Journal of Nonlinear and Convex Analysis Volume 14, Number 2, 2013, 389–414



WELL-POSEDNESS OF GENERAL MIXED IMPLICIT QUASI-VARIATIONAL INEQUALITIES, INCLUSION PROBLEMS AND FIXED POINT PROBLEMS

MU-MING WONG

ABSTRACT. In this paper the concept of well-posedness to a general mixed implicit quasi-variational inequality is generalized and some characterizations of its well-posedness is given. It is proven that under appropriate conditions, the wellposedness of a general mixed implicit quasi-variational inequality is equivalent to the well-posedness of a corresponding inclusion problem. We also discuss the relations between the well-posedness of a general mixed implicit quasi-variational inequality and the well-posedness of a fixed point problem. Finally, we derive some conditions under which a general mixed implicit quasi-variational inequality is well-posed.

1. INTRODUCTION

The concept of well-posedness for a minimization problem was initially introduced by Tykhonov [31] and ever since has been widely studied, since the concept of well-posedness has been applied to other contexts: variational inequality problems [7, 10, 18-21], saddle point problems [5], Nash equilibrium problems [20, 22-26, 28], inclusion problems [16, 17], and fixed point problems [16, 17, 32]. The concept of Tykhonov well-posedness in the generalized sense was introduced, which means the existence of minimizers and the convergence of some subsequence of every minimizing sequence toward a minimizer. It is clear that the concept of well-posedness is motivated by the numerical methods producing optimizing sequences. On account of its importance in optimization problems, various concepts of well-posedness have been introduced and studied for minimization problems in past decades; see, e.g., [2, 8, 14, 21, 27, 31, 37, 38].

Concerning the well-posedness of a given variational problem, it is very interesting and quite important to establish its metric characterization, to find conditions under which the problem is well-posed, and to investigate its links with the well-posedness of other related problems. Some metric characterizations of various well-posedness were established for minimization problems [8], variational inequalities [7,10,18,19] and Nash equilibrium problems [25]. For the well-posedness conditions of various variational problems, we refer the readers to [7, 8, 10, 18, 19, 26, 28]. The relations between the well-posedness of variational inequalities and the well-posedness of minimization problems were discussed in [7, 19, 21]. Lemaire [16] discussed the relations among the well-posedness of minimization problems, inclusion problems

²⁰¹⁰ Mathematics Subject Classification. 49J40, 49K40, 90C31.

Key words and phrases. General mixed implicit quasi-variational inequality, inclusion problem, fixed point problem, well-posedness.

This research was partially supported by a grant from NSC101-2115-M-033-001.

and fixed point problems. Recently, Lemaire et al [17] further extended the result in [16] by considering perturbations.

Very recently, motivated by the mentioned work as above, Fang, Huang and Yao [11] investigated the well-posedness of a mixed variational inequality which includes as a special case the classical variational inequality. They gave some metric characterizations of its well-posedness and establish the links with the wellposedness of inclusion problems and fixed point problems. Furthermore, they proved that under suitable conditions, the well-posedness of the mixed variational inequality is equivalent to the existence and uniqueness of its solutions, and the wellposedness in the generalized sense is equivalent to the existence of solutions.

In this paper, inspired by Fang, Huang and Yao [11], we generalize the concept of well-posedness to a general mixed implicit quasi-variational inequality which includes as a special case the mixed variational inequality. We derive some metric characterizations of its well-posedness and establish the links with the wellposedness of inclusion problems and fixed point problems. Finally we also prove that under appropriate conditions, the well-posedness of the general mixed implicit quasi-variational inequality is equivalent to the existence and uniqueness of its solutions, and the well-posedness in the generalized sense is equivalent to the existence of solutions. The results presented in this paper are the improvements and extension of the corresponding ones in Fang, Huang and Yao [11].

2. Preliminaries

Let *H* be a real Hilbert space with inner product $\langle \cdot, \cdot \rangle$ and norm $\|\cdot\|$. In order to show the main results, we need the follow concepts and results.

Definition 2.1. A mapping $g: H \to H$ is said to be

(i) monotone if

$$\langle g(x) - g(y), x - y \rangle \ge 0, \quad \forall x, y \in H;$$

(ii) δ -strongly monotone if there exists a constant $\delta > 0$ such that

$$\langle g(x) - g(y), x - y \rangle \ge \delta ||x - y||^2, \quad \forall x, y \in H;$$

(iii) σ -Lipschitz continuous if there exists a constant $\sigma > 0$ such that

$$||g(x) - g(y)|| \le \sigma ||x - y||, \quad \forall x, y \in H.$$

We remark that if mapping $g: H \to H$ is δ -strongly monotone and σ -Lipschitz continuous then g is a homeomorphism.

Let $\varphi : H \to \mathcal{R} \cup \{+\infty\}$ be a proper, convex and lower semicontinuous functional. Denote by dom φ the efficient domain of φ , i.e.,

$$\operatorname{dom}\varphi = \{ x \in H : \varphi(x) < +\infty \}.$$

Denote by $\partial \varphi$ and $\partial_{\epsilon} \varphi$ the subdifferential and ϵ -subdifferential of φ respectively, i.e.,

$$\partial \varphi(x) = \{ x^* \in H : \varphi(y) - \varphi(x) \ge \langle x^*, y - x \rangle, \forall y \in H \}, \quad \forall x \in \mathrm{dom}\varphi$$

and

$$\partial_{\epsilon}\varphi(x) = \{x^* \in H : \varphi(y) - \varphi(x) \ge \langle x^*, y - x \rangle - \epsilon, \forall y \in H\}, \quad \forall x \in \mathrm{dom}\varphi.$$

It is known that $\partial_{\epsilon}\varphi(x) \supset \partial\varphi(x) \neq \emptyset$ for all $x \in \operatorname{dom}\varphi$ and for all $\epsilon > 0$.

Now, let $F, g: H \to H$ be two mappings and $\phi: H \times H \to \mathcal{R} \cup \{+\infty\}$ be such that for each fixed $y \in H$, $\phi(\cdot, y): H \to H$ is a proper, convex and lower semicontinuous functional on H and $g(H) \cap \operatorname{dom}\partial\phi(\cdot, y) \neq \emptyset$. Consider the following general mixed implicit quasi-variational inequality associated with (F, g, ϕ) :

$$\operatorname{GMIQVI}(F,g,\phi): \qquad \left\{ \begin{array}{cc} \operatorname{Find} x \in H \text{ such that } g(x) \in \operatorname{dom}\partial\phi(\cdot,x) \text{ and} \\ \langle F(x), g(x) - y \rangle + \phi(g(x),x) - \phi(y,x) \leq 0, \quad \forall y \in H, \end{array} \right.$$

which has been studied intensively in Ding [6].

Some special cases.

(i) If $\phi(x, y) = \varphi(x)$ for all $x, y \in H$, the GMIQVI (F, g, ϕ) reduces to the following general mixed variational inequality associated with (F, g, φ) :

$$\mathrm{GMVI}(F,g,\varphi): \qquad \left\{ \begin{array}{cc} \mathrm{Find}\ x \in H \ \mathrm{such}\ \mathrm{that}\ g(x) \in \mathrm{dom}\partial\varphi \ \mathrm{and} \\ \langle F(x),g(x)-y\rangle + \varphi(g(x)) - \varphi(y) \leq 0, \quad \forall y \in H, \end{array} \right.$$

which was considered and studied by Hassouni and Moudafi [13].

(ii) If g = I the identity mapping of H, then the GMVI(F, g, φ) reduces to the following mixed variational inequality associated with (F, φ) :

$$MVI(F,\varphi): \qquad \text{Find } x \in H \text{ such that } \langle F(x), x - y \rangle + \varphi(x) - \varphi(y) \leq 0, \quad \forall y \in H,$$

which has been studied interviewly (see e.g. [2, 0, 11, 20, 25, 26])

which has been studied intensively (see, e.g., [3,9,11,29,35,36]).

(iii) If $K : H \to 2^H$ is a given multifunction such that each K(x) is a closed convex subset of H (or K(x) = m(x) + K where $m : H \to H$ and K is a closed convex subset of H) and if $\phi : H \times H \to \mathcal{R} \cup \{+\infty\}$ is defined by

$$\phi(x,y) = \delta_{K(y)}(x), \quad \forall x, y \in H,$$

where $\delta_{K(y)}(x)$ is the indicator function of K(y), i.e.,

$$\delta_{K(y)}(x) = \begin{cases} 0, \text{ if } x \in K(y), \\ +\infty, \text{ otherwise,} \end{cases}$$

then the GMIQVI(F, g, ϕ) reduces to the following strongly nonlinear quasi-variational inequality:

SNQVI
$$(F, g, K)$$
:

$$\begin{cases} \text{Find } x \in H \text{ such that } g(x) \in K(x) \text{ and} \\ \langle F(x), g(x) - y \rangle \leq 0, \quad \forall y \in K(x), \end{cases}$$

which includes a number of classes of variational inequalities, quasi-variational inequalities, complementarity and quasi-complementarity problems, studied previously by many authors, see, e.g., [6, 12, 30, 33, 34].

It is easy to see that $\partial_{\epsilon}\phi(x,y) \supset \partial\phi(x,y) \neq \emptyset$ for all $x \in \text{dom}\phi(\cdot,y)$ and for all $\epsilon > 0$. In terms of $\partial\phi(\cdot,y)$, GMIQVI (F,g,ϕ) is equivalent to the following inclusion problem associated with (F,g,ϕ) :

 $\operatorname{IP}(F, g, \phi)$: Find $x \in H$ such that $0 \in F(x) + \partial \phi(g(x), x)$.

For each fixed $y \in H$, the resolvent operator of $\partial \phi(\cdot, y)$ is defined by

$$J_{\lambda}^{\partial\phi(\cdot,y)}(x) = (I + \lambda \partial\phi(\cdot,y))^{-1}(x), \quad \forall x \in H,$$

which is well-defined, single-valued and nonexpansive, where $\lambda > 0$ is a constant. Recall that a mapping $T: H \to H$ is said to be nonexpansive if $||Tx - Ty|| \leq ||x - y||$ for all $x, y \in H$. In terms of $J_{\lambda}^{\partial\phi(\cdot,x)}$, GMIQVI (F, g, ϕ) is also equivalent to the following fixed point problem associated with (F, g, ϕ) :

$$\operatorname{FP}(F, g, \phi): \qquad \operatorname{Find} x \in H \text{ such that } x = x - g(x) + J_{\lambda}^{\partial \phi(\cdot, x)}(g(x) - \lambda F(x)).$$

Summarizing the above results, we have the following lemma:

Lemma 2.2. Let $F, g: H \to H$ be two mappings and $\phi: H \times H \to \mathcal{R} \cup \{+\infty\}$ be such that for each fixed $y \in H$, $\phi(\cdot, y)$ is a proper, convex and lower semicontinuous functional satisfying $g(H) \cap \operatorname{dom}\partial\phi(\cdot, y) \neq \emptyset$. Then the following conclusions are equivalent:

- (i) x solves $GMIQVI(F, g, \phi)$;
- (ii) x solves $IP(F, g, \phi)$;
- (iii) x solves $FP(F, g, \phi)$, where $\lambda > 0$ is a constant.

Proof. For the sake of completeness we give the proof of the lemma. Observe that for each $y \in H$,

$$x \text{ solves GMIQVI}(F, g, \phi) \Leftrightarrow \langle F(x), g(x) - y \rangle + \phi(g(x), x) - \phi(y, x) \le 0 \Leftrightarrow \phi(y, x) - \phi(g(x), x) \ge \langle -F(x), y - g(x) \rangle \Leftrightarrow -F(x) \in \partial \phi(g(x), x) \Leftrightarrow 0 \in F(x) + \partial \phi(g(x), x),$$

and for some $\lambda > 0$

$$0 \in F(x) + \partial \phi(g(x), x)$$

$$\Leftrightarrow g(x) - \lambda F(x) \in g(x) + \lambda \partial \phi(g(x), x)$$

$$\Leftrightarrow g(x) = (I + \lambda \partial \phi(\cdot, x))^{-1}(g(x) - \lambda F(x))$$

$$\Leftrightarrow x = x - g(x) + J_{\lambda}^{\partial \phi(\cdot, x)}(g(x) - \lambda F(x)).$$

Thus, conclusions (i)-(iii) are equivalent.

Definition 2.3. Let $F, g: H \to H$ be two mappings. F is said to be g-hemicontinuous if for any $x, y \in H$, the function $t \mapsto \langle F(x + t(y - x)), g(y) - g(x) \rangle$ from [0, 1] into \mathcal{R} is continuous at 0^+ .

Clearly, the continuity implies the hemicontinuity, but the converse is not true in general.

