost every point of X .*

Then, in the paper [5], the following parametrized version of Theorem 1.1 was established (where \mathcal{T}_μ denotes the completion of the Borel σ -algebra $\mathcal{B}(T)$ of T with respect to the measure μ).

Theorem 1.2 (Theorem 2 of [5]). *Let T, X be two Polish spaces and let μ, ψ be two positive regular Borel measures on T and X , respectively, with μ finite and ψ σ -finite. Let S be a separable metric space, $F : T \times X \rightarrow 2^S$ a multifunction with nonempty complete values, and let $E \subseteq X$ be a given set. Assume that:*

- (i) F is $\mathcal{T}_\mu \otimes \mathcal{B}(X)$ -measurable;

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(ii) for a.a. $t \in T$, one has

$$\{x \in X : F(t, \cdot) \text{ is not lower semicontinuous at } x\} \subseteq E.$$

Then, there exist a selection $\phi : T \times X \rightarrow S$ of F and a set $V \in \mathcal{B}(X)$, with $\psi(V) = 0$, such that:

- (a) $\phi(\cdot, x)$ is \mathcal{T}_μ -measurable for each $x \in X \setminus (E \cup V)$;
- (b) for a.a. $t \in T$, one has

$$\{x \in X : \phi(t, \cdot) \text{ is not continuous at } x\} \subseteq E \cup V.$$

As an application of Theorem 1.2, the following existence result for solutions of second-order (scalar) differential inclusions was proved in [5] (as usual, $W^{2,p}([a, b])$ denotes the space of all functions $u \in C^1([a, b])$ such that u' is absolutely continuous in $[a, b]$ and $u'' \in L^p([a, b])$; moreover, $\mathcal{L}([a, b])$ will denote the family of all Lebesgue-measurable subsets of $[a, b]$).

Theorem 1.3 (Theorem 3 of [5]). *Let $[a, b]$ be a closed interval, $F : [a, b] \times \mathbb{R} \rightarrow 2^{\mathbb{R}}$ a multifunction, $p \in [1, +\infty[$.*

Assume that there exists a multifunction $G : [a, b] \times \mathbb{R} \rightarrow 2^{\mathbb{R}}$, with nonempty closed values, and two functions $\alpha : [a, b] \rightarrow]0, +\infty[$ and $\beta \in L^p([a, b])$ such that:

- (i) G is $\mathcal{L}([a, b]) \otimes \mathcal{B}(\mathbb{R})$ -measurable;
- (ii) there exists $E \subseteq \mathbb{R}$, with $m(E) = 0$, such that for a.a. $t \in [a, b]$ one has

$$\{x \in \mathbb{R} : G(t, \cdot) \text{ is not l.s.c. at } x\} \cup \{x \in \mathbb{R} : G(t, x) \not\subseteq F(t, x)\} \subseteq E;$$

- (iii) for a.a. $t \in [a, b]$ and for all $x \in \mathbb{R}$, one has

$$G(t, x) \subseteq [\alpha(t), \beta(t)].$$

Then, there exists $u \in W^{2,p}([a, b])$ such that

$$\begin{cases} u''(t) \in F(t, u(t)) & \text{for a.a. } t \in [a, b] \\ u(a) = u(b) = 0. \end{cases}$$

The aim of this note is simply to extend Theorem 1.3 to the implicit case. Namely, our aim is to prove the following result.

Theorem 1.4. *Let $[a, b]$, F , p , G , α and β be as in Theorem 1.3. Let $A \subseteq]0, +\infty[$ be another interval, and $h : A \rightarrow \mathbb{R}$ a continuous function. Assume that assumptions (i) and (ii) of Theorem 1.3 are satisfied. Moreover, assume that:*

- (iii)' $\text{int}(h^{-1}(z)) = \emptyset$ for all $z \in \text{int}(h(A))$;
- (iv)' for a.a. $t \in [a, b]$ and for all $x \in \mathbb{R}$, one has

$$G(t, x) \subseteq h(A) \quad \text{and} \quad h^{-1}(G(t, x)) \subseteq [\alpha(t), \beta(t)] \subseteq A.$$

