# STRONG CONVERGENCE THEOREMS FOR GENERALIZED NONEXPANSIVE MAPPINGS WITH THE SYSTEM OF EQUILIBRIUM PROBLEMS IN BANACH SPACES 

WARUNUN INTHAKON


#### Abstract

In this paper, by using the shrinking projection method, we prove strong convergence theorems for finding a common element of the fixed points set of a generalized nonexpansive mapping and the set of common solutions of a family of equilibrium problems with bifunctions defined on the dual space of a Banach space.


## 1. Introduction

Let $E$ be a Banach space and $C$ be a nonempty, closed and convex subset of $E$. A mapping $T: C \rightarrow C$ is called nonexpansive if $\|T x-T y\| \leq\|x-y\|$ for all $x, y \in C$. Denote the set of all fixed points of $T$ by $F(T)$, i.e., $F(T)=\{x \in C: T x=x\}$.

In 2008, Takahashi, Takeuchi, and Kubota [19] introduced an iterative method called the shrinking projection as follows: $x_{0} \in H, C_{1}=C, x_{1}=P_{C_{1}} x_{0}$ and

$$
\left\{\begin{array}{l}
y_{n}=\alpha_{n} x_{n}+\left(1-\alpha_{n}\right) T x_{n} \\
C_{n+1}=\left\{z \in C_{n}:\left\|y_{n}-z\right\| \leq\left\|x_{n}-z\right\|\right\} \\
x_{n+1}=P_{C_{n+1}} x_{0}
\end{array}\right.
$$

where $n \in \mathbb{N}$ and $\left\{\alpha_{n}\right\} \subset[0,1]$ and $P_{C_{n}}$ is the metric projection of $H$ onto $C_{n}$. Under the certain control conditions, they proved that the sequence $\left\{x_{n}\right\}$ converges strongly to $P_{F(T)} x$, where $P_{F(T)}$ is the metric projection of $H$ onto $F(T)$. Since then, many authors used the shrinking projection method for proving strong convergence theorems in Banach spaces. (See for instance, $[10,11,12]$ and the references therein.) Later, in 2009, Kimura and Takahashi [14] proved strong convergence theorems for a family of relatively nonexpansive mappings in a Banach space by using the shrinking projection method.

Let $f$ be a bifunction from $C \times C$ to $\mathbb{R}$. The equilibrium problem is to find

$$
\begin{equation*}
\hat{x} \in C \quad \text { such that } f(\hat{x}, y) \geq 0, \quad \forall y \in C . \tag{1.1}
\end{equation*}
$$

The set of solutions of (1.1) is denoted by $E P(f)$. Finding such a solution is an important way to solve numerous problems in optimization problems, variational inequalities, minimax problems, games theory and others. (See Blum and Oettli [3],

[^0]Combettes and Hirstoaga [5] and Moudafi [17].) The system of equilibrium problems is to find $\hat{x} \in C$ such that

$$
\begin{equation*}
\hat{x} \in C \quad \text { such that } f_{\lambda}(\hat{x}, y) \geq 0, \quad \forall y \in C \text { and } \forall \lambda \in \Lambda . \tag{1.2}
\end{equation*}
$$

If $\Lambda$ is a singleton, then the problem (1.2) reduces to the problem (1.1).
In 2008, Takahashi and Zembayashi [21] considered the equilibrium problem with a bifunction defined on the dual space of a Banach space as follows: Let $E$ be a smooth Banach space with its dual $E^{*}$. Let $C$ be a nonempty and closed subset of $E$ such that $J C$ is a closed and convex subset of $E^{*}$, where $J$ is the duality mapping on $E$. Let $f$ be a bifunction from $J C \times J C$ to $\mathbb{R}$. Then the equilibrium problem is to find

$$
\hat{x} \in C \quad \text { such that } f(J \hat{x}, J y) \geq 0, \quad \forall y \in C .
$$

Consequently, the authors obtained a strong convergence theorem for finding a solution of the equilibrium problem. Since then, the problem has been studied by the others such as $[6,9,22]$. Recently, Takahashi and Yao [20] proved strong convergence theorems for nonlinear operators with this equilibrium problem in Banach spaces.

In this paper, motivated by [14] and [20], we prove strong convergence theorems for generalized nonexpansive mappings with the system of equilibrium problems with bifunctions defined on the dual of a Banach space.

## 2. Preliminaries

Let $E$ be a real Banach space with its dual $E^{*}$. The modulus $\delta$ of convexity of $E$ is defined by

$$
\delta(\epsilon)=\inf \left\{1-\frac{\|x+y\|}{2}:\|x\| \leq 1,\|y\| \leq 1,\|x-y\| \geq \epsilon\right\}
$$

for every $\epsilon$ with $0 \leq \epsilon \leq 2$. A Banach space $E$ is said to be uniformly convex if $\delta(\epsilon)>0$ for every $\epsilon>0$. Let $B=\{x \in E:\|x\|=1\}$. The norm of $E$ is said to be Gâteuax differentiable if for each $x, y \in B$, the limit

$$
\begin{equation*}
\lim _{t \rightarrow 0} \frac{\|x+t y\|-\|x\|}{t} \tag{2.1}
\end{equation*}
$$

exists. In this case, $E$ is called smooth. The norm of $E$ is said to be uniformly Gâteuax differentiable if for each $y \in B$, the limit (2.1) is attained uniformly for all $x \in B$. It is also said to be Fréchet differentiable if for each $x \in B$, the limit (2.1) is attained uniformly for all $y \in B$. We denote the value of $x^{*}$ at $x$ by $\left\langle x, x^{*}\right\rangle$. Then the duality mapping $J$ on $E$ defined by

$$
J(x)=\left\{x^{*} \in E^{*}:\left\langle x, x^{*}\right\rangle=\|x\|^{2}=\left\|x^{*}\right\|^{2}\right\}
$$

for every $x \in E$. It is known that if the norm of $E$ is uniformly Gâteuax differentiable, then the duality mapping $J$ is single valued and uniformly norm to weak* continuous on each bounded subset of $E$. If the norm of $E$ is Fréchet differentiable, then $J$ is norm-to-norm continuous. Furthermore, if $E$ is smooth, strictly convex and reflexive, then the duality mapping $J$ is single-valued, one-to-one and onto; see $[4,18]$ for more details.