Definition 2.4. A mapping $F : H \to H$ is said to be uniformly continuous if for any neighborhood V of 0, there exists a neighborhood U of 0 such that $F(x) - F(y) \in V$ for all $x, y \in H$ with $x - y \in U$. Obviously, the uniform continuity implies the hemicontinuity.

Definition 2.5. Let $F, g : H \to H$ be two mappings.

(i) F is said to be g-monotone if

$$\langle F(x) - F(y), g(x) - g(y) \rangle \ge 0, \quad \forall x, y \in H.$$

At the same time, g is said to be F-monotone.

(ii) F is said to be g-convex if for each
$$\lambda \in [0, 1]$$
 and each $x, y \in H$,

$$\langle F(w_{\lambda}), g(w_{\lambda}) \rangle \le \lambda \langle F(w_{\lambda}), g(x) \rangle + (1-\lambda) \langle F(w_{\lambda}), g(y) \rangle$$

where $w_{\lambda} = \lambda x + (1 - \lambda)y$.

Lemma 2.6. Let $g: H \to H$ be a homeomorphism. Let $F: H \to H$ be g-monotone, g-convex and g-hemicontinuous. Let $\phi: H \times H \to \mathcal{R} \cup \{+\infty\}$ be such that for each fixed $y \in H$, $\phi(g(\cdot), y)$ is a proper, convex and lower semicontinuous functional, and $x \in H$ a given point. Then

$$\langle F(x), g(x) - y \rangle + \phi(g(x), x) - \phi(y, x) \le 0, \quad \forall y \in H$$

if and only if

$$\langle F(y), g(x) - y \rangle + \phi(g(x), x) - \phi(y, x) \le 0, \quad \forall y \in H.$$

Proof. Suppose

(2.1)
$$\langle F(x), g(x) - y \rangle + \phi(g(x), x) - \phi(y, x) \le 0, \quad \forall y \in H.$$

Since $g: H \to H$ is a homeomorphism, we know that inequality (2.1) is equivalent to the following inequality

$$\langle F(x), g(x) - g(y) \rangle + \phi(g(x), x) - \phi(g(y), x) \le 0, \quad \forall y \in H.$$

Since F is g-monotone, we have

$$\langle F(y) - F(x), g(y) - g(x) \rangle \ge 0, \quad \forall y \in H$$

and hence

$$\begin{split} \langle F(y), g(y) - g(x) \rangle + \phi(g(y), x) - \phi(g(x), x) \\ \geq \langle F(x), g(y) - g(x) \rangle + \phi(g(y), x) - \phi(g(x), x) \ge 0, \end{split}$$

for all $y \in H$. Consequently,

$$\langle F(y), g(x) - g(y) \rangle + \phi(g(x), x) - \phi(g(y), x) \le 0, \quad \forall y \in H.$$

Utilizing again the condition that $g:H\to H$ is a homeomorphism, we deduce that

(2.2)
$$\langle F(y), g(x) - y \rangle + \phi(g(x), x) - \phi(y, x) \le 0, \quad \forall y \in H.$$

Conversely, suppose inequality (2.2) is valid. Since $g: H \to H$ is a homeomorphism, we deduce that inequality (2.2) is equivalent to the following inequality

$$\langle F(y), g(y) - g(x) \rangle + \phi(g(y), x) - \phi(g(x), x) \ge 0, \quad \forall y \in H.$$

For any given $y \in H$ we define $y_t = ty + (1-t)x$ for all $t \in (0, 1)$. Replacing y by y_t in the left-hand side of the last inequality, and utilizing the convexity of $\phi(g(\cdot), x)$ and the g-convexity of F, we derive for each $t \in (0, 1)$,

$$\begin{array}{ll} 0 &\leq \langle F(y_t), g(y_t) - g(x) \rangle + \phi(g(y_t), x) - \phi(g(x), x) \\ &= \langle F(y_t), g(y_t) \rangle - \langle F(y_t), g(x) \rangle + \phi(g(y_t), x) - \phi(g(x), x) \\ &\leq t \langle F(y_t), g(y) \rangle + (1 - t) \langle F(y_t), g(x) \rangle - \langle F(y_t), g(x) \rangle \\ &\quad + t \phi(g(y), x) + (1 - t) \phi(g(x), x) - \phi(g(x), x) \\ &= t [\langle F(y_t), g(y) - g(x) \rangle + \phi(g(y), x) - \phi(g(x), x)], \end{array}$$

which hence implies that

(2.3)
$$\langle F(y_t), g(x) - g(y) \rangle + \phi(g(x), x) - \phi(g(y), x) \le 0, \quad \forall t \in (0, 1).$$

Since F is g-hemicontinuous, we conclude from (2.3) that as $t \to 0^+$,

$$\langle F(x), g(x) - g(y) \rangle + \phi(g(x), x) - \phi(g(y), x) \le 0.$$

Since $g: H \to H$ is a homeomorphism, from the arbitrariness of y we obtain

$$\langle F(x), g(x) - y \rangle + \phi(g(x), x) - \phi(y, x) \le 0, \quad \forall y \in H$$

This completes the proof.

Definition 2.7 (See [15]). Let A be a nonempty subset of H. The measure of

$$\mu(A) = \inf\{\epsilon > 0 : A \subset \bigcup_{i=1}^{n} A_i, \text{ diam} A_i < \epsilon, \ i = 1, 2, ..., n\},\$$

where diam means the diameter of a set.

noncompactness μ of the set A is defined by

Definition 2.8. Let A, B be nonempty subsets of H. The Hausdorff metric $\mathcal{H}(\cdot, \cdot)$ between A and B is defined by

$$\mathcal{H}(A,B) = \max\{e(A,B), e(B,A)\},\$$

where $e(A, B) = \sup_{a \in A} d(a, B)$ with $d(a, B) = \inf_{b \in B} ||a - b||$. Let $\{A_n\}$ be a sequence of nonempty subsets of H. We say that A_n converges to A in the sense of Hausdorff metric if $\mathcal{H}(A_n, A) \to 0$. It is easy to see that $e(A_n, A) \to 0$ if and only if $d(a_n, A) \to 0$ for all section $a_n \in A_n$. For more details on this topic, we refer the readers to [1, 15].

3. Well-posedness and metric characterization

In this section we introduce some concepts of well-posedness of the general mixed implicit quasi-variational inequality and establish their metric characterizations. Let $\alpha \geq 0$ be a given number and let H, F, g, ϕ be defined as in the previous section.

Definition 3.1. Let $g : H \to H$ be a homeomorphism. A sequence $\{x_n\} \subset H$ is said to be an α -approximating sequence for $\text{GMIQVI}(F, g, \phi)$ if there exists a sequence $\{\epsilon_n\}$ of nonnegative numbers with $\epsilon_n \to 0$ such that

$$g(x_n) \in \operatorname{dom}\phi(\cdot, x_n),$$
$$\langle F(x_n), g(x_n) - y \rangle + \phi(g(x_n), x_n) - \phi(y, x_n) \le \frac{\alpha}{2} \|x_n - g^{-1}(y)\|^2 + \epsilon_n, \forall y \in H$$

for all $n \in N$. If $\alpha_1 > \alpha_2 \ge 0$, then every α_2 -approximating sequence is α_1 approximating. When $\alpha = 0$, we say that $\{x_n\}$ is approximating for GMIQVI (F, g, ϕ) .

Definition 3.2. We say that $\text{GMIQVI}(F, g, \phi)$ is strongly (resp. weakly) α -well-posed if $\text{GMIQVI}(F, g, \phi)$ has a unique solution and every α -approximating sequence converges strongly (resp. weakly) to the unique solution. In the sequel, strong (resp. weak) 0-well-posedness is always called as strong (resp. weak) well-posedness. If $\alpha_1 > \alpha_2 \geq 0$, then strong (resp. weak) α_1 -well-posedness implies strong (resp. weak) α_2 -well-posedness.

Remark 3.3. When $\phi(x, y) = \delta_K(x)$ and g = I where K is a closed convex subset of H, Definition 3.2 reduces to the definition of strong (resp. weak) α -well-posedness for the classical variational inequality. For details, we refer the readers to [7,19,20] and the references therein.

Definition 3.4. We say that $\text{GMIQVI}(F, g, \phi)$ is strongly (resp. weakly) α -wellposed in the generalized sense if $\text{GMIQVI}(F, g, \phi)$ has a nonempty solution set Sand every α -approximating sequence has a subsequence which converges strongly (resp. weakly) to some point of S. When $\alpha = 0$, we say that $\text{GMIQVI}(F, g, \phi)$ is strongly (resp. weakly) well-posed in the generalized sense. Clearly, if $\alpha_1 > \alpha_2 \ge 0$, then strong (resp. weak) α_1 -well-posedness in the generalized sense implies strong (resp. weak) α_2 -well-posedness in the generalized sense.

Remark 3.5. When $\phi(x, y) = \delta_K(x)$ and g = I where K is a closed convex subset of H, Definition 3.4 reduces to the definition of strong (resp. weak) α -well-posedness in the generalized sense for the classical variational inequality. For details, we refer the readers to [7, 19, 20] and the references therein.

Let $g : H \to H$ be a homeomorphism. The α -approximating solution set of $\text{GMIQVI}(F, g, \phi)$ is defined by

$$\Omega_{\alpha}(\epsilon) = \{ x \in H : \langle F(x), g(x) - y \rangle + \phi(g(x), x) - \phi(y, x) \\ \leq \frac{\alpha}{2} \| x - g^{-1}(y) \|^2 + \epsilon, \ \forall y \in H \}, \ \forall \epsilon \ge 0.$$

Now we give a metric characterization of strong α -well-posedness for GMIQVI (F, g, ϕ) .

Theorem 3.6. Let $g : H \to H$ be a homeomorphism. Let $F : H \to H$ be gmonotone, g-convex and g-hemicontinuous. Assume that for each fixed $y \in H$ there hold the following conditions for a proper functional $\phi : H \times H \to \mathcal{R} \cup \{+\infty\}$:

(i) $x \mapsto \phi(g(x), y)$ is convex;

(ii) $x \mapsto \phi(g(x), x) - \phi(g(y), x)$ is lower semicontinuous.

Then $\text{GMIQVI}(F, g, \phi)$ is strongly α -well-posed if and only if

(3.1)
$$\Omega_{\alpha}(\epsilon) \neq \emptyset, \quad \forall \epsilon > 0 \quad \text{and} \quad \operatorname{diam}\Omega_{\alpha}(\epsilon) \to 0 \text{ as } \epsilon \to 0.$$

Proof. Suppose that GMIQVI (F, g, ϕ) is strongly α -well-posed. Then GMIQVI (F, g, ϕ) has a unique solution which lies in $\Omega_{\alpha}(\epsilon)$ for all $\epsilon > 0$. If diam $\Omega_{\alpha}(\epsilon) \neq 0$ as $\epsilon \to 0$, then there exist constant l > 0 and sequences $\{\epsilon_n\} \subset \mathcal{R}_+$ with $\epsilon_n \to 0$, and $\{u_n\}, \{v_n\}$ with $u_n, v_n \in \Omega_{\alpha}(\epsilon_n)$ such that

$$||u_n - v_n|| > l, \quad \forall n \in N.$$

Since $u_n, v_n \in \Omega_{\alpha}(\epsilon_n)$, both $\{u_n\}$ and $\{v_n\}$ are α -approximating sequences for $\text{GMIQVI}(F, g, \phi)$. So they have to converge strongly to the unique solution of $\text{GMIQVI}(F, g, \phi)$, a contraction to (3.2).