Then, there exists $u \in W^{2,p}([a, b])$ such that

$$(1.1) \quad \begin{cases} h(u''(t)) \in F(t, u(t)) & \text{for a.a. } t \in [a, b] \\ u(a) = u(b) = 0. \end{cases}$$

Of course, the main peculiarity of Theorems 1.3 and 1.4 resides in the kind of discontinuity that is allowed for F . Indeed, assumption (ii) of Theorem 1.3 is satisfied, for instance, if (taking $F = G$) there exists a null-measure set $E \subseteq \mathbb{R}$ such that for a.a. $t \in [a, b]$ one has

$$\{x \in \mathbb{R} : F(t, \cdot) \text{ is not lower semicontinuous at } x\} \subseteq E.$$

As a matter of fact, Theorems 1.3 and 1.4 allow much more discontinuity for F . Assumption (ii) is satisfied, for instance, if for a.a. $t \in [a, b]$ one has

$$\{x \in \mathbb{R} : G(t, \cdot) \text{ is not l.s.c. at } x\} \cup \{x \in \mathbb{R} : G(t, x) \neq F(t, x)\} \subseteq E,$$

where $G : [a, b] \times \mathbb{R} \rightarrow 2^{\mathbb{R}}$ is a multifunction and $E \subseteq \mathbb{R}$ has null Lebesgue measure. In this case, for a.a. $t \in [a, b]$, the multifunction $F(t, \cdot)$ is required to be a.e. equal to a multifunction $G(t, \cdot)$ which, in turn, is a.e. lower semicontinuous in \mathbb{R} . As can be easily seen, such a multifunction F can fail to be lower semicontinuous even at all points $x \in \mathbb{R}$. Therefore, assumption (ii) of Theorem 1.3 seems to be much less restrictive than the usual lower semicontinuity, Lipschitz, Caratheodory, almost lower semicontinuity conditions usually required in the literature (see, for instance, [1–3, 6–8, 12, 13] and the references therein).

In particular, when F is single-valued, assumption (ii) is satisfied if there exist a $\mathcal{L}([a, b]) \otimes \mathcal{B}(\mathbb{R})$ -measurable single-valued function $g : [a, b] \times \mathbb{R} \rightarrow \mathbb{R}$ and a null-measure set $E \subseteq \mathbb{R}$ such that for a.e. $t \in [a, b]$ one has

$$\{x \in \mathbb{R} : g(t, \cdot) \text{ is discontinuous at } x\} \cup \{x \in \mathbb{R} : g(t, x) \neq F(t, x)\} \subseteq E.$$

It is easy to see that such a function F can be discontinuous in the second variable *even at all points* $x \in \mathbb{R}$. For instance, one can take (in the autonomous case) $F(x)$ as the usual Dirichlet function, which is discontinuous at each point $x \in \mathbb{R}$ and it is a.e. equal to a constant function. In this connection, it is useful to compare Theorem 1.4 with Theorem 2.2 of [12], where the implicit (single-valued) boundary value problem 1.1 is studied by assuming the continuity of F (under the same hypotheses on h).

The proof of Theorem 1.4 will be given in Section 2. The main tools will be the notion of inductively open function and a related result by B. Ricceri (Theorem 2.4 of [15]), together with Theorem 1.2 and an existence result for explicit and graph-closed differential inclusions (Theorem 3 of [14]).

It is worth noticing that in Theorem 1.4 no convexity assumption is required on the values of F . For the basic definitions and facts on multifunctions, the reader is referred to [11].

2. PROOF OF THEOREM 1.4

First, we observe that by assumption (iii)' and Theorem 2.4 of [15] the function h is inductively open. That is, there exists a set $Y \in \mathcal{B}(A)$ such that the function

$$h|_Y : Y \rightarrow h(A)$$

is open and $h(Y) = h(A)$. It follows that the multifunction $T : h(A) \rightarrow 2^Y$ defined by putting, for each $s \in h(A)$,

$$T(s) = h^{-1}(s) \cap Y$$

is lower semicontinuous in $h(A)$ with nonempty values. To see this, fix any set $\Omega_Y \subseteq Y$, with Ω_Y open in the relative topology of Y . We get

$$\begin{aligned} T^-(\Omega_Y) &:= \{s \in h(A) : T(s) \cap \Omega_Y \neq \emptyset\} \\ &= \{s \in h(A) : h^{-1}(s) \cap Y \cap \Omega_Y \neq \emptyset\} \\ &= \{s \in h(A) : h^{-1}(s) \cap \Omega_Y \neq \emptyset\} \\ &= h(\Omega_Y). \end{aligned}$$

Since the function $h|_Y : Y \rightarrow h(A)$ is open, the set $h(\Omega_Y)$ is open in $h(A)$. It follows that the set $T^-(\Omega_Y)$ is open in $h(A)$, hence T is lower semicontinuous in $h(A)$, as claimed.