Let $E$ be a smooth Banach space and consider the following function studied by Alber [1] and Kamimura and Takahashi [13]. Let $\phi: E \times E \rightarrow[0, \infty)$ be the mapping defined by

$$
\phi(x, y)=\|x\|^{2}-2\langle x, J y\rangle+\|y\|^{2}
$$

for all $(x, y) \in E \times E$. We know that

$$
\begin{equation*}
\phi(x, y)=\phi(x, z)+\phi(z, y)+2\langle x-z, J z-J y\rangle \tag{2.2}
\end{equation*}
$$

for each $x, y, z \in E$. By the fact that $(\|x\|-\|y\|)^{2} \leq \phi(x, y)$ for all $x, y \in E$, we can see that $\phi(x, y) \geq 0$, for all $x, y \in E$. Let $\phi_{*}: E^{*} \times E^{*} \rightarrow[0, \infty)$ be the mapping defined by

$$
\phi_{*}\left(x^{*}, y^{*}\right)=\left\|x^{*}\right\|^{2}-2\left\langle J^{-1} y^{*}, x^{*}\right\rangle+\left\|y^{*}\right\|^{2}
$$

for all $\left(x^{*}, y^{*}\right) \in E^{*} \times E^{*}$. It is easy to see that

$$
\phi(x, y)=\phi_{*}(J y, J x)
$$

for all $x, y \in E$. If $E$ is additionally assumed to be strictly convex, then

$$
\phi(x, y)=0 \Leftrightarrow x=y
$$

As is well known, the authors [13] proved the following theroem.
Theorem 2.1 ([13]). Let $E$ be a smooth and uniformly convex Banach space and let $\left\{x_{n}\right\}$ and $\left\{y_{n}\right\}$ be sequences in $E$ such that either $\left\{x_{n}\right\}$ or $\left\{y_{n}\right\}$ is bounded. If $\lim _{n \rightarrow \infty} \phi\left(x_{n}, y_{n}\right)=0$, then $\lim _{n \rightarrow \infty}\left\|x_{n}-y_{n}\right\|=0$.

If $\left\{C_{n}\right\}$ is a sequence of nonempty, closed and convex subsets of a reflexive Banach space $E$, the set $s-L i_{n} C_{n}$ is called the set of limit points of $\left\{C_{n}\right\}$ and $w-L s_{n} C_{n}$ is called the set of weak cluster points of $\left\{C_{n}\right\}$. That is, $x \in s-L i_{n} C_{n}$ if and only if there exists $\left\{x_{n}\right\} \subset E$ such that $x_{n} \in C_{n}$ for each $n \in \mathbb{N}$ and $x_{n} \rightarrow x$ as $n \rightarrow \infty$; and $y \in w-L s_{n} C_{n}$ if and only if there exists $\left\{y_{n_{i}}\right\} \subset E$ such that $y_{n_{i}} \in C_{n_{i}}$ for each $i \in \mathbb{N}$ and $y_{n_{i}} \rightharpoonup y$ as $i \rightarrow \infty$. If $C_{0}$ satisfies that

$$
s-L i_{n} C_{n}=C_{0}=w-L s_{n} C_{n}
$$

then we say that $\left\{C_{n}\right\}$ converges to $C_{0}$ in the sense of Mosco [16] and we denote by $C_{0}=M-\lim _{n \rightarrow \infty} C_{n}$. If $\left\{C_{n}\right\}$ is nonincreasing with respect to inclusion, then $\left\{C_{n}\right\}$ converges to $\bigcap_{n=1}^{\infty} C_{n}$ in the sense of Mosco; see [16] for more details.

In 2003, the following was proved by Ibaraki, Kimura, and Takahashi [7].
Theorem 2.2 ([7]). Let $E$ be a smooth Banach space such that $E^{*}$ has a Fréchet differentiable norm. Let $\left\{C_{n}\right\}$ be a sequence of nonempty, closed and convex subsets of $E$. If $C_{0}=M-\lim _{n \rightarrow \infty} C_{n}$ exists and nonempty, then for each $x \in E, \Pi_{C_{n}} x$ converges strongly to $\Pi_{C_{0}} x$, where $\Pi_{C_{n}}$ and $\Pi_{C_{0}}$ are the generalized projections of $E$ onto $C_{n}$ and $C_{0}$, respectively.

Let $C$ be a nonempty, closed and convex subset of a smooth Banach space $E$. A mapping $T: C \rightarrow C$ is a generalized nonexpansive type if

$$
\phi(T x, T y)+\phi(T y, T x) \leq \phi(x, T y)+\phi(y, T x)
$$

for all $x, y \in C$.
A mapping $T: C \rightarrow E$ is called generalized nonexpansive $[8]$ if $F(T) \neq \emptyset$ and

$$
\phi(T x, y) \leq \phi(x, y), \quad \forall x \in C, \forall y \in F(T),
$$

where $F(T)$ is the set of fixed points of $T$. A point $p \in C$ is said to be a generalized asymptotic fixed point of $T$ if there exists a sequence $\left\{x_{n}\right\}$ in $C$ such that $J x_{n} \rightarrow$ $J p$ and $\lim _{n \rightarrow \infty}\left\|x_{n}-T x_{n}\right\|=0$; see [10]. We denote the set of all generalized asymptotic fixed points of $T$ by $\dot{F}(T)$.