Conversely, suppose that condition (3.1) holds. Let $\{x_n\} \subset H$ be an α approximating sequence for GMIQVI (F, g, ϕ) . Then there exists a sequence $\{\epsilon_n\} \subset \mathcal{R}_+$ with $\epsilon_n \to 0$ such that

$$g(x_n) \in \operatorname{dom}\phi(\cdot, x_n),$$
$$\langle F(x_n), g(x_n) - y \rangle + \phi(g(x_n), x_n) - \phi(y, x_n) \le \frac{\alpha}{2} \|x_n - g^{-1}(y)\|^2 + \epsilon_n, \forall y \in H$$

for all $n \in N$. This implies that $x_n \in \Omega_{\alpha}(\epsilon_n)$. From (3.1), we know that $\{x_n\}$ is a Cauchy sequence and so it converges strongly to a point $\bar{x} \in H$. Note that

 $g: H \to H$ is a homeomorphism. Hence the last inequality is equivalent to the following inequality

(3.3)
$$\langle F(x_n), g(x_n) - g(y) \rangle + \phi(g(x_n), x_n) - \phi(g(y), x_n) \le \frac{\alpha}{2} ||x_n - y||^2 + \epsilon_n, \ \forall y \in H.$$

Since F is g-monotone and functional $x \mapsto \phi(g(x), x) - \phi(g(y), x)$ is lower semicontinuous for each fixed $y \in H$, it follows from (3.3) that

$$\langle F(y), g(\bar{x}) - g(y) \rangle + \phi(g(\bar{x}), \bar{x}) - \phi(g(y), \bar{x})$$

$$\leq \liminf_{n \to \infty} \{ \langle F(y), g(x_n) - g(y) \rangle + \phi(g(x_n), x_n) - \phi(g(y), x_n) \}$$

$$\leq \liminf_{n \to \infty} \{ \langle F(x_n), g(x_n) - g(y) \rangle + \phi(g(x_n), x_n) - \phi(g(y), x_n) \}$$

$$\leq \liminf_{n \to \infty} \{ \frac{\alpha}{2} ||x_n - y||^2 + \epsilon_n \}$$

$$= \frac{\alpha}{2} ||\bar{x} - y||^2, \quad \forall y \in H.$$

For any $y \in H$, put $y_t = (1 - t)\overline{x} + ty$, $\forall t \in (0, 1)$. Then

$$\langle F(y_t), g(\bar{x}) - g(y_t) \rangle + \phi(g(\bar{x}), \bar{x}) - \phi(g(y_t), \bar{x}) \le \frac{\alpha}{2} \|\bar{x} - y_t\|^2, \quad \forall t \in (0, 1).$$

Since F is g-convex and $\phi(g(\cdot), \bar{x})$ is convex, we have

$$\langle F(y_t), g(\bar{x}) - g(y) \rangle + \phi(g(\bar{x}), \bar{x}) - \phi(g(y), \bar{x}) \le \frac{t\alpha}{2} \|\bar{x} - y\|^2, \quad \forall t \in (0, 1).$$

Letting $t \to 0^+$ in the last inequality, from the g-hemicontinuity of F we get

$$\langle F(\bar{x}), g(\bar{x}) - g(y) \rangle + \phi(g(\bar{x}), \bar{x}) - \phi(g(y), \bar{x}) \le 0$$

for each $y \in H$. Since $g: H \to H$ is a homeomorphism, we have

$$\langle F(\bar{x}), g(\bar{x}) - y \rangle + \phi(g(\bar{x}), \bar{x}) - \phi(y, \bar{x}) \le 0, \quad \forall y \in H.$$

This shows that \bar{x} solves $\text{GMIQVI}(F, g, \phi)$.

To complete the proof, we need only to prove that $\text{GMIQVI}(F, g, \phi)$ has a unique solution. Assume by contradiction that $\text{GMIQVI}(F, g, \phi)$ has two distinct solutions x_1 and x_2 . Then it is easy to see that $x_1, x_2 \in \Omega_{\alpha}(\epsilon)$ for all $\epsilon > 0$ and

$$0 < ||x_1 - x_2|| \le \operatorname{diam}\Omega_{\alpha}(\epsilon) \to 0 \text{ as } \epsilon \to 0,$$

a contradiction to (3.1). This completes the proof.

Remark 3.7. Theorem 3.6 generalizes Theorem 3.1 of [11], and hence Proposition 2.2 of [7].

In terms of noncompact measure, we have the following analogous metric characterization of strong α -well-posedness in the generalized sense.

Theorem 3.8. Let $g : H \to H$ be a homeomorphism and $F : H \to H$ be such that the functional $x \mapsto \langle F(x), g(x) - g(y) \rangle$ is lower semicontinuous for each fixed $y \in H$. Let $\phi : H \times H \to \mathcal{R} \cup \{+\infty\}$ be a proper functional such that $x \mapsto \phi(g(x), x) - \phi(g(y), x)$ is lower semicontinuous for each fixed $y \in H$. Then GMIQVI (F, g, ϕ) is strongly α -well-posed in the generalized sense if and only if

(3.4)
$$\Omega_{\alpha}(\epsilon) \neq \emptyset, \quad \forall \epsilon > 0 \quad \text{and} \quad \mu(\Omega_{\alpha}(\epsilon)) \to 0 \text{ as } \epsilon \to 0.$$

Proof. Suppose that $\operatorname{GMIQVI}(F, g, \phi)$ is strongly α -well-posed in the generalized sense. Let S be the solution set of $\operatorname{GMIQVI}(F, g, \phi)$. Then S is nonempty and compact. Indeed, let $\{x_n\}$ be any sequence in S. Then $\{x_n\}$ is α -approximating for $\operatorname{GMIQVI}(F, g, \phi)$. Since $\operatorname{GMIQVI}(F, g, \phi)$ is strongly α -well-posed in the generalized sense, $\{x_n\}$ has a subsequence which converges strongly to some point of S. Thus S is compact. Clearly, $\Omega_{\alpha}(\epsilon) \supset S \neq \emptyset$ for all $\epsilon > 0$. Now let us show that

$$\mu(\Omega_{\alpha}(\epsilon)) \to 0 \text{ as } \epsilon \to 0.$$

Observe that for every $\epsilon > 0$,

$$\mathcal{H}(\Omega_{\alpha}(\epsilon), S) = \max\{e(\Omega_{\alpha}(\epsilon), S), e(S, \Omega_{\alpha}(\epsilon))\} = e(\Omega_{\alpha}(\epsilon), S).$$

Taking into account the compactness of S, we get

Taking into account the compactness of S, we get $\mu(\Omega_{\alpha}(\epsilon)) \leq 2\mathcal{H}(\Omega_{\alpha}(\epsilon), S) = 2e(\Omega_{\alpha}(\epsilon), S).$ To prove (3.4), it is sufficient to show that

$$e(\Omega_{\alpha}(\epsilon), S) \to 0 \text{ as } \epsilon \to 0.$$

If $e(\Omega_{\alpha}(\epsilon), S) \not\to 0$ as $\epsilon \to 0$, then there exist l > 0 and $\{\epsilon_n\} \subset \mathcal{R}_+$ with $\epsilon_n \to 0$, and $x_n \in \Omega_{\alpha}(\epsilon_n)$ such that

(3.5)
$$x_n \notin S + B(0,l), \quad \forall n \in N,$$

where B(0, l) is the closed ball centered at 0 with radius l. Because of $x_n \in \Omega_{\alpha}(\epsilon_n)$, $\{x_n\}$ is an α -approximating sequence for $\text{GMIQVI}(F, g, \phi)$. Since $\text{GMIQVI}(F, g, \phi)$ is strongly α -well-posed in the generalized sense, there exists a subsequence $\{x_{n_k}\}$ of $\{x_n\}$ converging strongly to some point of S. This contradicts to (3.5) and so

$$e(\Omega_{\alpha}(\epsilon), S) \to 0 \text{ as } \epsilon \to 0.$$

Conversely, assume that (3.4) holds. First, let us show that $\Omega_{\alpha}(\epsilon)$ is closed for all $\epsilon > 0$. Let $\{x_n\} \subset \Omega_{\alpha}(\epsilon)$ with $x_n \to x$. Then

$$\langle F(x_n), g(x_n) - y \rangle + \phi(g(x_n), x_n) - \phi(y, x_n) \le \frac{\alpha}{2} ||x_n - g^{-1}(y)||^2 + \epsilon, \quad \forall y \in H.$$

Since $g: H \to H$ is a homeomorphism, the last inequality is equivalent to the following one

$$\langle F(x_n), g(x_n) - g(y) \rangle + \phi(g(x_n), x_n) - \phi(g(y), x_n) \le \frac{\alpha}{2} ||x_n - y||^2 + \epsilon, \quad \forall y \in H.$$

Since $z \mapsto \langle F(z), g(z) - g(y) \rangle$ and $z \mapsto \phi(g(z), z) - \phi(g(y), z)$ are lower semicontinuous for each fixed $y \in H$, we deduce that

$$\langle F(x), g(x) - g(y) \rangle + \phi(g(x), x) - \phi(g(y), x) \le \frac{\alpha}{2} ||x - y||^2 + \epsilon, \quad \forall y \in H.$$

Since $g: H \to H$ is a homeomorphism, the last inequality is equivalent to the following one

$$\langle F(x), g(x) - y \rangle + \phi(g(x), x) - \phi(y, x) \le \frac{\alpha}{2} \|x - g^{-1}(y)\|^2 + \epsilon, \quad \forall y \in H.$$

This shows that $x \in \Omega_{\alpha}(\epsilon)$ and so $\Omega_{\alpha}(\epsilon)$ is nonempty closed for all $\epsilon > 0$. Observe that

$$S = \bigcap_{\epsilon > 0} \Omega_{\alpha}(\epsilon).$$

Since $\mu(\Omega_{\alpha}(\epsilon)) \to 0$, the Theorem on page 412 of [15] can be applied and one concludes that S is nonempty and compact with

$$e(\Omega_{\alpha}(\epsilon), S) = \mathcal{H}(\Omega_{\alpha}(\epsilon), S) \to 0 \text{ as } \epsilon \to 0.$$

Let $\{u_n\} \subset H$ be an α -approximating sequence for $\text{GMIQVI}(F, g, \phi)$. Then there exists $\epsilon_n > 0$ with $\epsilon_n \to 0$ such that

$$g(u_n) \in \operatorname{dom}\phi(\cdot, u_n),$$
$$\langle F(u_n), g(u_n) - y \rangle + \phi(g(u_n), u_n) - \phi(y, u_n) \le \frac{\alpha}{2} ||u_n - g^{-1}(y)||^2 + \epsilon_n, \ \forall y \in H$$

for all $n \in N$. So $u_n \in \Omega_{\alpha}(\epsilon_n)$ follows from definition. It follows from (3.4) that

$$d(u_n, S) \le e(\Omega_\alpha(\epsilon_n), S) \to 0.$$

Since S is compact, there exists $\bar{x}_n \in S$ such that

$$\|u_n - \bar{x}_n\| = d(u_n, S) \to 0.$$

Again from the compactness of S, $\{\bar{x}_n\}$ has a subsequence $\{\bar{x}_{n_k}\}$ converging strongly to $\bar{x} \in S$. Hence the corresponding subsequence $\{u_{n_k}\}$ of $\{u_n\}$ converges strongly to \bar{x} . Thus GMIQVI (F, g, ϕ) is strongly α -well-posed in the generalized sense. \Box

Now we give the following example as an application of Theorem 3.6.

Example 3.9. Let *H* be the 2-dimensional Euclidean space \mathcal{R}^2 . As usual, its inner product and norm are defined as

$$\langle x, y \rangle = x_1 y_1 + x_2 y_2$$
 and $||x|| = \sqrt{x_1^2 + x_2^2}, \quad \forall x, y \in H$

where $x = (x_1, x_2)$ and $y = (y_1, y_2)$. Define mappings $F, g : H \to H$ and functional $\phi : H \times H \to \mathcal{R} \cup \{+\infty\}$ as follows

$$F(x) = g(x) = (x_1 - x_2, x_1 + x_2)$$
 and $\phi(x, y) = ||x||^2 + ||y||^2$, $\forall x, y \in H$

where $x = (x_1, x_2)$ and $y = (y_1, y_2)$. Clearly, g is a homeomorphism, F is gmonotone, g-convex and g-hemicontinuous, and ϕ is a proper functional such that for each fixed $y \in H$ the following conditions are satisfied:

(i) $\phi(g(x), y) = 2||x||^2 + ||y||^2$ is convex in the variable x;

(ii) $\phi(g(x), x) - \phi(g(y), x) = 2(||x||^2 - ||y||^2)$ is lower semicontinuous in the variable x.

Let $\alpha = 4$. Then $\Omega_4(\epsilon)$

$$\begin{split} &= \{x \in H : \langle F(x), g(x) - y \rangle + \phi(g(x), x) - \phi(y, x) \leq \frac{\alpha}{2} \|x - g^{-1}(y)\|^2 + \epsilon, \forall y \in H\} \\ &= \{x \in H : \langle F(x), g(x) - g(y) \rangle + \phi(g(x), x) - \phi(g(y), x) \leq \frac{\alpha}{2} \|x - y\|^2 + \epsilon, \forall y \in H\} \\ &= \{x \in H : 2\langle x, x - y \rangle + 2(\|x\|^2 - \|y\|^2) \leq 2\|x - y\|^2 + \epsilon, \forall y \in H\} \\ &= \{x \in H : \langle x, x - y \rangle + \|x\|^2 - \|y\|^2 - \|x - y\|^2 - \frac{\epsilon}{2} \leq 0, \forall y \in H\} \\ &= \{x \in H : -2\|y - \frac{x}{4}\|^2 + \frac{9\|x\|^2}{8} - \frac{\epsilon}{2} \leq 0, \forall y \in H\} \\ &= \{x \in H : \|x\| \leq \frac{2\sqrt{\epsilon}}{3}\}. \end{split}$$

By Theorem 3.6, GMIQVI(F, g, ϕ) is 4-well-posed since diam $\Omega_4(\epsilon) = \frac{4\sqrt{\epsilon}}{3} \to 0$ as $\epsilon \to 0$.