Without loss of generality we can assume that assumptions (ii) and (iv)' are satisfied for all $t \in [a, b]$. Let $\Psi : [a, b] \times \mathbb{R} \rightarrow 2^Y$ be defined by

$$\Psi(t, x) := T(G(t, x)) = h^{-1}(G(t, x)) \cap Y$$

(note that Ψ is well-defined since $G(t, x) \subseteq h(A)$ for all $(t, x) \in [a, b] \times \mathbb{R}$). We observe the following facts:

(a) the multifunction Ψ is $\mathcal{L}([a, b]) \otimes \mathcal{B}(\mathbb{R})$ -weakly measurable. That is, for each set $\Omega \subseteq Y$, with Ω open in the relative topology of Y , the set

$$\Psi^-(\Omega) = \{(t, x) \in [a, b] \times \mathbb{R} : \Psi(t, x) \cap \Omega \neq \emptyset\}$$

belongs to $\mathcal{L}([a, b]) \otimes \mathcal{B}(\mathbb{R})$ (this follows from Proposition 13.2.1 of [11], since G is $\mathcal{L}([a, b]) \otimes \mathcal{B}(\mathbb{R})$ -measurable and T is lower semicontinuous);

(b) Ψ has nonempty values and for all $t \in [a, b]$ one has

$$\{x \in \mathbb{R} : \Psi(t, \cdot) \text{ is not lower semicontinuous at } x\} \subseteq E.$$

Indeed, if $t \in [a, b]$ and $\bar{x} \in \mathbb{R} \setminus E$ are fixed, then the multifunction $G(t, \cdot)$ is lower semicontinuous at \bar{x} , hence (by the lower semicontinuity of T) the multifunction

$$x \in \mathbb{R} \rightarrow \Psi(t, x) = T(G(t, x))$$

is lower semicontinuous at \bar{x} , as claimed.

Now, let $\bar{\Psi} : [a, b] \times \mathbb{R} \rightarrow 2^{\mathbb{R}}$ be defined by

$$\bar{\Psi}(t, x) = \overline{\Psi(t, x)}.$$

It follows by assumption (iv)' and by construction that

$$(2.1) \quad \bar{\Psi}(t, x) \subseteq [\alpha(t), \beta(t)] \quad \text{for all } (t, x) \in [a, b] \times \mathbb{R}.$$

By Proposition 2.6 and Theorem 3.5 of [10], the multifunction $\bar{\Psi}$ is $\mathcal{L}([a, b]) \otimes \mathcal{B}(\mathbb{R})$ -measurable with nonempty values. Moreover, for all $t \in [a, b]$ one has

$$\{x \in \mathbb{R} : \bar{\Psi}(t, \cdot) \text{ is not l.s.c. at } x\} \subseteq E.$$

By Theorem 1.2, there exists a selection $\phi : [a, b] \times \mathbb{R} \rightarrow \mathbb{R}$ of $\bar{\Psi}$ and two negligible sets

$$K_1 \subseteq [a, b] \quad \text{and} \quad V \subseteq \mathbb{R}$$

such that, if one puts $D := E \cup V$, one has

(a)' for each $x \in \mathbb{R} \setminus D$, the function $\phi(\cdot, x)$ is measurable;

(b)' for each $t \in [a, b] \setminus K_1$, one has

$$\{x \in \mathbb{R} : \phi(t, \cdot) \text{ is not continuous at } x\} \subseteq D.$$

Moreover, by (2.1) we get

$$(2.2) \quad \phi(t, x) \in [\alpha(t), \beta(t)] \quad \text{for all } (t, x) \in [a, b] \times \mathbb{R}.$$