Recently, Takahashi and Yao [20] proved the following:
Theorem 2.3 ([20]). Let E be a smooth and reflexive Banach space such that $E^{*}$ has a uniformly Gâteaux differentiable norm. Let $C$ be a closed subset of $E$ such that JC is closed and convex and let $T: C \rightarrow C$ be a generalized nonexpansive type mapping. Then, the followings hold:
(1) $\check{F}(T)=F(T)$;
(2) $J F(T)$ is closed and convex;
(3) $F(T)$ is closed.

A nonempty and closed subset $C$ of a smooth Banach space $E$ is said to be a sunny generalized nonexpansive retract of $E$ if there exists a sunny generalized nonexpansive retraction $R$ from $E$ onto $C$. We know the following lemmas from Ibaraki and Takahashi [8]:
Lemma 2.4 ([8]). Let $C$ be a nonempty, closed and convex subset of a smooth and strictly convex Banach space $E$. Then the sunny generalized nonexpansive retraction from $E$ to $C$ is uniquely determined.

Lemma 2.5 ([8]). Let $C$ be a nonempty, closed and convex subset of a smooth and strictly convex Banach space $E$ such that there exists a sunny generalized nonexpansive retraction from $E$ onto $C$ and let $(x, z) \in E \times C$. Then the followings hold:
(1) $z=R x$ if and only if $\langle x-z, J y-J z\rangle \leq 0$ for all $y \in C$;
(2) $\phi(R x, z)+\phi(x, R x) \leq \phi(x, z)$.

In 2007, Kohsaka and Takahashi [15] proved the following results:
Theorem 2.6 ([15]). Let $E$ be a smooth, strictly convex and reflexive Banach space and let $C_{*}$ be a nonempty, closed and convex subset of $E^{*}$. Suppose that $\Pi_{C_{*}}$ is the generalized projection of $E^{*}$ onto $C_{*}$. Then $R$ defined by $R=J^{-1} \Pi_{C_{*}} J$ is a sunny generalized nonexpansive retraction of $E$ onto $J^{-1} C_{*}$.
Theorem 2.7 ([15]). Let $E$ be a smooth, strictly convex and reflexive Banach space and let $C$ be a nonempty and closed subset of $E$. Then the followings are equivalent:
(1) $C$ is a sunny generalized nonexpansive retract of $E$;
(2) $C$ is a generalized nonexpansive retract of $E$;
(3) JC is closed and convex.

Lemma 2.8 ([15]). Let $E$ be a smooth, strictly convex and reflexive Banach space and let $C$ be a nonempty and closed sunny generalized nonexpansive retract of $E$. Let $R$ be the sunny generalized nonexpansive retraction from $E$ onto $C$ and let $(x, z) \in E \times C$. Then the followings are equivalent:
(1) $z=R x$;
(2) $\phi(x, z)=\min _{y \in C} \phi(x, y)$.

We know some structures of the set of fixed points of a generalized nonexpansive mapping from the following results:
Theorem 2.9 ([10, 12]). Let E be a smooth, strictly convex and reflexive Banach space and let $C$ be a closed subset of $E$ such that JC is closed and convex. If $T: C \rightarrow C$ is a generalized nonexpansive mapping such that $F(T) \neq \emptyset$, then $F(T)$ is closed and $J F(T)$ is closed and convex.

Theorem 2.10 ([10, 12]). Let E be a smooth, strictly convex and reflexive Banach space and $C$ be a closed subset of $E$ such that $J C$ is closed and convex. If $T: C \rightarrow C$ is a generalized nonexpansive mapping such that $F(T) \neq \emptyset$, then $F(T)$ is a sunny generalized nonexpansive retract of $E$.

Let $C$ be a nonempty and closed subset of a smooth, strictly convex and reflexive Banach space $E$ such that $J C$ is closed and convex. For solving the equilibrium problem, let us assume that a bifunction $f$ from $J C \times J C$ to $\mathbb{R}$ satisfying the following conditions:
(A1) $f\left(x^{*}, x^{*}\right)=0$ for all $x^{*} \in J C$;
(A2) $f$ is monotone, i.e. $f\left(x^{*}, y^{*}\right)+f\left(y^{*}, x^{*}\right) \leq 0$ for all $x^{*}, y^{*} \in J C$;
(A3) for all $x^{*}, y^{*}, z^{*} \in J C$,

$$
\underset{t \downarrow 0}{\lim \sup } f\left(t z^{*}+(1-t) x^{*}, y^{*}\right) \leq f\left(x^{*}, y^{*}\right) ;
$$

(A4) for all $x^{*} \in J C, f\left(x^{*}, \cdot\right)$ is convex and lower semicontinuous.
The followings are some results on such a bifunction :
Lemma 2.11 ([2, 3]). Let $C$ be a closed subset of a smooth, strictly convex and reflexive Banach space $E$ such that $J C$ is closed and convex, let $f$ be a bifunction from $J C \times J C$ to $\mathbb{R}$ satisfying (A1)-(A4), let $r>0$ and let $x \in E$. Then, there exists $z \in C$ such that

$$
f(J z, J y)+\frac{1}{r}\langle z-x, J y-J z\rangle \geq 0 \quad \text { for all } y \in C .
$$

Lemma 2.12 ([21]). Let $C$ be a closed subset of a uniformly smooth and strictly convex Banach space E such that JC is closed and convex, and let $f$ be a bifunction from $J C \times J C$ to $\mathbb{R}$ satisfying (A1)-(A4). For $r>0$ and $x \in E$, define a mapping $T_{r}: E \rightarrow C$ as follows :

$$
T_{r}(x)=\left\{z \in C: f(J z, J y)+\frac{1}{r}\langle z-x, J y-J z\rangle \geq 0 \text { for all } y \in C\right\}
$$

for all $x \in E$. Then, the followings hold:
(1) $T_{r}$ is single-valued;
(2) for all $x, y \in E$,

$$
\left\langle T_{r} x-T_{r} y, J T_{r} x-J T_{r} y\right\rangle \leq\left\langle x-y, J T_{r} x-J T_{r} y\right\rangle ;
$$

(3) $F\left(T_{r}\right)=E P(f)$;
(4) $J E P(f)$ is closed and convex.