4. LINKS WITH WELL-POSEDNESS OF INCLUSION PROBLEMS

In this section we shall investigate the relations between the well-posedness of general mixed implicit quasi-variational inequalities and the well-posedness of inclusion problems. In what follows we always denote by \rightarrow and \rightarrow the strong convergence and weak convergence, respectively. Let $A: H \rightarrow 2^H$ be a set-valued mapping. The inclusion problem associated with A is defined by

IP(A): Find $x \in H$ such that $0 \in A(x)$.

Definition 4.1 ([16, 17]). A sequence $\{x_n\} \subset H$ is called an approximating sequence for IP(A) if $d(0, A(x_n)) \to 0$, or equivalently, there exists $y_n \in A(x_n)$ such that $||y_n|| \to 0$ as $n \to \infty$.

Definition 4.2 ([16,17]). We say that IP(A) is strongly (resp. weakly) well-posed if it has a unique solution and every approximating sequence converges strongly (resp. weakly) to the unique solution of IP(A). IP(A) is said to be strongly (resp. weakly) well-posed in the generalized sense if the solution set S of IP(A) is nonempty and every approximating sequence has a subsequence which converges strongly (resp. weakly) to a point of S.

Definition 4.3. A proper functional $\phi : H \times H \to \mathcal{R} \cup \{+\infty\}$ is said to be diagonally convex if for each $(u_i, v_i) \in H \times H$, i = 1, 2 and each $\lambda \in [0, 1]$

$$\phi(\lambda u_1 + (1 - \lambda)u_2, \lambda v_1 + (1 - \lambda)v_2) \le \lambda \phi(u_1, v_1) + (1 - \lambda)\phi(u_2, v_2).$$

Remark 4.4. If a proper functional $\phi : H \times H \to \mathcal{R} \cup \{+\infty\}$ is diagonally convex, then for each fixed $(x, y) \in H \times H$ the functionals $u \mapsto \phi(u, y)$ and $v \mapsto \phi(x, v)$ are convex. Now we illustrate the concept of diagonal convexity. Take two fixed vectors $a, b \in H$. Define a proper functional $\phi : H \times H \to \mathcal{R} \cup \{+\infty\}$ as follows

$$\phi(x,y) = \|x\|^2 + \langle a, y - b \rangle, \quad \forall (x,y) \in H \times H.$$

Then it is easy to see that $\phi: H \times H \to \mathcal{R} \cup \{+\infty\}$ is diagonally convex. Meantime, it is clear that $\phi(y, \cdot)$ is affine for each fixed $y \in H$.

The following theorems establish the relations between the strong (resp. weak) well-posedness of general mixed implicit quasi-variational inequalities and the strong (resp. weak) well-posedness of inclusion problems.

Theorem 4.5. Let $g: H \to H$ be a homeomorphism which is affine and σ -Lipschitz continuous. Let $F: H \to H$ be g-monotone and g-hemicontinuous. Let $\phi: H \times H \to \mathcal{R} \cup \{+\infty\}$ be a proper and diagonally convex functional such that for each fixed $y \in H$ there hold the following conditions:

(i) $\phi(y, \cdot)$ is affine;

(ii) $\phi(\cdot, y)$ is a lower semicontinuous functional satisfying $g(H) \cap \text{dom}\partial\phi(\cdot, y) \neq \emptyset$; (iii) $x \mapsto \phi(g(x), x) - \phi(g(y), x)$ is weakly lower semicontinuous.

If $GMIQVI(F, g, \phi)$ is weakly well-posed, then $IP(F, g, \phi)$ is weakly well-posed.

Proof. Suppose that $\text{GMIQVI}(F, g, \phi)$ is weakly well-posed. Then $\text{GMIQVI}(F, g, \phi)$ has a unique solution x^* . By Lemma 2.2, x^* is also the unique solution of $\text{IP}(F, g, \phi)$. Let $\{x_n\}$ be an approximating sequence for $\text{IP}(F, g, \phi)$. Then there exists $y_n \in F(x_n) + \partial \phi(g(x_n), x_n)$ such that $||y_n|| \to 0$. It follows that

$$\phi(y, x_n) - \phi(g(x_n), x_n) \ge \langle y_n - F(x_n), y - g(x_n) \rangle, \quad \forall y \in H, n \in N.$$

Since $g: H \to H$ is a homeomorphism, the last inequality is equivalent to the following one

(4.1)
$$\phi(g(y), x_n) - \phi(g(x_n), x_n) \ge \langle y_n - F(x_n), g(y) - g(x_n) \rangle, \quad \forall y \in H, n \in N.$$

If $\{x_n\}$ is unbounded, without loss of generality, we may assume that $||x_n|| \to +\infty$. Let

$$t_n = \frac{1}{\|x_n - x^*\|}, \quad z_n = x^* + t_n(x_n - x^*).$$

Without loss of generality, we may assume that $t_n \in (0, 1]$ and $z_n \rightarrow z \neq x^*$. For any $y \in H$, it follows from the affinity of g that

Since F is g-monotone,

(4.3)
$$\langle F(y), g(x^*) - g(y) \rangle \leq \langle F(x^*), g(x^*) - g(y) \rangle$$

and $\langle F(y), g(x_n) - g(y) \rangle \leq \langle F(x_n), g(x_n) - g(y) \rangle.$

Furthermore, since x^* is the unique solution of $\text{GMIQVI}(F, g, \phi)$, we have

$$\langle F(x^*), g(x^*) - y \rangle + \phi(g(x^*), x^*) - \phi(y, x^*) \le 0, \quad \forall y \in H$$

which is equivalent to the following inequality

(4.4)
$$\langle F(x^*), g(x^*) - g(y) \rangle + \phi(g(x^*), x^*) - \phi(g(y), x^*) \le 0, \quad \forall y \in H.$$

Also, since ϕ is diagonally convex, and both $\phi(g(y), \cdot)$ and g are affine, it follows from (4.1)-(4.4) that

$$\begin{split} &\langle F(y), g(z) - g(y) \rangle \\ &\leq \langle F(y), g(z) - g(z_n) \rangle + t_n \phi(g(y), x_n) - t_n \phi(g(x_n), x_n) + t_n \langle y_n, g(x_n) - g(y) \rangle \\ &+ (1 - t_n) [\phi(g(y), x^*) - \phi(g(x^*), x^*)] \\ &= \langle F(y), g(z) - g(z_n) \rangle + t_n \phi(g(y), x_n) + (1 - t_n) \phi(g(y), x^*) \\ &- [t_n \phi(g(x_n), x_n) + (1 - t_n) \phi(g(x^*), x^*)] + \frac{\langle y_{n,g}(x_n) - g(y) \rangle}{\|x_n - x^*\|} \\ &\leq \langle F(y), g(z) - g(z_n) \rangle + \phi(g(y), z_n) - \phi(g(z_n), z_n) + \frac{\langle y_{n,g}(x_n) - g(y) \rangle}{\|x_n - x^*\|} \\ &\leq \langle F(y), g(z) - g(z_n) \rangle + \phi(g(y), z_n) - \phi(g(z_n), z_n) + \sigma \|y_n\| \frac{\|x_n - y\|}{\|x_n - x^*\|}. \end{split}$$

Note that $x \mapsto \phi(g(x), x) - \phi(g(y), x)$ is weakly lower semicontinuous. Utilizing the fact that every convex and lower semicontinuous functional has to be weakly lower semicontinuous, we deduce that

$$\langle F(y), g(z) - g(y) \rangle \leq \limsup_{n \to \infty} \{ \langle F(y), g(z) - g(z_n) \rangle + \phi(g(y), z_n) - \phi(g(z_n), z_n) + \sigma \|y_n\| \frac{\|x_n - y\|}{\|x_n - x^*\|} \} \leq \phi(g(y), z) - \phi(g(z), z),$$

which is equivalent to the following inequality

$$\langle F(y), g(z) - y \rangle + \phi(g(z), z) - \phi(y, z) \le 0, \quad \forall y \in H.$$

This together with Lemma 2.6 yields that z solves $\text{GMIQVI}(F, g, \phi)$, a contradiction. Thus, $\{x_n\}$ is bounded.

Let $\{x_{n_k}\}$ be any subsequence of $\{x_n\}$ such that $x_{n_k} \rightharpoonup \bar{x}$ as $k \rightarrow \infty$. It follows from (4.1) that

$$\langle F(x_{n_k}), g(x_{n_k}) - g(y) \rangle + \phi(g(x_{n_k}), x_{n_k}) - \phi(g(y), x_{n_k}) \le \langle y_{n_k}, g(x_{n_k}) - g(y) \rangle,$$

$$\forall y \in H, n \in N.$$

Since g is affine, F is g-monotone, $x \mapsto \phi(g(x), x) - \phi(g(y), x)$ is weakly lower semicontinuous, and $||y_n|| \to 0$, we have

$$\langle F(y), g(\bar{x}) - g(y) \rangle + \phi(g(\bar{x}), \bar{x}) - \phi(g(y), \bar{x})$$

$$\leq \liminf_{n \to \infty} \{ \langle F(y), g(x_{n_k}) - g(y) \rangle + \phi(g(x_{n_k}), x_{n_k}) - \phi(g(y), x_{n_k}) \}$$

$$\leq \liminf_{n \to \infty} \{ \langle F(x_{n_k}), g(x_{n_k}) - g(y) \rangle + \phi(g(x_{n_k}), x_{n_k}) - \phi(g(y), x_{n_k}) \}$$

$$\leq \liminf_{n \to \infty} \langle y_{n_k}, g(x_{n_k}) - g(y) \rangle$$

$$\leq \liminf_{n \to \infty} \sigma \| y_{n_k} \| \| x_{n_k} - y \| = 0, \quad \forall y \in H,$$

which is equivalent to the following inequality

$$\langle F(y), g(\bar{x}) - y \rangle + \phi(g(\bar{x}), \bar{x}) - \phi(y, \bar{x}) \le 0, \quad \forall y \in H.$$

This together with Lemma 2.6 yields that \bar{x} solves $\text{GMIQVI}(F, g, \phi)$. We have $\bar{x} = x^*$ since $\text{GMIQVI}(F, g, \phi)$ has a unique solution x^* . Therefore $\{x_n\}$ converges weakly to x^* and so $\text{IP}(F, g, \phi)$ is weakly well-posed.

Theorem 4.6. Let $g: H \to H$ be a homeomorphism whose inverse g^{-1} is uniformly continuous. Let $F: H \to H$ be uniformly continuous and g-monotone, and let $\phi: H \times H \to \mathcal{R} \cup \{+\infty\}$ be such that for each fixed $y \in H$, $\phi(\cdot, y)$ is a proper, convex and lower semicontinuous functional satisfying $g(H) \cap \operatorname{dom}\partial\phi(\cdot, y) \neq \emptyset$. Assume that for any bounded sequences $\{x_n\}, \{y_n\}$ in H there holds the following:

 $||x_n - y_n|| \to 0 \ (n \to \infty) \quad \Rightarrow \quad \partial \phi(g(y_n), x_n) \subset \partial \phi(g(y_n), y_n) \text{ for } n \text{ sufficiently large.}$

If $IP(F, g, \phi)$ is strongly (resp. weakly) well-posed, then $GMIQVI(F, g, \phi)$ is strongly (resp. weakly) well-posed.

Proof. Let $\{x_n\}$ be an approximating sequence for $\text{GMIQVI}(F, g, \phi)$. Then there exists $\epsilon_n > 0$ with $\epsilon_n \to 0$ such that

$$\phi(g(x_n), x_n) \le \phi(y, x_n) + \langle F(x_n), y - g(x_n) \rangle + \epsilon_n, \quad \forall y \in H, n \in N.$$

Define $\tilde{\phi}_n : H \to \mathcal{R} \cup \{+\infty\}$ as follows:

$$\phi_n(y) = \phi(y, x_n) + \langle F(x_n), y - g(x_n) \rangle, \quad \forall y \in H.$$

Clearly $\tilde{\phi}_n$ is proper, convex and lower semicontinuous and $0 \in \partial_{\epsilon_n} \tilde{\phi}_n(g(x_n))$ for all $n \in N$. By the Brøndsted-Rockafellar theorem [4], there exists $\bar{x}_n \in H$ and

$$x_n^* \in \partial \phi_n(g(\bar{x}_n)) = \partial \phi(g(\bar{x}_n), x_n) + F(x_n)$$

such that

$$||g(x_n) - g(\bar{x}_n)|| \le \sqrt{\epsilon_n}, \quad ||x_n^*|| \le \sqrt{\epsilon_n}.$$

It follows that

$$x_n^* + F(\bar{x}_n) - F(x_n) \in F(\bar{x}_n) + \partial \phi(g(\bar{x}_n), x_n) \subset F(\bar{x}_n) + \partial \phi(g(\bar{x}_n), \bar{x}_n)$$

for n sufficiently large. Since $g^{-1},F:H\to H$ are uniformly continuous, we deduce that

$$||x_n - \bar{x}_n|| = ||g^{-1}(g(x_n)) - g^{-1}(g(\bar{x}_n))|| \to 0$$

and hence

$$||x_n^* + F(\bar{x}_n) - F(x_n)|| \le ||x_n^*|| + ||F(\bar{x}_n) - F(x_n)|| \to 0.$$

So $\{\bar{x}_n\}$ is an approximating sequence for IP (F, g, ϕ) .