Since $m(D) = 0$ (m denoting the Lebesgue measure on the real line), there exists a numerable set $P \subseteq \mathbb{R} \setminus D$ which is dense in \mathbb{R} . Let $H : [a, b] \times \mathbb{R} \rightarrow 2^{\mathbb{R}}$ be defined by

$$H(t, x) = \bigcap_{m \in \mathbb{N}} \overline{\text{co}} \left(\bigcup_{y \in P, |y-x| \leq \frac{1}{m}} \{\phi(t, y)\} \right)$$

(where “ $\overline{\text{co}}$ ” stands for “closed convex hull”) By Proposition 2 of [4], we have that:

- (a)'' H has nonempty closed convex values;
- (b)'' for all $x \in \mathbb{R}$, the multifunction $H(\cdot, x)$ is measurable;
- (c)'' for all $t \in [a, b]$, $H(t, \cdot)$ has closed graph;
- (d)'' for all $t \in [a, b] \setminus K_1$, and for all $x \in \mathbb{R} \setminus D$, one has

$$H(t, x) = \{\phi(t, x)\}.$$

Moreover, it follows by (2.2) that

$$H(t, x) \subseteq [\alpha(t), \beta(t)] \quad \text{for all } (t, x) \in [a, b] \times \mathbb{R}.$$

By Theorem 3 of [14] (where we can take $r = \|\beta\|_{L^p([a,b])}$), there exists a function $u \in W^{2,p}([a, b])$ such that

$$\begin{cases} u''(t) \in H(t, u(t)) & \text{for a.a. } t \in [a, b] \\ u(a) = u(b) = 0. \end{cases}$$

Let $K \subseteq [a, b]$, with $K_1 \subseteq K$ and $m(K) = 0$, be such that

$$u''(t) \in H(t, u(t)) \quad \text{for all } t \in [a, b] \setminus K.$$

Since

$$u''(t) \in H(t, u(t)) \subseteq [\alpha(t), \beta(t)] \quad \text{for a.e. } t \in [a, b],$$

we have that $u''(t) > 0$ a.e. in $[a, b]$. It follows easily that u' is strictly increasing in $[a, b]$. Since $u(a) = u(b) = 0$, there exists a point $c \in]a, b[$ such that

$$\begin{aligned} u'(t) < 0 & \quad \text{for all } t \in [a, c[, \\ u'(t) > 0 & \quad \text{for all } t \in]c, b]. \end{aligned}$$

Let

$$g_1 := u|_{[a,c]}, \quad g_2 := u|_{[c,b]}.$$

By Theorem 2 of [17], the functions g_1^{-1} and g_2^{-1} are absolutely continuous. Therefore, by Theorem 18.25 of [9], the sets $g_1^{-1}(D)$ and $g_2^{-1}(D)$ have null Lebesgue measure, hence $m(u^{-1}(D)) = 0$. Consequently, the set

$$S := u^{-1}(D) \cup K$$

has null Lebesgue measure. We claim that

$$(2.3) \quad h(u''(t)) \in F(t, u(t)) \quad \text{for all } t \in [a, b] \setminus S.$$

To this aim, fix $t \in [a, b] \setminus S$. Since $u(t) \notin D$ and $t \notin K$, we get

$$u''(t) \in H(t, u(t)) = \{\phi(t, u(t))\},$$

hence

$$(2.4) \quad u''(t) \in \overline{\Psi}(t, u(t)) = \overline{h^{-1}(G(t, u(t)) \cap Y} \subseteq \overline{h^{-1}(G(t, u(t)))}.$$

Since $G(t, u(t))$ is closed and h is continuous, the set $W := h^{-1}(G(t, u(t)))$ is closed in A . By (iv)', we have

$$W := h^{-1}(G(t, u(t))) \subseteq [\alpha(t), \beta(t)] \subseteq A,$$

hence W is closed in \mathbb{R} . Consequently, by (2.4) we get

$$u''(t) \in \overline{h^{-1}(G(t, u(t)))} = h^{-1}(G(t, u(t))),$$

and thus $h(u''(t)) \in G(t, u(t))$. Since $u(t) \notin E$, we get $G(t, u(t)) \subseteq F(t, u(t))$, hence

$$h(u''(t)) \in F(t, u(t))$$

and our claim (2.3) is proved. Consequently, the function u satisfies the conclusion.

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