Lemma 2.13 ([21]). Let $C$ be a closed subset of a smooth, strictly convex, and reflexive Banach space $E$ such that JC is closed and convex, let $f$ be a bifunction from $J C \times J C$ to $\mathbb{R}$ satisfying $(A 1)-(A 4)$, and let $r>0$. Then, for $x \in E$ and $q \in F\left(T_{r}\right)$,

$$
\phi\left(x, T_{r} x\right)+\phi\left(T_{r} x, q\right) \leq \phi(x, q)
$$

## 3. Strong convergence theorems with a system of equilibrium PROBLEMS

Motivated by [20] and [14], we obtain the following theorem.
Theorem 3.1. Let $E$ be a uniformly convex and uniformly smooth Banach space and let $C$ be a nonempty and closed subset of $E$ such that JC is closed and convex. Let $\left\{f_{\lambda}: \lambda \in \Lambda\right\}$ be a family of bifunctions from $J C \times J C$ to $\mathbb{R}$ satisfying $(A 1)-(A 4)$. Let $T: C \rightarrow C$ be a generalized nonexpansive mapping such that $\check{F}(T)=F(T)$ and $F(T) \cap F^{*} \neq \emptyset$, where $F^{*}=\bigcap_{\lambda \in \Lambda} E P\left(f_{\lambda}\right)$. Let $C_{1}=C$ and $\left\{x_{n}\right\}$ be a sequence generated by $x_{1}=x \in C$ and

$$
\left\{\begin{array}{l}
z_{n, \lambda} \in C \text { such that } f_{\lambda}\left(J z_{n, \lambda}, J y\right)+\frac{1}{r_{\lambda}}\left\langle z_{n, \lambda}-x_{n}, J y-J z_{n, \lambda}\right\rangle \geq 0, \\
y_{n, \lambda}=\alpha_{n} x_{n}+\left(1-\alpha_{n}\right) T z_{n, \lambda}, \quad \forall \lambda \in \Lambda, \\
C_{n+1}=\left\{z \in C_{n}: \sup _{\lambda \in \Lambda} \phi\left(y_{n, \lambda}, z\right) \leq \phi\left(x_{n}, z\right)\right\}, \\
x_{n+1}=R_{C_{n+1}} x
\end{array}\right.
$$

for every $n \in \mathbb{N}$, where $J$ is the duality mapping on $E$, $\left\{\alpha_{n}\right\} \subset[0,1]$ such that $0 \leq \alpha_{n} \leq a<1$ and $\left\{r_{\lambda}\right\} \subset[0, \infty)$ such that $0<b \leq r_{\lambda}$ for some $a, b \in \mathbb{R}$. Then $\left\{x_{n}\right\}$ converges strongly to $R_{F(T) \cap F^{*}} x$, where $R_{F(T) \cap F^{*}}$ is the sunny generalized nonexpansive retraction from $E$ onto $F(T) \cap F^{*}$.

Proof. We first show that $\left\{x_{n}\right\}$ is well-defined. For each $n \in \mathbb{N}$, put $z_{n, \lambda}=T_{r_{\lambda}} x_{n}$ and let $z \in F(T) \cap F^{*}$. From $z_{n, \lambda}=T_{r_{\lambda}} x_{n}$ and Lemma 2.13, we have that for any $n \in \mathbb{N}$

$$
\phi\left(z_{n, \lambda}, z\right)=\phi\left(T_{r_{\lambda}} x_{n}, z\right) \leq \phi\left(x_{n}, z\right) .
$$

From the assumption, we have $F(T) \cap F^{*} \subset C=C_{1}$. Suppose that $F(T) \cap F^{*} \subset C_{k}$, hence $z \in C_{k}$. From the definition of $T$, we have that for all $\lambda \in \Lambda$

$$
\begin{aligned}
\phi\left(y_{n, \lambda}, z\right) & =\phi\left(\alpha_{n} x_{n}+\left(1-\alpha_{n}\right) T z_{n, \lambda}, z\right) \\
& \leq \alpha_{n} \phi\left(x_{n}, z\right)+\left(1-\alpha_{n}\right) \phi\left(T z_{n, \lambda}, z\right) \\
& \leq \alpha_{n} \phi\left(x_{n}, z\right)+\left(1-\alpha_{n}\right) \phi\left(z_{n, \lambda}, z\right) \\
& \leq \alpha_{n} \phi\left(x_{n}, z\right)+\left(1-\alpha_{n}\right) \phi\left(x_{n}, z\right) \\
& =\phi\left(x_{n}, z\right) .
\end{aligned}
$$

Thus, $\sup _{\lambda \in \Lambda} \phi\left(y_{n, \lambda}, z\right) \leq \phi\left(x_{n}, z\right)$. This implies that $z \in C_{k+1}$ and hence $C_{n}$ is nonempty for all $n \in \mathbb{N}$. By the definition of $\phi$, we obtain that

$$
C_{n+1}=\left\{z \in C_{n}: \sup _{\lambda \in \Lambda} \phi\left(y_{n, \lambda}, z\right) \leq \phi\left(x_{n}, z\right)\right\}
$$

$$
\begin{aligned}
& =\bigcap_{\lambda \in \Lambda}\left\{z \in C_{n}: \phi\left(y_{n, \lambda}, z\right) \leq \phi\left(x_{n}, z\right)\right\} \\
& =\bigcap_{\lambda \in \Lambda}\left\{z \in C: 2\left\langle x_{n}-y_{n, \lambda}, J z\right\rangle+\left\|y_{n, \lambda}\right\|^{2}-\left\|x_{n}\right\|^{2} \leq 0\right\} \cap C_{n},
\end{aligned}
$$