Let x^* be the unique solution of $\text{GMIQVI}(F, g, \phi)$. By Lemma 2.2, x^* is also the unique solution of $\text{IP}(F, g, \phi)$.

If IP (F, g, ϕ) is strongly well-posed, then $\bar{x}_n \to x^*$. It follows that

$$||x_n - x^*|| \le ||x_n - \bar{x}_n|| + ||\bar{x}_n - x^*|| \to 0$$

and so $\text{GMIQVI}(F, g, \phi)$ is strongly well-posed.

If IP (F, g, ϕ) is weakly well-posed, then $\bar{x}_n \rightharpoonup x^*$. For any $f \in H$, we have

$$|\langle f, x_n - x^* \rangle| \le |\langle f, x_n - \bar{x}_n \rangle| + |\langle f, \bar{x}_n - x^* \rangle| \le ||f|| ||x_n - \bar{x}_n|| + |\langle f, \bar{x}_n - x^* \rangle| \to 0.$$

Thus GMIQVI(F, g, ϕ) is weakly well-posed.

For the well-posedness in the generalized sense, we have the following analogous results.

Theorem 4.7. Let $g: H \to H$ be a homeomorphism which is σ -Lipschitz continuous, and $F: H \to H$ be g-hemicontinuous and g-monotone. Let $\phi: H \times H \to \mathcal{R} \cup \{+\infty\}$ be such that for each fixed $y \in H$, $\phi(\cdot, y)$ is a proper, convex and lower semicontinuous functional satisfying $g(H) \cap \operatorname{dom}\partial\phi(\cdot, y) \neq \emptyset$. If GMIQVI(F, g, ϕ) is strongly (resp. weakly) σ^2 -well-posed in the generalized sense, then IP(F, g, ϕ) is strongly (resp. weakly) well-posed in the generalized sense.

Proof. Let $\{x_n\}$ be an approximating sequence for $\operatorname{IP}(F, g, \phi)$. Then there exists $y_n \in F(x_n) + \partial \phi(g(x_n), x_n)$ such that $||y_n|| \to 0$. It follows that

$$\phi(y, x_n) - \phi(g(x_n), x_n) \ge \langle y_n - F(x_n), y - g(x_n) \rangle, \quad \forall y \in H, n \in N,$$

which is equivalent to the following inequality

$$\phi(g(y), x_n) - \phi(g(x_n), x_n) \ge \langle y_n - F(x_n), g(y) - g(x_n) \rangle, \quad \forall y \in H, n \in N.$$

Hence we have

$$\langle F(x_n), g(x_n) - g(y) \rangle + \phi(g(x_n), x_n) - \phi(g(y), x_n) \leq \langle y_n, g(x_n) - g(y) \rangle \leq \frac{1}{2} ||g(x_n) - g(y)||^2 + \frac{1}{2} ||y_n||^2 \leq \frac{\sigma^2}{2} ||x_n - y||^2 + \frac{1}{2} ||y_n||^2, \quad \forall y \in H, n \in N,$$

which is equivalent to the following inequality

$$\langle F(x_n), g(x_n) - y \rangle + \phi(g(x_n), x_n) - \phi(y, x_n) \le \frac{\sigma^2}{2} \|x_n - g^{-1}(y)\|^2 + \frac{1}{2} \|y_n\|^2,$$

$$\forall y \in H, n \in N.$$

This together with $||y_n|| \to 0$ implies that $\{x_n\}$ is σ^2 -approximating for GMIQVI (F, g, ϕ) . Since GMIQVI (F, g, ϕ) is strongly (resp. weakly) σ^2 -well-posed in the generalized sense, $\{x_n\}$ converges strongly (resp. weakly) to some solution x^* of GMIQVI (F, g, ϕ) . By Lemma 2.2, x^* is also a solution of IP (F, g, ϕ) . So IP (F, g, ϕ) is strongly (resp. weakly) well-posed in the generalized sense. \Box

Theorem 4.8. Let $g: H \to H$ be a homeomorphism whose inverse g^{-1} is uniformly continuous. Let $F: H \to H$ be uniformly continuous and g-monotone, and let $\phi: H \times H \to \mathcal{R} \cup \{+\infty\}$ be such that for each fixed $y \in H$, $\phi(\cdot, y)$ is a proper, convex and lower semicontinuous functional satisfying $g(H) \cap \operatorname{dom}\partial\phi(\cdot, y) \neq \emptyset$. Assume that for any bounded sequences $\{x_n\}, \{y_n\}$ in H there holds the following:

 $||x_n-y_n|| \to 0 \ (n \to \infty) \Rightarrow \partial \phi(g(y_n), x_n) \subset \partial \phi(g(y_n), y_n)$ for *n* sufficiently large. If IP(*F*, *g*, ϕ) is strongly (resp. weakly) well-posed in the generalized sense, then GMIQVI(*F*, *g*, ϕ) is strongly (resp. weakly) well-posed in the generalized sense.

Proof. The conclusion follows from the arguments similar to that of Theorem 4.6. \Box

5. Links with well-posedness of fixed point problems

In this section, we shall investigate the relations between the well-posedness of general mixed implicit quasi-variational inequalities and the well-posedness of fixed point problems. Let $T : H \to H$ be a single-valued mapping. The fixed-point problem associated with T is defined by

FP(T): Find $x \in H$ such that T(x) = x.

We first recall some concepts.

Definition 5.1 ([16, 17]). A sequence $\{x_n\} \subset H$ is called an approximating sequence for FP(T) if $||x_n - T(x_n)|| \to 0$ as $n \to \infty$.

Definition 5.2 ([16, 17]). We say that FP(T) is strongly (resp. weakly) wellposed if FP(T) has a unique solution and every approximating sequence for FP(T)converges strongly (resp. weakly) to the unique solution. FP(T) is said to be strongly (resp. weakly) well-posed in the generalized sense if FP(T) has a nonempty solution set S and every approximating sequence for FP(T) has a subsequence which converges strongly (resp. weakly) to some point of S.

Theorem 5.3. Let $g : H \to H$ be a homeomorphism which is affine and σ -Lipschitz continuous. Let $F : H \to H$ be Lipschitz continuous and g-monotone. Let $\phi : H \times H \to \mathcal{R} \cup \{+\infty\}$ be a proper and diagonally convex functional such that for each fixed $y \in H$ there hold the following conditions:

(i) $\phi(y, \cdot)$ is affine;

(ii) $\phi(\cdot, y)$ is a lower semicontinuous functional satisfying $g(H) \cap \operatorname{dom} \partial \phi(\cdot, y) \neq \emptyset$;

(iii) for any weak convergence sequence $\{z_n\} \subset H$ with $z_n \rightarrow z \in H$ and any sequence $\{e_n\} \subset H$ with $e_n \rightarrow 0$, there holds for each fixed $y \in H$

$$\liminf_{n \to \infty} [\phi(g(z_n) + e_n, z_n) - \phi(g(y), z_n)] \ge \phi(g(z), z) - \phi(g(y), z);$$

(iv) for any sequences $\{x_n\}, \{w_n\} \subset H$ with $||w_n|| \to +\infty$ and $||x_n - w_n|| \to 0$,

$$\limsup_{n \to \infty} \frac{\langle F(x_n), g(w_n) - g(x_n) + x_n - w_n \rangle}{\|w_n\|} \le 0.$$

If GMIQVI(F, g, ϕ) is weakly well-posed, then $FP(F, g, \phi)$ is weakly well-posed, where $\lambda > 0$ is a constant.

Remark 5.4. It is easy to see that condition (iv) of Theorem 5.3 holds if one of the following statements (a), (b) holds:

(a) g = I the identity mapping of H;

(b) $F: H \to H$ is Lipschitz continuous.

In addition, if g = I the identity mapping of H and $\phi(x, y) = \varphi(x)$ is a proper, convex and lower semicontinuous functional, then there is no doubt that condition (iii) in Theorem 5.3 holds.

Proof of Theorem 5.3. Suppose that $\text{GMIQVI}(F, g, \phi)$ is weakly well-posed. Let x^* be the unique solution of $\text{GMIQVI}(F, g, \phi)$. By Lemma ??, x^* is also the unique solution of $\text{FP}(F, g, \phi)$. Let $\{x_n\}$ be an approximating sequence for $\text{FP}(F, g, \phi)$. Then $||x_n - w_n|| \to 0$, where

$$w_n = x_n - g(x_n) + J_{\lambda}^{\partial \phi(\cdot, x_n)}(g(x_n) - \lambda F(x_n)).$$

By the definition of $J_{\lambda}^{\partial \phi(\cdot,x)}$,

$$\frac{x_n - w_n}{\lambda} - F(x_n) \in \partial \phi(w_n - x_n + g(x_n), x_n).$$

It follows that

(5.1)

$$\phi(y, x_n) - \phi(w_n - x_n + g(x_n), x_n) \ge \langle \frac{x_n - w_n}{\lambda} - F(x_n), y - (w_n - x_n + g(x_n)) \rangle,$$

$$\forall y \in H, n \in N,$$

which is equivalent to the following inequality

(5.2)

$$\phi(g(y), x_n) - \phi(w_n - x_n + g(x_n), x_n) \ge \langle \frac{x_n - w_n}{\lambda} - F(x_n), g(y) - (w_n - x_n + g(x_n)) \rangle$$

$$\forall y \in H, n \in N.$$

If $\{w_n\}$ is unbounded, without loss of generality, we may assume that $||w_n|| \to +\infty$. Let

$$t_n = \frac{1}{\|w_n - x^*\|}, \quad z_n = x^* + t_n(x_n - x^*).$$

Without loss of generality, we may assume that $t_n \in (0, 1)$ and $z_n \rightharpoonup z \neq x^*$. From the affinity of g it follows that

$$\langle F(y), g(z) - g(y) \rangle = \langle F(y), g(z) - g(z_n) \rangle + \langle F(y), g(z_n) - g(x^*) \rangle + \langle F(y), g(x^*) - g(y) \rangle (5.3) = \langle F(y), g(z) - g(z_n) \rangle + t_n \langle F(y), g(x_n) - g(y) \rangle + (1 - t_n) \langle F(y), g(x^*) - g(y) \rangle.$$

Since x^* is the unique solution of $\text{GMIQVI}(F, g, \phi)$, we have

$$\langle F(x^*), g(x^*) - y \rangle + \phi(g(x^*), x^*) - \phi(y, x^*) \le 0, \quad \forall y \in H, n \in N,$$

which is equivalent to the following inequality

(5.4)
$$\langle F(x^*), g(x^*) - g(y) \rangle + \phi(g(x^*), x^*) - \phi(g(y), x^*) \le 0, \quad \forall y \in H, n \in N.$$

Note that ϕ is diagonally convex and g and $\phi(g(y), \cdot)$ are affine. Hence it follows from (13)-(15) that for all $y \in H$ and $n \in N$,

$$\begin{split} &\langle F(y), g(z) - g(y) \rangle \\ &\leq \langle F(y), g(z) - g(z_n) \rangle + t_n \langle F(x_n), g(x_n) - g(y) \rangle + (1 - t_n) \langle F(x^*), g(x^*) - g(y) \rangle \\ &\leq \langle F(y), g(z) - g(z_n) \rangle + t_n [\phi(g(y), x_n) - \phi(w_n - x_n + g(x_n), x_n) \\ &+ \langle \frac{w_n - x_n}{\lambda}, g(y) - (w_n - x_n + g(x_n)) \rangle + \langle F(x_n), g(w_n) - g(x_n) + x_n - w_n \rangle] \\ &+ (1 - t_n) [\phi(g(y), x^*) - \phi(g(x^*), x^*)] \\ &= \langle F(y), g(z) - g(z_n) \rangle + t_n \phi(g(y), x_n) + (1 - t_n) \phi(g(y), x^*) \\ &- [t_n \phi(w_n - x_n + g(x_n), x_n) + (1 - t_n) \phi(g(x^*), x^*)] \\ &+ t_n [\langle \frac{w_n - x_n}{\lambda}, g(y) - (w_n - x_n + g(x_n)) \rangle + \langle F(x_n), g(w_n) - g(x_n) + x_n - w_n \rangle] \\ &\leq \langle F(y), g(z) - g(z_n) \rangle + \phi(g(y), z_n) - \phi(g(z_n) + t_n(w_n - x_n), z_n) \\ &+ t_n [\langle \frac{w_n - x_n}{\lambda}, g(y) - (w_n - x_n + g(x_n)) \rangle + \langle F(x_n), g(w_n) - g(x_n) + x_n - w_n \rangle]. \end{split}$$

Consequently, from conditions (i), (iii) and (iv) it follows that

$$\langle F(y), g(z) - g(y) \rangle$$

$$\leq \limsup_{n \to \infty} \{ \langle F(y), g(z) - g(z_n) \rangle + \phi(g(y), z_n) - \phi(g(z_n) + t_n(w_n - x_n), z_n)$$

$$+ t_n [\langle \frac{w_n - x_n}{\lambda}, g(y) - (w_n - x_n + g(x_n)) \rangle + \langle F(x_n), g(w_n) - g(x_n) + x_n - w_n \rangle] \}$$

$$\leq \phi(g(y), z) - \phi(g(z), z), \quad \forall y \in H.$$

This together with Lemma 2.6 implies that z solves $\text{GMIQVI}(F, g, \phi)$, a contradiction. Thus, $\{w_n\}$ is bounded.