which implies that $C_{n}$ is closed for all $n \in \mathbb{N}$. Since $J$ is injective, we get that

$$
\begin{aligned}
J C_{n+1} & =J\left(\bigcap_{\lambda \in \Lambda}\left\{z \in C: 2\left\langle x_{n}-y_{n, \lambda}, J z\right\rangle+\left\|y_{n, \lambda}\right\|^{2}-\left\|x_{n}\right\|^{2} \leq 0\right\} \cap C_{n}\right) \\
& =\bigcap_{\lambda \in \Lambda}\left\{z^{*} \in J C: 2\left\langle x_{n}-y_{n, \lambda}, z^{*}\right\rangle+\left\|y_{n, \lambda}\right\|^{2}-\left\|x_{n}\right\|^{2} \leq 0\right\} \cap J C_{n},
\end{aligned}
$$

and thus $J C_{n}$ is closed and convex for all $n \in \mathbb{N}$. By Theorem 2.7 and Lemma 2.4, there exists a unique sunny generalized retraction $R_{C_{n}}$ of $E$ onto $C_{n}$. In addition, from Theorem 2.6, we know that $R_{C_{n}}$ is denoted by $J^{-1} \Pi_{J C_{n}} J$, where $\Pi_{J C_{n}}$ is the generalized projection of $E^{*}$ onto $J C_{n}$. Thus $\left\{x_{n}\right\}$ is well-defined.

Since $\left\{J C_{n}\right\}$ is a nonincreasing sequence of nonempty, closed and convex subsets of $E^{*}$ with respect to inclusion, it follows that

$$
\begin{equation*}
M-\lim _{n \rightarrow \infty} J C_{n}=\bigcap_{n=1}^{\infty} J C_{n} . \tag{3.1}
\end{equation*}
$$

Thus, $\emptyset \neq J F(T) \cap J F^{*} \subset \bigcap_{n=1}^{\infty} J C_{n}$. Put $C_{0}^{*}=\bigcap_{n=1}^{\infty} J C_{n}$. From Theorem 2.2, we have that $\left\{\Pi_{J C_{n}} J x\right\}$ converges strongly to $x_{0}^{*}=\Pi_{C_{0}^{*}} J x$. Since $E^{*}$ has a Fréchet differentiable norm, $J^{-1}$ is continuous. Then, we have

$$
J^{-1} \Pi_{J C_{n}} J x \rightarrow J^{-1} x_{0}^{*}
$$

Since $x_{n}=R_{C_{n}} x=J^{-1} \Pi_{J C_{n}} J x$, we can conclude that $\left\{x_{n}\right\}$ converges strongly to $J^{-1} x_{0}^{*}$. We shall show that $J^{-1} x_{0}^{*}=R_{F(T) \cap F^{*}} x$.

Since $x_{n}=R_{C_{n}} x$ and $x_{n+1}=R_{C_{n+1}} x \subset C_{n+1} \subset C_{n}$, we have from Lemma 2.5 and (2.2) that

$$
\begin{aligned}
0 & \leq 2\left\langle x-x_{n}, J x_{n}-J x_{n+1}\right\rangle \\
& =\phi\left(x, x_{n+1}\right)-\phi\left(x, x_{n}\right)-\phi\left(x_{n}, x_{n+1}\right) \\
& \leq-\phi\left(x, x_{n}\right)+\phi\left(x, x_{n+1}\right)
\end{aligned}
$$

which implies $\phi\left(x, x_{n}\right) \leq \phi\left(x, x_{n+1}\right)$ for all $n \in \mathbb{N}$. Further, since $x_{n}=R_{C_{n}} x$ and $z \in F(T) \cap F^{*}$, we have from Lemma 2.8 that

$$
\phi\left(x, x_{n}\right) \leq \phi(x, z) .
$$

Thus, $\left\{\phi\left(x, x_{n}\right)\right\}$ is nondecreasing and bounded which imply that $\lim _{n \rightarrow \infty} \phi\left(x, x_{n}\right)$ exists and hence $\left\{x_{n}\right\}$ is bounded. Therefore, $\left\{y_{n, \lambda}\right\},\left\{z_{n, \lambda}\right\}$ and $\left\{T z_{n, \lambda}\right\}$ are also bounded for all $\lambda \in \Lambda$. From Lemma 2.5, we have

$$
\begin{aligned}
\phi\left(x_{n}, x_{n+1}\right) & =\phi\left(R_{C_{n}} x, x_{n+1}\right) \\
& \leq \phi\left(x, x_{n+1}\right)-\phi\left(x, R_{C_{n}} x\right)
\end{aligned}
$$

$$
=\phi\left(x, x_{n+1}\right)-\phi\left(x, x_{n}\right) \rightarrow 0 .
$$

Then, we have

$$
\begin{equation*}
\lim _{n \rightarrow \infty} \phi\left(x_{n}, x_{n+1}\right)=0 . \tag{3.2}
\end{equation*}
$$

Since $x_{n+1} \in C_{n+1}, \sup _{\lambda \in \Lambda} \phi\left(y_{n, \lambda}, x_{n+1}\right) \leq \phi\left(x_{n}, x_{n+1}\right)$.
Therefore, $\lim _{n \rightarrow \infty} \phi\left(y_{n, \lambda}, x_{n+1}\right)=0$ for all $\lambda \in \Lambda$.
By using Theorem 2.1, we have

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|y_{n, \lambda}-x_{n+1}\right\|=\lim _{n \rightarrow \infty}\left\|x_{n}-x_{n+1}\right\|=0 \tag{3.3}
\end{equation*}
$$