Let $\{w_{n_k}\}$ be any subsequence of $\{w_n\}$ such that $w_{n_k} \rightharpoonup \bar{w}$ as $k \rightarrow \infty$. From (5.2) we have

$$\langle F(w_{n_k}), (w_{n_k} - x_{n_k} + g(x_{n_k})) - g(y) \rangle + \phi(w_{n_k} - x_{n_k} + g(x_{n_k}), x_{n_k}) - \phi(g(y), x_{n_k})$$

$$\leq \langle \frac{x_{n_k} - w_{n_k}}{\lambda}, (w_{n_k} - x_{n_k} + g(x_{n_k})) - g(y) \rangle$$

$$+ \langle F(w_{n_k}) - F(x_{n_k}), (w_{n_k} - x_{n_k} + g(x_{n_k})) - g(y) \rangle,$$

for all $y \in H$. Since F is g-monotone and uniformly continuous, from condition (iii) and the affinity of g we obtain

$$\begin{array}{l} \langle F(y), g(\bar{w}) - g(y) \rangle + \phi(g(\bar{w}), \bar{w}) - \phi(g(y), \bar{w}) \\ \leq \liminf_{n \to \infty} \{ \langle F(y), g(w_{n_k}) - g(y) \rangle + \phi(w_{n_k} - x_{n_k} + g(x_{n_k}), x_{n_k}) - \phi(g(y), x_{n_k}) \} \\ \leq \liminf_{n \to \infty} \{ \langle F(w_{n_k}), g(w_{n_k}) - g(y) \rangle + \langle F(w_{n_k}), g(x_{n_k}) - g(w_{n_k}) + w_{n_k} - x_{n_k} \rangle \\ + \phi(w_{n_k} - x_{n_k} + g(x_{n_k}), x_{n_k}) - \phi(g(y), x_{n_k}) \} \\ \leq \liminf_{n \to \infty} \{ \langle \frac{x_{n_k} - w_{n_k}}{\lambda}, (w_{n_k} - x_{n_k} + g(x_{n_k})) - g(y) \rangle \\ + \langle F(w_{n_k}) - F(x_{n_k}), (w_{n_k} - x_{n_k} + g(x_{n_k})) - g(y) \rangle \} \\ = 0, \quad \forall y \in H. \end{array}$$

This together with Lemma 2.6 yields that \overline{w} solves $\text{GMIQVI}(F, g, \phi)$. We have $w_n \rightharpoonup x^*$ since $\text{GMIQVI}(F, g, \phi)$ has a unique solution x^* . For any $f \in H$, it follows that

$$\begin{aligned} |\langle f, x_n - x^* \rangle| &\leq |\langle f, x_n - w_n \rangle| + |\langle f, w_n - x^* \rangle| \\ &\leq ||f|| ||x_n - w_n|| + |\langle f, w_n - x^* \rangle| \to 0. \end{aligned}$$

Therefore, $x \rightharpoonup x^*$ and so $FP(F, g, \phi)$ is weakly well-posed.

Theorem 5.5. Let $g: H \to H$ be a homeomorphism whose inverse g^{-1} is uniformly continuous. Let $F: H \to H$ be uniformly continuous and g-monotone, and let $\phi: H \times H \to \mathcal{R} \cup \{+\infty\}$ be such that for each fixed $y \in H$, $\phi(\cdot, y)$ is a proper, convex and lower semicontinuous functional satisfying $g(H) \cap \operatorname{dom}\partial\phi(\cdot, y) \neq \emptyset$. Assume that for any bounded sequences $\{x_n\}, \{y_n\}$ in H there holds the following:

 $\|x_n - y_n\| \to 0 \ (n \to \infty) \quad \Rightarrow \quad \partial \phi(g(y_n), x_n) \subset \partial \phi(g(y_n), y_n) \text{ for } n \text{ sufficiently large.}$

If $FP(F, g, \phi)$ is strongly (resp. weakly) well-posed, then $GMIQVI(F, g, \phi)$ is strongly (resp. weakly) well-posed.

Proof. Let $\{x_n\}$ be an approximating sequence for $\text{GMIQVI}(F, g, \phi)$. Then there exists $\epsilon_n > 0$ with $\epsilon_n \to 0$ such that

$$\phi(g(x_n), x_n) \le \phi(y, x_n) + \langle F(x_n), y - g(x_n) \rangle + \epsilon_n, \quad \forall y \in H, n \in N.$$

Define $\tilde{\phi}_n : H \to \mathcal{R} \cup \{+\infty\}$ as follows:

$$\tilde{\phi}_n(y) = \phi(y, x_n) + \langle F(x_n), y - g(x_n) \rangle, \quad \forall y \in H.$$

Clearly $\tilde{\phi}_n$ is proper, convex and lower semicontinuous and $0 \in \partial_{\epsilon_n} \tilde{\phi}_n(g(x_n))$ for all $n \in N$. By the Brøndsted-Rockafellar theorem [4], there exists $\bar{x}_n \in H$ and

(5.5)
$$x_n^* \in \partial \tilde{\phi}_n(g(\bar{x}_n)) = \partial \phi(g(\bar{x}_n), x_n) + F(x_n)$$

such that

(5.6)
$$\|g(x_n) - g(\bar{x}_n)\| \le \sqrt{\epsilon_n}, \quad \|x_n^*\| \le \sqrt{\epsilon_n}.$$

It follows that

$$g(\bar{x}_n) + \lambda(x_n^* - F(x_n)) \in \partial \phi(g(\bar{x}_n), x_n) + g(\bar{x}_n) \subset g(\bar{x}_n) + \lambda \partial \phi(g(\bar{x}_n), \bar{x}_n) + g(\bar{x}_n) = (I + \lambda \partial \phi(\cdot, \bar{x}_n))(g(\bar{x}_n)),$$

406

and hence

(5.7)
$$\bar{x}_n = \bar{x}_n - g(\bar{x}_n) + J_{\lambda}^{\partial\phi(\cdot,\bar{x}_n)}(g(\bar{x}_n) + \lambda(x_n^* - F(x_n)))$$

9/(=)

It follows from (5.5)-(5.7) that

$$\begin{aligned} &\|\bar{x}_{n} - (\bar{x}_{n} - g(\bar{x}_{n}) + J_{\lambda}^{O\phi(\cdot,\bar{x}_{n})}(g(\bar{x}_{n}) - \lambda F(\bar{x}_{n})))\| \\ &= \|J_{\lambda}^{\partial\phi(\cdot,\bar{x}_{n})}(g(\bar{x}_{n}) + \lambda(x_{n}^{*} - F(x_{n}))) - J_{\lambda}^{\partial\phi(\cdot,\bar{x}_{n})}(g(\bar{x}_{n}) - \lambda F(\bar{x}_{n}))\| \\ &\leq \|(g(\bar{x}_{n}) + \lambda(x_{n}^{*} - F(x_{n}))) - (g(\bar{x}_{n}) - \lambda F(\bar{x}_{n}))\| \\ &\leq \lambda \|x_{n}^{*}\| + \lambda \|F(\bar{x}_{n}) - F(x_{n})\| \to 0 \end{aligned}$$

and so $\{\bar{x}_n\}$ is an approximating sequence for $FP(F, g, \phi)$.

Let x^* be the unique solution of FP (F, g, ϕ) . By Lemma 2.2, x^* is also the unique solution of GMIQVI (F, g, ϕ) .

If $\operatorname{FP}(F, g, \phi)$ is strongly well-posed, then $\overline{x}_n \to x^*$. It follows that

 $||x_n - x^*|| \le ||x_n - \bar{x}_n|| + ||\bar{x}_n - x^*|| \to 0.$

Thus $\text{GMIQVI}(F, g, \phi)$ is strongly well-posed.

If
$$\operatorname{FP}(F, g, \phi)$$
 is weakly well-posed, then $\overline{x}_n \rightharpoonup x^*$. For any $f \in H$, we have

$$|\langle f, x_n - x^* \rangle| \le |\langle f, x_n - \bar{x}_n \rangle| + |\langle f, \bar{x}_n - x^* \rangle| \le ||f|| \sqrt{\epsilon_n} + |\langle f, \bar{x}_n - x^* \rangle| \to 0$$

and so $\text{GMIQVI}(F, g, \phi)$ is weakly well-posed.

Theorem 5.6. Let $g: H \to H$ be a homeomorphism which is σ -Lipschitz continuous, and $F: H \to H$ be uniformly continuous and g-monotone. Let $\phi: H \times H \to \mathcal{R} \cup \{+\infty\}$ be such that for each fixed $y \in H$, $\phi(\cdot, y)$ is a proper, convex and lower semicontinuous functional satisfying $g(H) \cap \operatorname{dom}\partial\phi(\cdot, y) \neq \emptyset$. For any approximating sequence $\{x_n\} \subset H$ of $\operatorname{FP}(F, g, \phi)$, suppose for each $n \in N$ there exists $\delta_n > 0$ such that

$$|\phi(g(w_n), w_n) - \phi(w_n - x_n + g(x_n), x_n)| \le \delta_n \text{ and } |\phi(y, x_n) - \phi(y, w_n)| \le \delta_n, \quad \forall y \in H,$$

where $\delta_n \to 0$ and $w_n = x_n - g(x_n) + J_{\lambda}^{\partial \phi(\cdot,x_n)}(g(x_n) - \lambda F(x_n))$. If GMIQVI(F, g, ϕ) is strongly (resp. weakly) $(1+\frac{1}{\lambda})$ -well-posed in the generalized sense, then FP(F, g, ϕ) is strongly (resp. weakly) well-posed in the generalized sense, where $\lambda > 0$ is a constant.

Proof. Let $\{x_n\}$ be an approximating sequence for $FP(F, g, \phi)$. Then $||x_n - w_n|| \to 0$, where

$$w_n = x_n - g(x_n) + J_{\lambda}^{\partial \phi(\cdot, x_n)}(g(x_n) - \lambda F(x_n)).$$

By the definition of $J^{\partial \phi(\cdot, x_n)}$,

$$\frac{x_n - w_n}{\lambda} - F(x_n) \in \partial \phi(w_n - x_n + g(x_n), x_n).$$

From the definition of subdifferential, we get

$$\phi(y, x_n) - \phi(w_n - x_n + g(x_n), x_n) \ge \langle \frac{x_n - w_n}{\lambda} - F(x_n), y - (w_n - x_n + g(x_n)) \rangle,$$

$$\forall y \in H, n \in N,$$

which is equivalent to the following inequality

$$\begin{split} \phi(g(y), x_n) - \phi(w_n - x_n + g(x_n), x_n) &\geq \langle \frac{x_n - w_n}{\lambda} - F(x_n), g(y) - (w_n - x_n + g(x_n)) \rangle, \\ \forall y \in H, \end{split}$$

for all $n \in N$. It follows from g-monotonicity that

$$\begin{aligned} &\langle F(w_n), (w_n - x_n + g(x_n)) - g(y) \rangle + \phi(w_n - x_n + g(x_n), x_n) - \phi(g(y), x_n) \\ &\leq \langle F(w_n) - F(x_n), (w_n - x_n + g(x_n)) - g(y) \rangle \\ &+ \frac{1}{\lambda} \langle x_n - w_n, (w_n - x_n + g(x_n)) - g(y) \rangle \\ &\leq \langle F(w_n) - F(x_n), w_n - x_n + g(w_n) - g(y) \rangle \\ &+ \frac{1}{\lambda} \langle x_n - w_n, g(x_n) - g(w_n) + g(w_n) - g(y) \rangle \\ &= \langle F(w_n) - F(x_n), w_n - x_n \rangle + \langle F(w_n) - F(x_n), g(w_n) - g(y) \rangle \\ &+ \frac{1}{\lambda} \langle x_n - w_n, g(x_n) - g(w_n) \rangle + \frac{1}{\lambda} \langle x_n - w_n, g(w_n) - g(y) \rangle \\ &\leq \frac{1}{2} (1 + \frac{1}{\lambda}) \| g(w_n) - g(y) \|^2 + (\frac{1}{2} \| F(w_n) - F(x_n) \|^2 + \frac{1}{2\lambda} \| x_n - w_n \|^2) \\ &+ \langle F(w_n) - F(x_n), w_n - x_n \rangle + \frac{1}{\lambda} \langle x_n - w_n, g(x_n) - g(w_n) \rangle, \quad \forall y \in H, \end{aligned}$$

for all $n \in N$. Thus from the last inequality we get

$$\begin{split} \langle F(w_n), g(w_n) - g(y) \rangle &+ \phi(g(w_n), w_n) - \phi(g(y), w_n) \\ \leq \frac{1}{2}(1 + \frac{1}{\lambda}) \|g(w_n) - g(y)\|^2 + (\frac{1}{2} \|F(w_n) - F(x_n)\|^2 + \frac{1}{2\lambda} \|x_n - w_n\|^2) \\ &+ \langle F(w_n) - F(x_n), w_n - x_n \rangle + \frac{1}{\lambda} \langle x_n - w_n, g(x_n) - g(w_n) \rangle \\ &+ \langle F(w_n), x_n - w_n + g(w_n) - g(x_n) \rangle + \phi(g(w_n), w_n) - \phi(w_n - x_n + g(x_n), x_n) \\ &+ \phi(g(y), x_n) - \phi(g(y), w_n) \\ \leq \frac{1}{2}(1 + \frac{1}{\lambda}) \|g(w_n) - g(y)\|^2 + (\frac{1}{2} \|F(w_n) - F(x_n)\|^2 + \frac{1}{2\lambda} \|x_n - w_n\|^2) \\ &+ |\langle F(w_n) - F(x_n), w_n - x_n \rangle| + \frac{1}{\lambda} |\langle x_n - w_n, g(x_n) - g(w_n) \rangle| \\ &+ |\langle F(w_n), x_n - w_n + g(w_n) - g(x_n) \rangle| + 2\delta_n, \quad \forall y \in H, n \in N. \end{split}$$

Since F and g are uniformly continuous and $||w_n - x_n|| \to 0$, we deduce that $\{w_n\}$ is $(1 + \frac{1}{\lambda})$ -approximating for GMIQVI (F, g, ϕ) .

If GMIQVI(F, g, ϕ) is strongly $(1 + \frac{1}{\lambda})$ -well-posed in the generalized sense, then $\{w_n\}$ has a subsequence $\{w_{n_k}\}$ such that $w_{n_k} \to x^*$ as $k \to \infty$, where x^* is a solution of GMIQVI(F, g, ϕ). By Lemma 2.2, x^* is also a solution of FP(F, g, ϕ). It follows that

$$||x_{n_k} - x^*|| \le ||x_{n_k} - w_{n_k}|| + ||w_{n_k} - x^*|| \to 0$$

as $k \to \infty$. Thus $FP(F, g, \phi)$ is strongly well-posed in the generalized sense.

If GMIQVI (F, g, ϕ) is weakly $(1 + \frac{1}{\lambda})$ -well-posed in the generalized sense, then $\{w_n\}$ has a subsequence $\{w_{n_k}\}$ such that $w_{n_k} \rightarrow x^*$ as $k \rightarrow \infty$, where x^* is a solution of GMIQVI (F, g, ϕ) . By Lemma 2.2, x^* is also a solution of FP (F, g, ϕ) . For any $f \in H$, it follows that, as $k \rightarrow \infty$,

$$\begin{aligned} |\langle f, x_{n_k} - x^* \rangle| &\leq |\langle f, x_{n_k} - w_{n_k} \rangle| + |\langle f, w_{n_k} - x^* \rangle| \\ &\leq ||f|| \cdot ||x_{n_k} - w_{n_k}|| + |\langle f, w_{n_k} - x^* \rangle| \to 0. \end{aligned}$$

Thus $FP(F, g, \phi)$ is weakly well-posed in the generalized sense.

Theorem 5.7. Let $g: H \to H$ be a homeomorphism whose inverse g^{-1} is uniformly continuous. Let $F: H \to H$ be uniformly continuous and g-monotone, and let $\phi: H \times H \to \mathcal{R} \cup \{+\infty\}$ be such that for each fixed $y \in H$, $\phi(\cdot, y)$ is a proper, convex and lower semicontinuous functional satisfying $g(H) \cap \operatorname{dom}\partial\phi(\cdot, y) \neq \emptyset$. Assume that for any bounded sequences $\{x_n\}, \{y_n\}$ in H there holds the following:

$$||x_n - y_n|| \to 0 \ (n \to \infty) \quad \Rightarrow \quad \partial \phi(g(y_n), x_n) \subset \partial \phi(g(y_n), y_n) \text{ for } n \text{ sufficiently large}$$

If $FP(F, g, \phi)$ is strongly (resp. weakly) well-posed in the generalized sense, then $GMIQVI(F, g, \phi)$ is strongly (resp. weakly) well-posed in the generalized sense.

Proof. The conclusion follows from the arguments similar to that of Theorem 5.5. \Box

6. Conclusions for well-posedness

In this section we shall prove that under suitable conditions the well-posedness of the general mixed implicit quasi-variational inequality is equivalent to the existence and uniqueness of its solutions, and the well-posedness in the generalized sense is equivalent to the existence of its solutions.

Theorem 6.1. Let $g: H \to H$ be a homeomorphism which is affine and σ -Lipschitz continuous. Let $F: H \to H$ be g-monotone and g-hemicontinuous. Let $\phi: H \times H \to \mathcal{R} \cup \{+\infty\}$ be a proper and diagonally convex functional such that for each fixed $y \in H$ there hold the following conditions:

(i) $\phi(y, \cdot)$ is affine;

(ii) $\phi(\cdot, y)$ is a lower semicontinuous functional satisfying $g(H) \cap \text{dom}\partial\phi(\cdot, y) \neq \emptyset$; (iii) $x \mapsto \phi(g(x), x) - \phi(g(y), x)$ is weakly lower semicontinuous.

If $GMIQVI(F, g, \phi)$ is weakly well-posed if and only if it has a unique solution.

Proof. The necessity is obvious. For the sufficiency, suppose that $\text{GMIQVI}(F, g, \phi)$ has a unique solution x^* . If $\text{GMIQVI}(F, g, \phi)$ is not weakly well-posed, then there exists an approximating sequence $\{x_n\}$ for $\text{GMIQVI}(F, g, \phi)$ such that $x_n \not\rightharpoonup x^*$. Thus, there exists $\epsilon_n > 0$ with $\epsilon_n \to 0$ such that

$$\langle F(x_n), g(x_n) - y \rangle + \phi(g(x_n), x_n) - \phi(y, x_n) \le \epsilon_n, \quad \forall y \in H, n \in N,$$

which is equivalent to the following inequality

(6.1)
$$\langle F(x_n), g(x_n) - g(y) \rangle + \phi(g(x_n), x_n) - \phi(g(y), x_n) \le \epsilon_n, \quad \forall y \in H, n \in N.$$

If $\{x_n\}$ is unbounded, without loss of generality, we may assume that $||x_n|| \to +\infty$. Let

$$t_n = \frac{1}{\|x_n - x^*\|}, \quad z_n = x^* + t_n(x_n - x^*)$$

Without loss of generality, we may assume that $t_n \in (0,1]$ and $z_n \rightharpoonup z \neq x^*$). By the arguments similar to that of Theorem 4.5, we have

$$\langle F(y), g(z) - g(y) \rangle \leq \langle F(y), g(z) - g(z_n) \rangle + \phi(g(y), z_n) - \phi(g(z_n), z_n) + t_n \epsilon_n,$$

$$\forall y \in H, n \in N.$$

It follows that

$$\begin{aligned} \langle F(y), g(z) - g(y) \rangle &\leq \lim_{n \to \infty} \sup \{ \langle F(y), g(z) - g(z_n) \rangle \\ &+ \phi(g(y), z_n) - \phi(g(z_n), z_n) + t_n \epsilon_n \} \\ &\leq \phi(g(y), z) - \phi(g(z), z), \quad \forall y \in H, \end{aligned}$$

which is equivalent to the following inequality

$$\langle F(y), g(z) - y \rangle \le \phi(y, z) - \phi(g(z), z), \quad \forall y \in H.$$

This together with Lemma 2.6 yields that z solves $\text{GMIQVI}(F, g, \phi)$, a contradiction. Thus, $\{x_n\}$ is bounded.

Let $\{x_{n_k}\}$ be any subsequence of $\{x_n\}$ such that $x_{n_k} \rightharpoonup \bar{x}$ as $k \rightarrow \infty$. It follows from (6.1) that

$$\langle F(x_{n_k}), g(x_{n_k}) - g(y) \rangle + \phi(g(x_{n_k}), x_{n_k}) - \phi(g(y), x_{n_k}) \le \epsilon_{n_k}, \quad \forall y \in H, k \in N.$$

Since F is g-monotone, from condition (iii) we conclude that

 $\langle F(y), g(\bar{x}) - g(y) \rangle + \phi(g(\bar{x}), \bar{x}) - \phi(g(y), \bar{x})$ $\leq \liminf n \to \infty \{ \langle F(y), g(x_{n_k}) - g(y) \rangle + \phi(g(x_{n_k}), x_{n_k}) - \phi(g(y), x_{n_k}) \}$ $\leq \liminf n \to \infty \{ \langle F(x_{n_k}), g(x_{n_k}) - g(y) \rangle + \phi(g(x_{n_k}), x_{n_k}) - \phi(g(y), x_{n_k}) \}$ $\leq \liminf n \to \infty \epsilon_n = 0, \quad \forall y \in H.$

This together with Lemma 2.6 yields that \bar{x} solves $\text{GMIQVI}(F, g, \phi)$. We have $\bar{x} = x^*$ since $\text{GMIQVI}(F, g, \phi)$ has a unique solution x^* . Thus $\{x_n\}$ converges weakly to x^* , a contradiction. So $\text{GMIQVI}(F, g, \phi)$ is weakly well-posed. \Box

Example 6.2. Let H, F, g be as in Example 3.9 and ϕ be as in Remark 4.4. Clearly, $g: H \to H$ be a homeomorphism which is affine and σ -Lipschitz continuous. Moreover, $F: H \to H$ be g-monotone and g-hemicontinuous. On the other hand, $\phi: H \times H \to \mathcal{R} \cup \{+\infty\}$ is obviously a proper and diagonally convex functional such that for each fixed $y \in H$ there hold the following conditions:

(i) $\phi(y, \cdot)$ is affine;

(ii) $\phi(\cdot, y)$ is a lower semicontinuous functional satisfying $g(H) \cap \operatorname{dom} \partial \phi(\cdot, y) \neq \emptyset$; (iii) $x \mapsto \phi(g(x), x) - \phi(g(y), x)$ is weakly lower semicontinuous.

Furthermore, it is easy to see that $\text{GMIQVI}(F, g, \phi)$ has a unique solution $x^* = 0$. By Theorem 6.1, $\text{GMIQVI}(F, g, \phi)$ is well-posed.

Theorem 6.3. Let $g : \mathbb{R}^m \to \mathbb{R}^m$ be a homeomorphism which is affine and σ -Lipschitz continuous. Let $F : H \to H$ be g-monotone and g-hemicontinuous. Let $\phi : \mathbb{R}^m \times \mathbb{R}^m \to \mathbb{R} \cup \{+\infty\}$ be a proper and diagonally convex functional such that for each fixed $y \in \mathbb{R}^m$ there hold the following conditions:

(i) $\phi(y, \cdot)$ is affine;

(ii) $\phi(\cdot, y)$ is a lower semicontinuous functional satisfying $g(\mathcal{R}^m) \cap \operatorname{dom} \partial \phi(\cdot, y) \neq \emptyset$;

(iii) $x \mapsto \phi(g(x), x) - \phi(g(y), x)$ is lower semicontinuous.

If there exists some $\epsilon > 0$ such that $\Omega_{\alpha}(\epsilon)$ is nonempty bounded, then GMIQVI(F, g, ϕ) is α -well-posed in the generalized sense.