Then for all $\lambda \in \Lambda$, we have

$$
\begin{aligned}
\left\|y_{n, \lambda}-x_{n}\right\| & \leq\left\|y_{n, \lambda}-x_{n+1}\right\|+\left\|x_{n+1}-x_{n}\right\| \\
& \rightarrow 0
\end{aligned}
$$

Since $\left\|x_{n}-y_{n, \lambda}\right\|=\left\|x_{n}-\left(\alpha_{n} x_{n}+\left(1-\alpha_{n}\right) T z_{n, \lambda}\right)\right\|=\left(1-\alpha_{n}\right)\left\|x_{n}-T z_{n, \lambda}\right\|$ and $0 \leq \alpha_{n} \leq a<1$, we have that for all $\lambda \in \Lambda$

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|x_{n}-T z_{n, \lambda}\right\|=0 \tag{3.4}
\end{equation*}
$$

Let $z \in F(T) \cap F^{*}$. Using $z_{n, \lambda}=T_{r_{\lambda}} x_{n}$ and Lemma 2.13, we have that for each $n \in \mathbb{N}$ and $\lambda \in \Lambda$,

$$
\begin{aligned}
\phi\left(x_{n}, z\right) & \geq \phi\left(x_{n}, T_{r_{\lambda}} x_{n}\right)+\phi\left(T_{r_{\lambda}} x_{n}, z\right) \\
& =\phi\left(x_{n}, z_{n, \lambda}\right)+\phi\left(z_{n, \lambda}, z\right),
\end{aligned}
$$

and hence $\phi\left(x_{n}, z_{n, \lambda}\right) \leq \phi\left(x_{n}, z\right)-\phi\left(z_{n, \lambda}, z\right)$. Using the definition of $\phi$ again, we get that

$$
\begin{aligned}
\phi\left(y_{n, \lambda}, z\right) & =\phi\left(\left(\alpha_{n} x_{n}+\left(1-\alpha_{n}\right) T z_{n, \lambda}\right), z\right) \\
& \leq \alpha_{n} \phi\left(x_{n}, z\right)+\left(1-\alpha_{n}\right) \phi\left(z_{n, \lambda}, z\right) .
\end{aligned}
$$

Thus,

$$
\phi\left(z_{n, \lambda}, z\right) \geq \frac{\phi\left(y_{n, \lambda}, z\right)-\alpha_{n} \phi\left(x_{n}, z\right)}{1-\alpha_{n}}
$$

which implies that

$$
\begin{aligned}
\phi\left(x_{n}, z_{n, \lambda}\right) & \leq \phi\left(x_{n}, z\right)-\frac{\phi\left(y_{n, \lambda}, z\right)-\alpha_{n} \phi\left(x_{n}, z\right)}{1-\alpha_{n}} \\
& =\frac{\phi\left(x_{n}, z\right)-\phi\left(y_{n, \lambda}, z\right)}{1-\alpha_{n}} .
\end{aligned}
$$

Consider

$$
\begin{aligned}
\phi\left(x_{n}, z\right)-\phi\left(y_{n, \lambda}, z\right) & =\left\|x_{n}\right\|^{2}-2\left\langle x_{n}, J z\right\rangle+\|z\|^{2}-\left\|y_{n, \lambda}\right\|^{2}+2\left\langle y_{n, \lambda}, J z\right\rangle-\|z\|^{2} \\
& =\left\|x_{n}\right\|^{2}-\left\|y_{n, \lambda}\right\|^{2}-2\left\langle x_{n}-y_{n, \lambda}, J z\right\rangle \\
& \leq\left|\left\|x_{n}\right\|^{2}-\left\|y_{n, \lambda}\right\|^{2}\right|+2\left|\left\langle x_{n}-y_{n, \lambda}, J z\right\rangle\right| \\
& \leq\left(\left\|x_{n}\right\|+\left\|y_{n, \lambda}\right\|\right)\left\|x_{n}-y_{n, \lambda}\right\|+2\left\|x_{n}-y_{n, \lambda}\right\|\|J z\| .
\end{aligned}
$$

Since $\lim _{n \rightarrow \infty}\left\|x_{n}-y_{n, \lambda}\right\|=0, \lim _{n \rightarrow \infty}\left(\phi\left(x_{n}, z\right)-\phi\left(y_{n, \lambda}, z\right)\right)=0$ for all $\lambda \in \Lambda$.
Since $0 \leq \alpha_{n} \leq a<1$, we have $\lim _{n \rightarrow \infty} \phi\left(x_{n}, z_{n, \lambda}\right)=0 \quad$ for all $\lambda \in \Lambda$. From Theorem 2.1 again, we get that

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|x_{n}-z_{n, \lambda}\right\|=0 \tag{3.5}
\end{equation*}
$$

Since $\left\|z_{n, \lambda}-T z_{n, \lambda}\right\| \leq\left\|z_{n, \lambda}-x_{n}\right\|+\left\|x_{n}-T z_{n, \lambda}\right\|$ and from (3.4) and (3.5), we have

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|z_{n, \lambda}-T z_{n, \lambda}\right\|=0 \tag{3.6}
\end{equation*}
$$

for all $\lambda \in \Lambda$. Since $J x_{n}=\prod_{J C_{n}} J x \rightarrow x_{0}^{*}=J J^{-1} x_{0}^{*}$, we have $J z_{n, \lambda} \rightarrow x_{0}^{*}$. Thus, from (3.6) and $\check{F}(T)=F(T)$, we can conclude that $J^{-1} x_{0}^{*} \in F(T)$.

Next, we show that $J^{-1} x_{0}^{*} \in F^{*}$. From $x_{n} \rightarrow J^{-1} x_{0}^{*}$ and (3.5), we have $z_{n, \lambda} \rightarrow$ $J^{-1} x_{0}^{*}$ for all $\lambda \in \Lambda$. By the definition of $z_{n, \lambda}$, we have that for all $y \in C$ and for all $\lambda \in \Lambda$,

$$
f_{\lambda}\left(J z_{n, \lambda}, J y\right)+\frac{1}{r_{\lambda}}\left\langle J y-J z_{n, \lambda}, z_{n, \lambda}-x_{n}\right\rangle \geq 0 .
$$

From (A2), we have that for all $\lambda \in \Lambda$

$$
\frac{1}{r_{\lambda}}\left\langle J y-J z_{n, \lambda}, z_{n, \lambda}-x_{n}\right\rangle \geq f_{\lambda}\left(J y, J z_{n, \lambda}\right)
$$

From $0<b \leq r_{\lambda}$ and (3.5), we get

$$
\lim _{n \rightarrow \infty} \frac{z_{n, \lambda}-x_{n}}{r_{\lambda}}=0 .
$$

Therefore,

$$
\begin{equation*}
0 \geq f_{\lambda}\left(J y, x_{0}^{*}\right) \tag{3.7}
\end{equation*}
$$

For all $t \in(0,1]$ and $y \in C$, put $z_{t}^{*}=t J y+(1-t) x_{0}^{*}$. Since $J C$ is convex, $z_{t}^{*} \in J C$. By using (A1), (A4) and (3.7), we have that for all $\lambda \in \Lambda$

$$
\begin{aligned}
0 & =f_{\lambda}\left(J z_{t}^{*}, J z_{t}^{*}\right) \\
& \leq t f_{\lambda}\left(z_{t}^{*}, J y\right)+(1-t) f_{\lambda}\left(z_{t}^{*}, x_{0}^{*}\right) \\
& \leq t f_{\lambda}\left(z_{t}^{*}, J y\right) .
\end{aligned}
$$

Dividing by $t$, we have $f_{\lambda}\left(z_{t}^{*}, J y\right) \geq 0$ for all $y \in C$. Letting $t \rightarrow 0$, we have from (A3) that

$$
f_{\lambda}\left(x_{0}^{*}, J y\right) \geq 0
$$

for all $y \in C$. Therefore, we have $J^{-1} x_{0}^{*} \in E P\left(f_{\lambda}\right)$ for all $\lambda \in \Lambda$ and hence $J^{-1} x_{0}^{*} \in F^{*}$. This implies that $J^{-1} x_{0}^{*} \in F(T) \cap F^{*}$.

Finally, we show that $J^{-1} x_{0}^{*}=R_{F(T) \cap F^{*}} x$. From Theorem 2.9, we have that $F(T)$ is closed and $J F(T)$ is closed and convex. Moreover, we have from Lemma 2.12 that $E P\left(f_{\lambda}\right)$ is closed and $J E P\left(f_{\lambda}\right)$ is closed and convex for each $\lambda \in \Lambda$. Since $F^{*}=\bigcap_{\lambda \in \Lambda} E P\left(f_{\lambda}\right)$ and $J$ is injective, $J\left(F(T) \cap F^{*}\right)$ is also closed and convex. Then, we have from Theorem 2.7 that $F(T) \cap F^{*}$ is a sunny generalized nonexpansive retract of $E$. Let $z_{0}=R_{F(T) \cap F^{*}} x$. Then $z_{0} \in C_{n+1}$. Since $x_{n+1}=R_{C_{n+1}} x$, we have

$$
\phi\left(x, x_{n+1}\right) \leq \phi\left(x, z_{0}\right)
$$

Therefore,

$$
\phi\left(x, J^{-1} x_{0}^{*}\right)=\lim _{n \rightarrow \infty} \phi\left(x, x_{n}\right) \leq \phi\left(x, z_{0}\right)
$$

Thus, $z_{0}=J^{-1} x_{0}^{*}$ and hence we can complete the proof.

By Theorem 3.1, we have the following result.
Corollary 3.2. Let $E$ be a uniformly convex and uniformly smooth Banach space and let $C$ be a nonempty and closed subset of $E$ such that $J C$ is closed and convex. Let $\left\{f_{\lambda}: \lambda \in \Lambda\right\}$ be a family of bifunctions from $J C \times J C$ to $\mathbb{R}$ satisfying $(A 1)-(A 4)$. Let $T: C \rightarrow C$ be a generalized nonexpansive type mapping and $F(T) \cap F^{*} \neq \emptyset$, where $F^{*}=\bigcap_{\lambda \in \Lambda} E P\left(f_{\lambda}\right)$. Let $C_{1}=C$ and $\left\{x_{n}\right\}$ be a sequence generated by $x_{1}=$ $x \in C$ and

$$
\left\{\begin{array}{l}
\begin{array}{l}
z_{n, \lambda} \in C \text { such that } f_{\lambda}\left(J z_{n, \lambda}, J y\right)+\frac{1}{r_{\lambda}}\left\langle z_{n, \lambda}-x_{n}, J y-J z_{n, \lambda}\right\rangle \geq 0 \\
\\
y_{n, \lambda}=\alpha_{n} x_{n}+\left(1-\alpha_{n}\right) T z_{n, \lambda}, \quad \forall \lambda \in \Lambda, \\
C_{n+1}=\left\{z \in C_{n}: \sup _{\lambda \in \Lambda} \phi\left(y_{n, \lambda}, z\right) \leq \phi\left(x_{n}, z\right)\right\}, \\
x_{n+1}=R_{C_{n+1}} x
\end{array} \quad \forall y \in \lambda \in \Lambda,
\end{array}\right.
$$

for every $n \in \mathbb{N}$, where $J$ is the duality mapping on $E$, $\left\{\alpha_{n}\right\} \subset[0,1]$ such that $0 \leq \alpha_{n} \leq a<1$ and $\left\{r_{\lambda}\right\} \subset[0, \infty)$ such that $0<b \leq r_{\lambda}$ for some $a, b \in \mathbb{R}$. Then $\left\{x_{n}\right\}$ converges strongly to $R_{F(T) \cap F^{*}} x$, where $R_{F(T) \cap F^{*}}$ is the sunny generalized nonexpansive retraction from $E$ onto $F(T) \cap F^{*}$.