Proof. Let $\{x_n\}$ be an α -approximating sequence for GMIQVI (F, g, ϕ) . Then there exists $\epsilon_n > 0$ with $\epsilon_n \to 0$ such that for all $y \in \mathcal{R}^m$ and all $n \in N$

$$\langle F(x_n), g(x_n) - y \rangle + \phi(g(x_n), x_n) - \phi(y, x_n) \le \frac{\alpha}{2} ||x_n - g^{-1}(y)||^2 + \epsilon_n,$$

which is equivalent to the following inequality

(6.2)
$$\langle F(x_n), g(x_n) - g(y) \rangle + \phi(g(x_n), x_n) - \phi(g(y), x_n) \le \frac{\alpha}{2} ||x_n - y||^2 + \epsilon_n.$$

Let $\epsilon > 0$ be such that $\Omega_{\alpha}(\epsilon)$ is nonempty bounded. Then there exists n_0 such that $x_n \in \Omega_{\alpha}(\epsilon)$ for all $n > n_0$. This implies that $\{x_n\}$ is bounded and so there exists a

subsequence $\{x_{n_k}\}$ of $\{x_n\}$ such that $x_{n_k} \to \bar{x}$ as $k \to \infty$. Since g is affine and F is g-monotone, it follows from (6.2) and condition (iii) that for all $y \in \mathbb{R}^m$

$$\begin{array}{l} \langle F(y), g(\bar{x}) - g(y) \rangle + \phi(g(\bar{x}), \bar{x}) - \phi(g(y), \bar{x}) \\ \leq \liminf_{k \to \infty} \{ \langle F(y), g(x_{n_k}) - g(y) \rangle + \phi(g(x_{n_k}), x_{n_k}) - \phi(g(y), x_{n_k}) \} \\ \leq \liminf_{k \to \infty} \{ \langle F(x_{n_k}), g(x_{n_k}) - g(y) \rangle + \phi(g(x_{n_k}), x_{n_k}) - \phi(g(y), x_{n_k}) \} \\ \leq \liminf_{k \to \infty} \{ \frac{\alpha}{2} \| x_{n_k} - y \|^2 + \epsilon_{n_k} \} \\ = \frac{\alpha}{2} \| \bar{x} - y \|^2. \end{array}$$

For any $y \in \mathcal{R}^m$, let $y_t = \bar{x} + t(y - \bar{x})$ for all $t \in (0, 1)$. Then

$$\langle F(y_t), g(\bar{x}) - g(y_t) \rangle + \phi(g(\bar{x}), \bar{x}) - \phi(g(y_t), \bar{x}) \le \frac{\alpha}{2} \|\bar{x} - y_t\|^2.$$

By the convexity of $\phi(\cdot, \bar{x})$ and the affinity of g, we conclude that for all $y \in \mathcal{R}^m$ and all $t \in (0, 1)$

$$\langle F(y_t), g(\bar{x}) - g(y) \rangle + \phi(g(\bar{x}), \bar{x}) - \phi(g(y), \bar{x}) \le \frac{t\alpha}{2} \|\bar{x} - y\|^2.$$

Letting $t \to 0^+$ in the above inequality, we have for all $y \in \mathcal{R}^m$

$$\langle F(y), g(\bar{x}) - g(y) \rangle + \phi(g(\bar{x}), \bar{x}) - \phi(g(y), \bar{x}) \le 0,$$

which is equivalent to the following inequality

$$\langle F(y), g(\bar{x}) - y \rangle + \phi(g(\bar{x}), \bar{x}) - \phi(y, \bar{x}) \le 0.$$

This together with Lemma 2.6 implies that \bar{x} solves $\text{GMIQVI}(F, g, \phi)$. Thus $\text{GMIQVI}(F, g, \phi)$ is α -well-posed in the generalized sense.

Theorem 6.3 says nothing but that, under suitable conditions, the α -well-posedness in the generalized sense is equivalent to the existence of solutions.

The following example shows the assumption that $\Omega_{\alpha}(\epsilon)$ is nonempty bounded for some $\epsilon > 0$ is essential in Theorem 6.3.

Example 6.4. Let m = 2, F(x) = 0 and $\phi(x, y) = \delta_K$, where $K = [0, +\infty) \times [0, +\infty)$. Let g be as in Example 3.9. Then, clearly, F is g-monotone and g-hemicontinuous, and there hold conditions (i)-(iii) for the proper and diagonally convex functional ϕ . For any $\epsilon > 0$, we have $\Omega_{\alpha}(\epsilon) = [0, +\infty) \times [0, +\infty)$. By Theorem 3.8, GMIQVI(F, g, ϕ) is not α -well-posed in the generalized sense.

7. Conclusions

In this paper we introduce some concepts of well-posedness for general mixed implicit quasi-variational inequalities. In Section 3, we establish some metric characterizations of strong α -well-posedness. In Section 4, we discuss the connections between the strong (weak) well-posedness of general mixed implicit quasi-variational inequalities and strong (weak) well-posedness of inclusion problems. In Section 5, we further investigate the relationships between the strong (weak) well-posedness of general mixed implicit quasi-variational inequalities and the strong (weak) wellposedness of fixed point problems. In Section 6, we prove that under suitable conditions, the well-posedness of general mixed implicit quasi-variational inequalities is

equivalent to the existence and uniqueness of solutions, and that the well-posedness in the generalized sense is equivalent to the existence of solutions. Our results are the improvements and extension of the corresponding ones in [11].

It is known that the concept of α -well-posedness has been introduced and considered for optimization problems [7], variational inequalities [7,20] and Nash equilibrium problems [20], mixed variational inequalities [11]. It is worth pointing out that in [11] there are two unsolved open problems arise in nature way.

Q1 Is it possible to consider the concept of α -well-posedness for the inclusion problems ?

Q2 Is it possible to give a metric characterization only for weak well-posedness?

The above two unsolved open problems are interesting and important which deserve investigation in the future.

References

- Q. H. Ansari and J. C. Yao, Iterative schemes for solving mixed variational-like inequalities, Journal of Optimization Theory and Applications 108 (2001), 527–541.
- [2] E. Bednarczuk and J. P. Penot, Metrically well-set minimization problems, Applied Mathematics and Optimization 26 (1992) 273–285.
- [3] H. Brezis, Operateurs Maximaux Monotone et Semigroups de Contractions dans les Espaces de Hilbert, North-Holland, Amsterdam, 1973.
- [4] A. Brøndsted and R. T. Rockafellar, On the subdifferentiability of convex functions, Proceedings of the American Mathematical Society 16 (1965), 605–611.
- [5] E. Cavazzuti and J. Morgan, Well-posed saddle point problems, in Optimization, Theory and Algorithms, Hirriart-Urruty, W. Oettli and J. Stoer (eds.), Marcel Dekker, New York, NY, 1983, pp. 61–76.
- [6] X. P. Ding and C. L. Luo, Perturbed proximal point algorithms for general quasi-variational-like inclusions, Journal of Computational and Applied Mathematics 113 (2000), 153–165.
- [7] I. Delprete, M. B. Lignola and J. Morgan, New concepts of well-posedness for optimization problems with variational inequality constraints, Journal of Inequalities in Pure and Applied Mathematics 4 (2003), 26–43.
- [8] A. L. Dontchev and T. Zolezzi, Well-Posed Optimization Problems, Lecture Notes in Mathematics, 1543, Springer-Verlag, Berlin, Germany 1993.
- [9] Y. P. Fang and C. X. Deng, Stability of new implicit iteration procedures for a class of nonlinear set-valued mixed variational inequalities, Zeitschrift fur Angewandte Mathematik und Mechanik 84 (2004), 53–59.
- [10] Y. P. Fang and R. Hu, Parametric well-posedness for variational Inequalities defined by bifunctions, Computers and Mathematics with Applications 53(8) (2007), 1306–1316.
- [11] Y. P. Fang, N. J. Huang and J. C. Yao, On the subdifferentiability of convex functions, Inclusion Problems and Fixed Point Problems, Journal of Global Optimization 41 (2008), 117–133.
- [12] J. S. Guo and J. C. Yao, Extension of strong nonlinear quasivariational Inequalities, Applied Mathematics Letters 5 (1992), 35–38.
- [13] A. Hassouni and A. Moudafi, A perturbed algorithm for variational inclusions, Journal of Mathematical Analysis and Applications 185 (1994), 706–712.
- [14] X. X. Huang, Extended and strongly extended well-posedness of set-valued optimization problems, Mathematical Methods of Operations Research 53 (2001), 101–116.
- [15] K. Kuratowski, Topology, 1 and 2 Academic Press, New York, NY, 1968.
- [16] B. Lemaire, Well-Posedness, Conditioning, and Regularization of Minimization, Inclusion, and Fixed-Point Problems, Pliska Studia Mathematica Bulgaria 12 (1998), 71–84.

- [17] B. Lemaire, C. Ould Ahmed Salem and J. P. Revalski, Well-posedness by perturbations of variational problems, Journal of Optimization Theory and Applications 115 (2002), 345–368.
- [18] M. B. Lignola, Well-posedness and L-well-posedness for quasivariational liequalities, Journal of Optimization Theory and Applications 128 (2006), 119–138.
- [19] M. B. Lignola and J. Morgan, Well-posedness for optimization problems with constraints defined by a variational inequality having a unique solution, Journal of Global Optimization 16 (2000), 57–67.
- [20] M. B. Ligola and J. Morgan, Approximate solutions and α-well-posedness for variational inequalities and Nash equilibria, in Decision and Control in Management Science, G. Zaccour (ed.), Kluwer Academic Publishers, Dordrecht, Netherlands, 2002, pp. 367–378.
- [21] R. Lucchetti and F. Patrone, A characterization of Tykhonov well-posedness for minimum problems with applications to variational inequalities, Numerical Functional Analysis and Optimization 3 (1981), 461–476.
- [22] R. Lucchetti and F. Patrone, Hadamard and Tykhonov well-posedness of certain class of convex functions, Journal of Mathematical Analysis and Applications 88 (1982), 204–215.
- [23] R. Lucchetti and J. Revalski (Eds), Recent Developments in Well-Posed Variational Problems, Kluwer Academic Publishers, Dordrecht, Holland, 1995.
- [24] M. Margiocco, F. Patrone and L. Pusillo, A new approach to Tykhonov well-posedness for Nash equilibria, Optimization 40 (1997), 385–400.
- [25] M. Margiocco, F. Patrone and L. Pusillo, *Metric characterizations of Tykhonov well-posedness in value*, Journal of Optimization Theory and Applications **100** (1999), 377–387.
- [26] M. Margiocco, F. Patrone and L. Pusillo, On the Tykhonov well-posedness of concave games and cournot oligopoly games, Journal of Optimization Theory and Applications 112 (2002), 361–379.
- [27] E. Miglierina and E. Molho, Well-posedness and convexity in vector optimization, Mathematical Methods of Operations Research 58 (2003), 375–385.
- [28] J. Morgan, Approximations and well-posedness in multicriteria games, Annals of Operations Research 137 (2005), 257–268.
- [29] S. Schaible, J. C. Yao and L. C. Zeng, Iterative method for set-valued mixed quasivariational inequalities in a Banach space, Journal of Optimization Theory and Applications 129 (2006), 425–436.
- [30] A. H. Siddiqi and Q. H. Ansari, General Strongly Nonlinear Variational Inequalities, Journal of Mathematical Analysis and Applications 166 (1992), 386–392.
- [31] A. N. Tykhonov, On the stability of the functional optimization problem, USSR Journal of Computational Mathematics and Mathematical Physics 6 (1966), 631–634.
- [32] H. Yang and J. Yu, Unified approaches to well-posedness with some applications, Journal of Global Optimization 31 (2005), 371–381.
- [33] J. C. Yao, Existence of generalized variational inequalities, Operations Research Letters 15 (1994), 35–40.
- [34] L. C. Zeng, Iterative algorithms for finding approximate solutions for general strongly nonlinear variational inequalities, Journal of Mathematical Analysis and Applications 187 (1994), 352– 360.
- [35] L. C. Zeng, S. M. Guu and J. C. Yao, Characterization of H-monotone operators with applications to variational Inclusions, Computers and Mathematics with Applications 50 (2005), 329–337.
- [36] L. C. Zeng and J. C. Yao, Existence of solutions of generalized vector variational inequalities in reflexive Banach spaces, Journal of Global Optimization 36 (2006), 483–496.
- [37] T. Zolezzi, Well-posedness criteria in optimization with application to the calculus of variations, Nonlinear Analysis-TMA 25 (1995), 437–453.
- [38] T. Zolezzi, Extended well-posedness of optimization problems, Journal of Optimization Theory and Applications 91 (1996), 257–266.

Mu-Ming Wong

Department of Applied Mathematics, Chung Yuan Christian University, Chung Li, 32023, Taiwan *E-mail address:* mmwong@cycu.edu.tw