Proof. By the assumption, we have $F(T) \neq \emptyset$ and hence $T$ is a generalized nonexpansive mapping. From Theorem 2.3, we can use Theorem 3.1 to complete the proof.

## Acknowledgements

The author is indebted to the referee for comments and suggestions which lead to the improvement of this paper.

## References

[1] Ya. Alber, Metric and generalized projection operators in Banach spacesin Properties and applications, in Theory and Applications of Nonlinear Operators of Accretive and Monotone Type (A. G. Karsatos Ed.), Marcel Dekker, New York, 1996, pp. 15-50.
[2] K. Aoyama, Y. Kimura and W. Takahashi, Maximal monotone operators and maximal monotone functions for equilibrium problems, J. Convex Anal. 15 (2008), 395-409.
[3] E. Blum and W. Oettli, From optimization and variational inequilities to equilibrium problems, Math. Student 63 (1994), 123-145.
[4] I. Cioranescu, Geometry of Banach Spaces, Duality Mappings and Nonlinear Problems, Kluwer, Dordrecht, 1990.
[5] P. L. Combettes and S. A. Hirstoaga, Equilibrium programming in Hilbert spaces, J. Nonlinear Convex Anal. 6 (2005), 117-136.
[6] S. Dhompongsa, W. Inthakon and W. Takahashi, Strong and weak convergence theorems for equilibrium problems and generalized nonexpansive mappings in Banach spaces, in Fixed Point Theory and its Applications (L. J. Lin, A. Petruşel, and H. K. Xu, eds.), Yokohama Publishers, Yokohama, 2009, pp. 39-54.
[7] T. Ibaraki, Y. Kimura and W. Takahashi, Convergence theorems for generalized projection and maximal monotone operators in Banach spaces, Abst. Appl. Anal. 2003 (2003), 621629.
[8] T. Ibaraki and W. Takahashi, A new projection and convergence theorems for the projections in Banach spaces, J. Approx. Theory 149 (2007), 1-14.
[9] T. Ibaraki and W. Takahashi, Strong convergence theorems by two hybrid methods for equilibrium problems and feasibility problems in Banach spaces, in Fixed Point Theory and its Applications (L. J. Lin, A. Petruşel, and H. K. Xu, eds.), Yokohama Publishers, Yokohama, 2009, pp. 77-91.
[10] T. Ibaraki and W. Takahashi, Generalized nonexpansive mappings and a proximal- type algorithm in Banach spaces, Nonlinear Analysis and Optimization I: Nonlinear Analysis, Contemp. Math. 513, Amer. Math. Soc., Providence, RI, 2010, pp. 169-180.
[11] T. Ibaraki and Y. Kimura, Convergence of nonlinear projections and shrinking projection methods for common fixed point problems, J. Nonlinear Anal. Optim. 2 (2011), 225-238.
[12] W. Inthakon, S. Dhompongsa and W. Takahashi, Strong convergence theorems for maximal monotone operators and generalized nonexpansive mappings in Banach spaces, J. Nonlinear Convex Anal. 11 (2010), 45-63.
[13] S. Kamimura and W. Takahashi, Strong convergence of proximal - type algorithm in a Banach space, SIAM J. Optim. 13 (2002) 938-945.
[14] Y. Kimura and W. Takahashi, On hybrid method for a family of relatively nonexpansive mappings in a Banach space, J. Math. Anal. Appl. 357 (2009), 356-363.
[15] F. Kohsaka and W. Takahashi, Generalized nonexpansive retractions and a proximal - type algorithm in Banach spaces, J. Nonlinear Convex Anal. 8 (2007), 197-209.
[16] U. Mosco, Convergence of convex sets and of solutions of variational inequalities, Adv. Math. 3 (1969), 510-585.
[17] A. Moudafi, Second-order differential proximal methods for equilibrium problems, J. Inequal. Pure Appl. Math. 4 (2003), art. 18.
[18] W. Takahashi, Nonlinear Functional Analysis, Yokohama Publishers, Yokohama, 2000.
[19] W. Takahashi, Y. Takeuchi, and R. Kubota, Strong convegence theorems by hybrid methods for families of nonexpansive mappings in Hilbert spaces. J. Math. Anal. Appl. 341 (2008), 276-286.
[20] W. Takahashi and J.-C. Yao, Nonlinear Operators of Monotone type and convergence theorems with equilibrium problems in Banach spaces, Taiwanese J. Math. 15 (2011), 787-818.
[21] W. Takahashi and K. Zembayashi, A strong convergence theorems for the equilibrium problem with a bifunction defined on the dual space of a Banach space, in Fixed Point Theory and its Applications (S. Dhompongsa, K. Goebel, W.A. Kirk, S. Plubtieng, B. Sim and S. Suantai, eds.), Yokohama Publishers, Yokohama, 2008, pp. 197-209.
[22] W. Takahashi and K. Zembayashi, A strong and weak convergence theorems for equilibrium problems and relatively nonexpansive mappings in Banach spaces, Nonlinear Anal. 70 (2009), 45-57.

Manuscript received March 3, 2013
revised November 11, 2013

## Warunun Inthakon

Department of Mathematics, Faculty of Science, Chiang Mai University, Chiang Mai 50200, Thailand,
Centre of Excellence in Mathematics, CHE, Si Ayutthaya RD., Bangkok 10400, Thailand
E-mail address: w_inthakon@hotmail.com


[^0]:    2010 Mathematics Subject Classification. Primary 47H05; Secondary 47J25.
    Key words and phrases. Generalized nonexpansive mapping, sunny generalized nonexpansive retraction, system of equilibrium problems, shrinking projection

    This research is supported by the Centre of Excellence in Mathematics, the Commission on Higher Education, Thailand.

